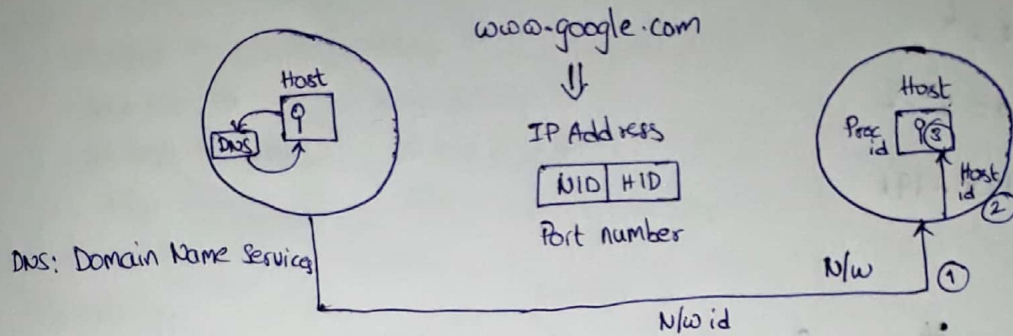


02/12/20

Computer Networks

83

Introduction:



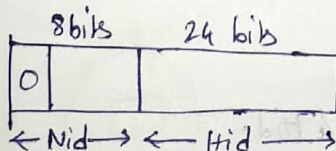
- Port number is used to identify a process in host. Well known services have predefined fixed port numbers.
- The overhead involved in translating domain name to IP address using DNS is called DNS overhead.

Class full IP address classification:

Class A: 0___; class B: 10___; class C: 110___; class D: 1110___; class E: 1111___

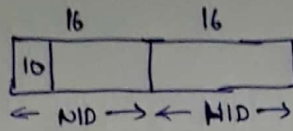
- size of IPv4 address is 32 bits.
- It is represented using dotted decimal notation, where every 8 bit part of the address is represented in decimal form.

Class A:



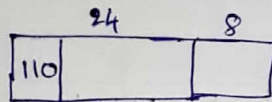
- No of networks = 128
- no of IP add per n/w = 2^{24}
- no of hosts per N/w = $2^{24} - 2$
- Out of 128 N/w's we don't use starting ~~128~~ (all 0's) and last N/w (all 1's) ⇒ Range: 1. to 126.

Class B :



- N/Ws : 2^{14}
- IP/NW : 2^{16}
- Hosts/NW : $2^{16} - 2$
- Range : 128 - 191

Class C :



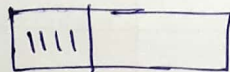
- N/Ws : 2^{21}
- IP/NW : 2^8
- Hosts/NW : $2^8 - 2$
- Range : 192 - 223

Class D :



- Here addresses are not classified into Nid and Hid.
 - This class of addresses are used for multicasting.
 - No of address : 2^{28}
 - This class is a drawback because 2^{28} is a large number for multicasting.
- Range : 224 - 239

Class E :



- These are also not divided into Nid & Hid.
- These are reserved for special purpose.
- Range : 240 - 255.

Note : Under every N/W, 1st & last IP addresses are used for special purposes (i.e., for network id & ~~multicasting~~ Direct broadcast)

Casting:

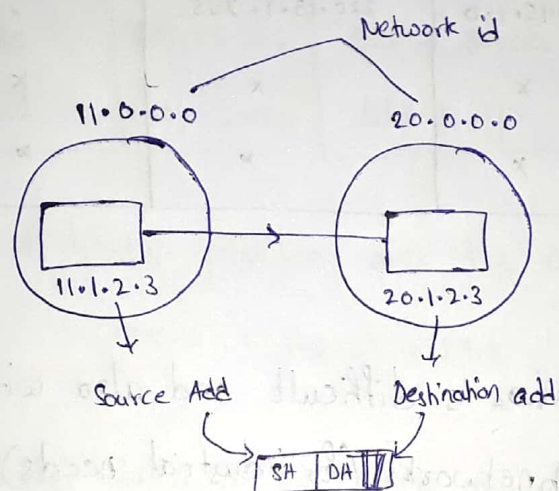
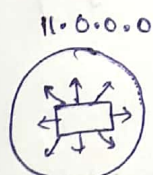
- Unicast: Sending packet from one host to other host
- Broadcast: sending a packet from one host to many hosts.

Limited

- send pkt to all hosts of same N/w

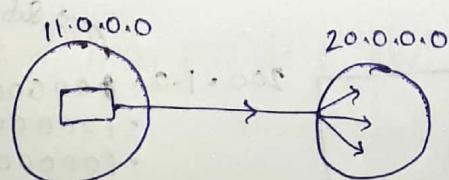
Directed

- send pkt to all host of diff N/w

Unicasting:Limited Broadcasting:

Source Add: 11.1.2.3

Destination Add: 255.255.255.255

Directed Broadcast:

Source Add: 11.1.2.3

Destination Add: 20.255.255.255

Note:

limited broadcast add: 255.255.255.255

Directed broadcast add: Nid.1111...1

Network id: Nid.000...0

Q1

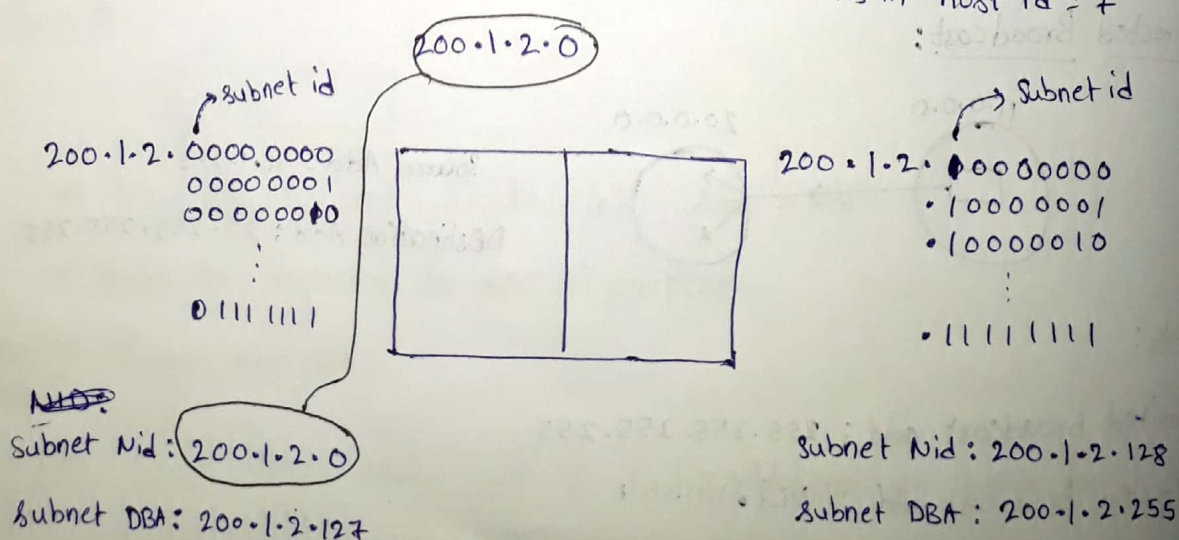
IP Add	class	Nid	DBA	LBA
1.2.3.4	A	1.0.0.0	1.255.255.255	255.255.255.255
10.15.20.60	BA	10.0.0.0	10.255.255.255	"
130.1.2.3	B	130.1.0.0	130.1.255.255	"
150.0.150.150	B	150.0.0.0	150.0.255.255	"
200.1.10.100	C	200.1.10.0	200.1.10.255	"
220.15.1.10	C	220.15.1.0	220.15.1.255	"
250.0.1.2	E	x	x	x
330.1.2.3	invalid	x	x	x

Subnets:

- Maintenance of large N/w is difficult and also within a N/w we need small subnetworks (for industrial needs).
- Subnetting is ~~per~~ process of dividing large N/w into smaller networks.
- But subnetting ~~to~~ incurs more time in identifying host.

Ex: Consider class C N/w 200.1.2.0

Now lets divide it into 2 subnets $\Rightarrow$ no of bits in subnet id = 1
no of bits in host id = 7



→ Now there is a confusion that whether

200.1.2.0 is Nid or subnet Nid

200.1.2.255 is DBA of subnet or DBA of whole N/w.

→

Sender	Address	Interpretation
within N/w	200.1.2.0	subnet N/w id
outside	200.1.2.0	N/w id
inside	200.1.2.255	DBA of subnet
outsid	200.1.2.255	DBA of N/w

→ Now no of hosts possible over this organization is

$$(128-2) + (128-2) = 252$$

→ Now consider dividing the same network into 4 subnets.

⇒ no of bits in subnet id: 2

no of bits in host id: 6

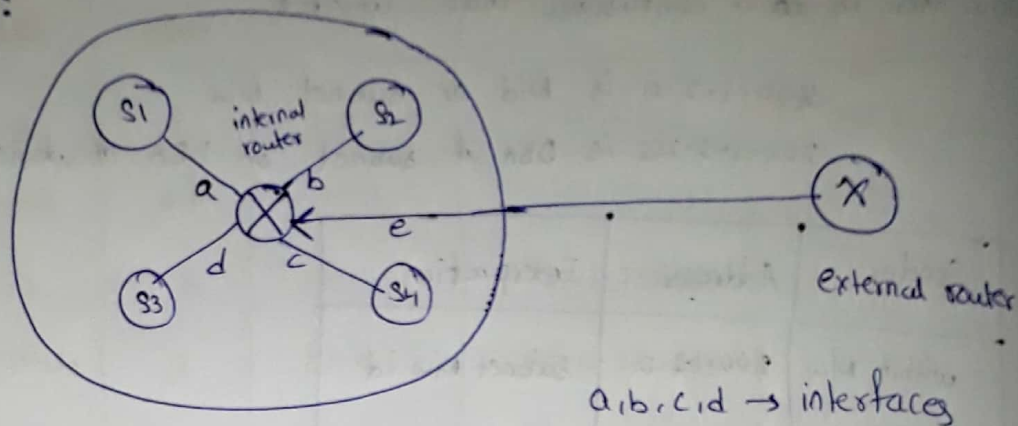
S1	S2
200.1.2.0 to 200.1.2.63	200.1.2.64 to 200.1.2.127
200.1.2.128 to 200.1.2.191	200.1.2.192 to 200.1.2.255
S3	S4

no of hosts possible : $256 - (2 \times \text{no of subnets})$

$$= 256 - (8) = 248$$

→ Generally router gets the packets and forwards to the correct host and makes correct interpretation (in the case when there is confusion)

Routing:



Subnet mask: It is a 32-bit number used by router to identify the subnet to which a given address belongs. to within subnet mask,

all bits corresponding to Nid & subnet id are 1's

" " " " host id are 0's

Eg: For current example subnet mask is

Subnet mask is also known as network mask

11111111	11111111	11111111	11000000
----------	----------	----------	----------

 $\approx 255.255.255.192$

we obtain subnet network id by performing bitwise and with given ip address.

For example consider ip add 200.1.2.130

Subnet mask: 11111111 11111111 11111111 11000000

ip add: 11001000 00000001 00000010 10000010

bitwise and: 11001000 00000001 00000010 10000000

i.e., 200.1.2.128 (subnet id)

$\rightarrow$ whenever router gets an address, it performs bit wise and b/w ip add. & subnet mask.

After this it finds subnet network id and forwards the packet to the correct interface accordingly. This process is done using routing table.

→ Routing table:

Subnet id	Subnet mask	Interface
200.1.2.0	255.255.255.192 255.255.255.192	a
200.1.2.64	255.255.255.192 "	b
200.1.2.128	255.255.255.192 "	c
200.1.2.192	255.255.255.192 "	d
0.0.0.0	0.0.0.0	e

→ when ever ip add is obtained, it is ~~an~~ anded with subnet mask and check if ~~cor~~ it matches with corresponding subnet id or not.

→ If all the entries doesn't match, then default entry (0.0.0.0) is used.

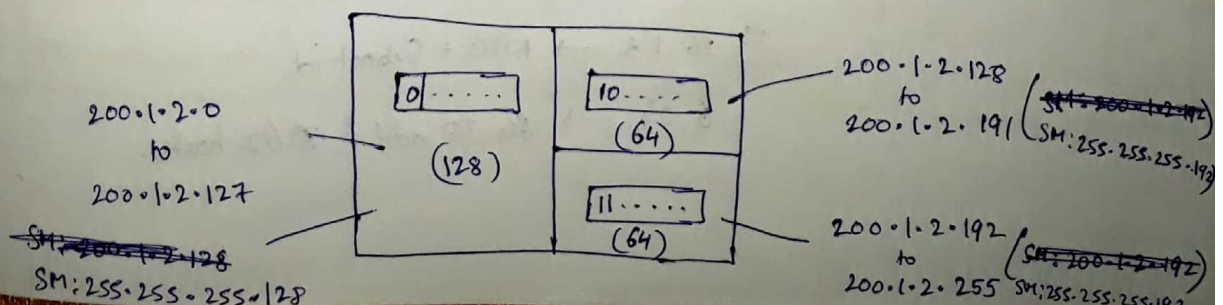
→ If an address match with more than one pair then choose the pair with longest subnet mask (i.e., the one with more no of 1's)

→ when sizes of all the subnets are same, it is called Fixed Length Subnet Masking (FLSM):

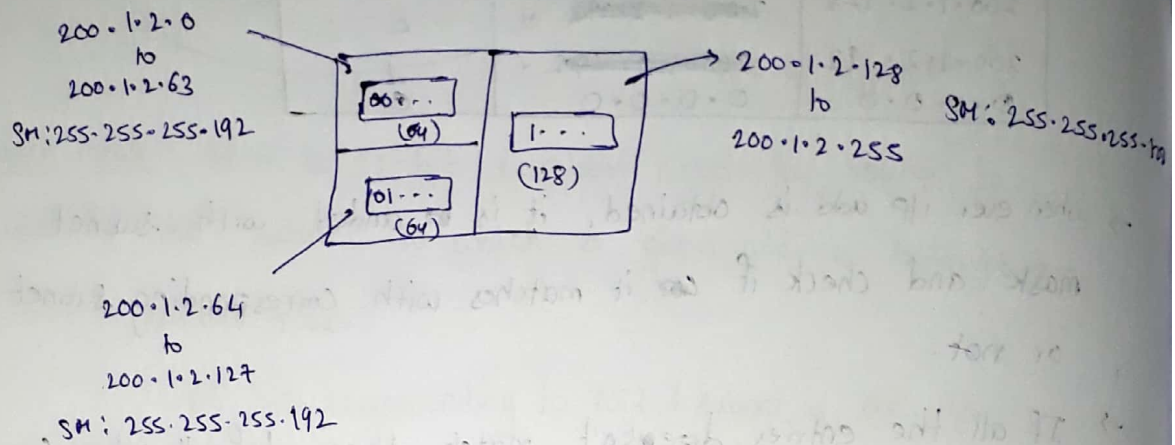
→ when sizes of subnets differ, it is called Variable Length Subnet Masking (VLSM)

→ Now consider subnetting of previous example into 3 subnets ~~with~~ with 128, 64, 64 IP addresses.

~~no of bits in subnet id~~

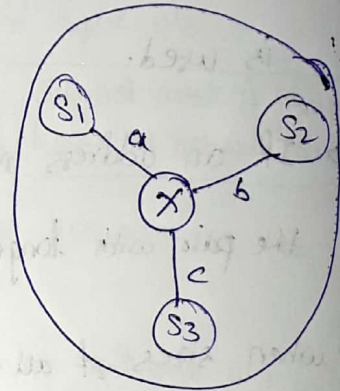


- Subnets of equal sizes will have same value of ~~sub~~ subnet mask.
- ~~Smaller~~ Larger the size of subnet, smaller the size of subnet mask is.
- Another variant can also be used ~~where larger subnets get larger value of subnet mask~~ ~~is not shown below~~



Routing table:

Subnet ID	SM	Interface
200.1.2.0	255.255.255.128	a
200.1.2.128	255.255.255.192	b
200.1.2.192	255.255.255.192	c
0.0.0.0	0.0.0.0	d



p3/12/20

- Given a subnet mask we can find no of IP add. in the the subnet.

Eg: Consider 255.255.255.192

11111111.11111111.11111111.11000000

⇒ 26 1's → NID + Subnet id

6 0's → 64 IP add & 62 hosts.

If class & IP add is given then we can find ^{no of bits} subnet id also

Class A:

NID: 8 bits Sid: 18

Class B:

NID: 16 Sid: 10

Class C: NID: 24 Sid: 2

→ Practically MSB bits of HID are only used for subnet id.

But theoretically any bits of HID can be used.

→ If LSB bits are used for subnet id then we can't get proper ranges

Eg: Consider dividing 200.1.2.0 into 2 subnets. If LSB^{bit} is used as subnet id then one subnet will have all even IP addresses and other will have all odd IP addresses.

Q2

	Subnet Mask	No of hosts Per subnet	Subnets in class A	Subnets in class B	Subnets in class C	Subnet if no of bits in NID > 10
1	255.0.0.0	$2^{24} - 2$	1	—	—	—
2	255.128.0.0	$2^{23} - 2$	2	—	—	—
3	255.192.0.0	$2^{22} - 2$	2^2	—	—	1
4	255.240.0.0	2^{32} $2^{20} - 2$	2^4	—	—	2^2
5	<u>255.255.0.0</u> default subnet mask of class B	$2^{16} - 2$	2^8	1	—	2^6
6	255.255.254.0	$2^9 - 2$	2^{15}	2^7	—	2^{13}
7	<u>255.255.255.0</u> default subnet mask of class C	$2^8 - 2$	2^{16}	2^8	1	2^{14}
8	255.255.255.224	$2^5 - 2$	2^{19}	2^{11}	2^3	2^{17}
9	255.255.255.240	$2^4 - 2$	2^{20}	2^{12}	2^4	2^{18}

1) 255.0.0.0

$Nid + \overset{Sid}{Hid} = 8 \text{ bits}$

$Hid : 24 \text{ bits} \Rightarrow \text{no of hosts} = 2^4 - 2$

Class A : $Nid + Sid = 8$

$$8 + Sid = 8$$

$$Sid = 0$$

i.e., no subnets.

Entire network is one subnet

Class B : $Nid + Sid = 8$

$Nid \text{ of Class B} : 16 \text{ bits}$

$\therefore$ not possible

Class C :
Here also not possible

2) 255.128.0.0

11111111.10000000.0.0.0.0.0.0

$\Rightarrow Nid + \overset{Sid}{Hid} = 9 \text{ bits}$

Class A : $2^{23} - 2 \Rightarrow 12 \text{ bits for Sid}$

Class B : not possible

Class C : not possible

CIDR : (Classless Inter Domain Routing)

→ The problem with classful classification ~~that~~ is that it not flexible for assigning IP addresses.

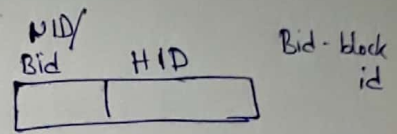
→ So we use ~~CIP~~ CIDR ~~tech~~ technique which doesn't have any ~~to~~ classes.

→ whenever a set of IP addresses are needed, the available IP address set is ~~at~~ assigned. This set of IP addresses is called block.

→ In classful, given an IP add we can determine ~~no of~~ network id to which the address belongs to (Knd in class of address)

But in CIDR we need to mention no of bits in NID field explicitly.

CIDR representation: $a.b.c.d/n$



$n \rightarrow$ no of bits in NID part

$32-n \rightarrow$ no of bits in host id

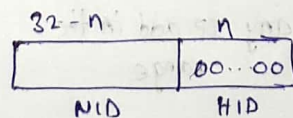
no of IP addresses = 2^{32-n}

Rules for CIDR blocks:

- (i) All the IP addresses should be contiguous.
- (ii) Block size is always in power of 2.
- (iii) First IP address in the block should be divisible by size of the block.

i.e., ~~IP~~ starting address should have all 0's in HID.

For example if block size is 2^n then least significant n bits should be all 0's.



This lets IP addresses of block range from $NID.00...0$ to $NID.11...1$ } 2^n

Eg: Check whether below set of IP addresses form a valid CIDR block or not.

100.1.2.32
100.1.2.33
⋮
100.1.2.47

All the addresses are contiguous

~~And~~ size of block = $16 = 2^4$

starting address: $100.1.2. \boxed{00100000}$

least significant 4 bits are 0's.

$\therefore$ All 3 rules are satisfied

$\therefore$ It is a valid CIDR block.

Eg: $20.10.30.32$
 $20.10.30.33$
 $\vdots$
 $20.10.30.63$

Contiguous

Size = $2^5 = 32$

starting ~~id~~ host id: $\boxed{00100000}$

$\therefore$ valid CIDR block.

Eg: $150.10.20.64$
 $150.10.20.65$
 $\vdots$
 $150.10.20.127$

Contiguous

Size: $64 = 2^6$

$\boxed{01000000}$
6 bits

$\therefore$ valid CIDR block

This represented as $150.10.20.70/26$

This can be
any IP add in the
range

no of bits
in NID. Using this
Network id can be found

$\rightarrow$ Here also, the first address of block is used to represent block id or network id.

The last address of the block is used ~~for~~ as directed broadcast address.

Q: Find the ^{CIDR} block of addresses using below CIDR representation.

$$20.10.30.35/27$$

Sol:

no of bits in NID = 27

no of bits in host id : 5 $\Rightarrow$ LSB 5 bits must be 0

no of IP add : $2^5 = 32$ for starting add

$$20.10.30. \boxed{00100000}$$

= 20.10.30.32 is that starting address

$\therefore$ The range of addresses is 20.10.30.32

$$20.10.30.33$$

$$\vdots$$

$$20.10.30.63$$

Eg: $100.1.2.35/28$

$$100.1.2. \boxed{00100011}$$

$$\left. \begin{array}{l} \text{Range of add: } 100.1.2. \boxed{00100000} \\ \vdots \\ 100.1.2. \boxed{00101111} \end{array} \right\} \approx \begin{array}{l} 100.1.2.32 \\ \vdots \\ 100.1.2.47 \end{array}$$

Eg: $100.1.2.35/20$

Ans: 100.1.0.0 to 100.1.15.255

Subnetting in CIDR:

$\rightarrow$ Consider forming 2 subnets from block 20.30.40.10/25

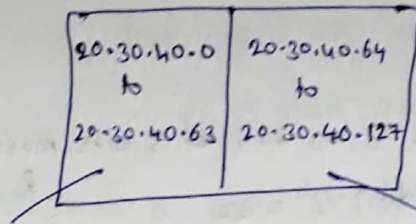
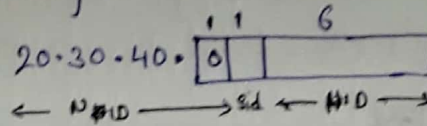
$\Rightarrow$ no of bits in host id = 7

$$\text{Block} \rightarrow 20.30.40. \boxed{00001010}$$

$$\Rightarrow \text{N/w id: } 20.30.40. \boxed{00000000}$$

Host id

Now by subnetting we have

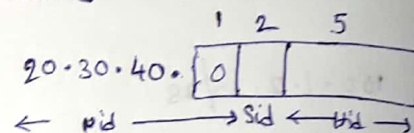
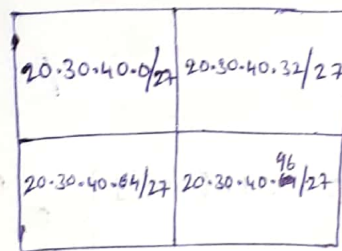


20.30.40.0/26
↓
Block id

20.30.40.64/26
↓
Block id

In CIDR representation ~~no~~ no bits in block id of subnet are represented. Also these bits represent ~~sub~~ subnet mask also.

Similarly we can divide it into 4 subnets

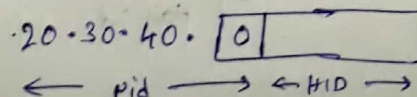
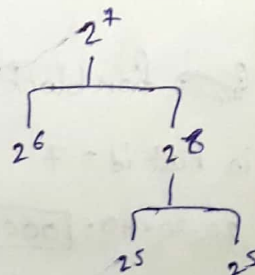


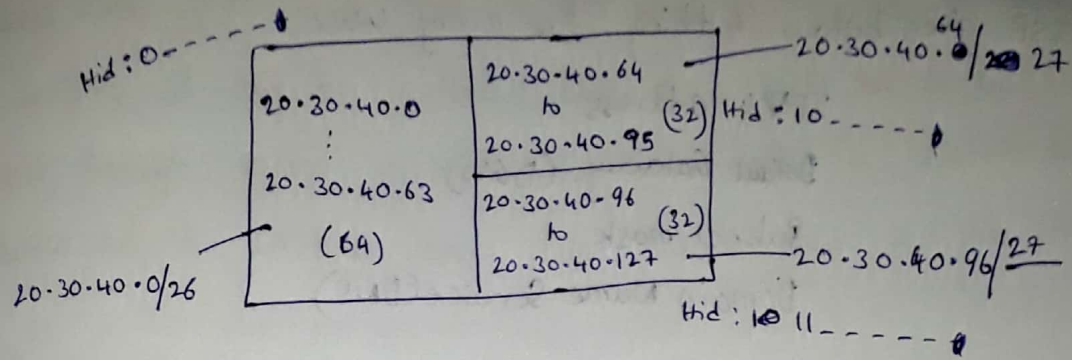
VLSM in CIDR Blocks

→ Consider 20.30.40.0/25

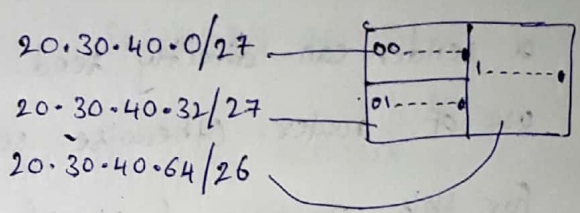
⇒ no of hosts: 2^7

Consider following division

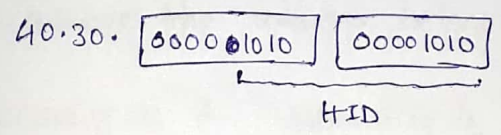




Another way of subnetting is



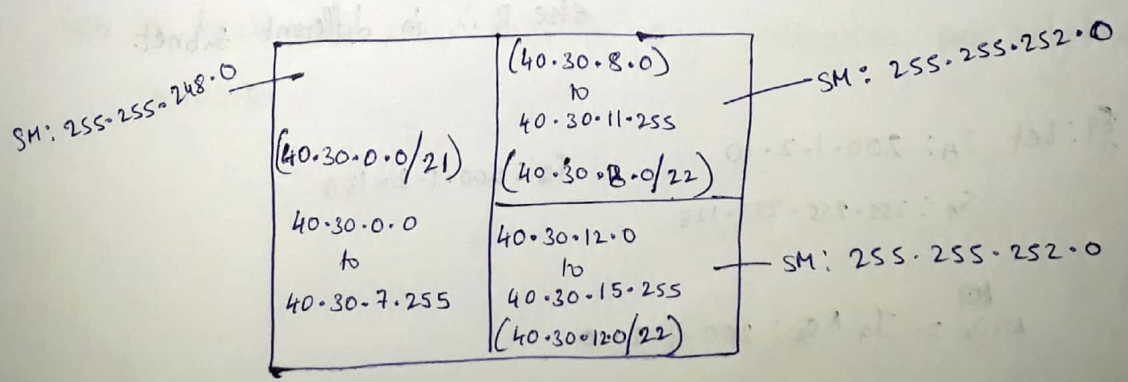
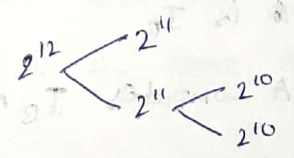
Eg: Consider $40.30.10.10/20$



$\therefore$ HID: $40.30.0.0$
no of IP add: 2^{12}

Range of add: $40.30.0.0$ to $40.30.15.255$

Consider subnetting this into 3 subnets as shown below



→ ISP gives below 4.thing for every user

IPv4 address

Default Gateway (DGW)

Subnet mask

Domain Name-Service (DNS)

→ Using ~~subnet mask~~ a IP destination is in same N/w then a sender can directly send packet to destination without use of router. Otherwise sender sends packet to router. For this purpose of identifying whether destination is within same ~~net~~ subnet or not, the host is provided subnet mask.

→ Consider



let IP add of A is I_A and subnet mask be S_A and ~~net id~~ be Nid_A

$$Nid_A = I_A \wedge S_A$$

let IP add of B is I_B

now A computes $I_B \wedge S_A$

if $Nid_A = I_B \wedge S_A$ then B is in same subnet
else B is in different subnet.

Eg: Let $I_A: 200.1.2.10$

$I_B: 200.1.2.130$

$S_A: 255.255.255.128$

$$Nid_A = I_A \wedge S_A: 200.1.2.0$$

$$I_B \wedge S_B: 200.1.2.128$$

$$Nid_A \neq I_B \wedge S_B$$

∴ B is in diff subnet. so A forwards pkt to DGW.

→ Subnet mask given to a host by ISP may or may not be correct. Sometimes it may be needed that a packet has to be sent through router even if the destination is within the same subnet. In that case false subnet mask will be given.

Eg: Consider

$$I_A: 200.1.2.10$$

$$I_B: 200.1.2.69$$

$$S_A: 255.255.255.128$$

$$S_B: 255.255.255.192$$

Here A knows that A & B are in same network.

But for B, it gets an illusion that A is in different subnet

If we assume the address belong to class C

According to A, subnetting is 

According to B, subnetting is 

→ Thus using subnet mask, security is provided

i.e., Some host must send data through router even if the destination is in the same network.

→ When subnet mask is 255.255.255.255,

a host must send data to any destination ~~any~~ only through a router

Supernetting or aggregation:

→ In ~~the~~ a routing table,

no of entries = no of networks connected to the router

→ For large no of networks, size of routing table grows exponentially.

→ So we perform supernetting using which create an illusion

to router that all the small networks belong to one network.

→ Supernetting doesn't really combine N/w's. It is an illusion.

Rules for aggregation:

(i) Addresses ⁱⁿ subnets ~~are~~ must be contiguous.

i.e., contiguous blocks can only be aggregated

(ii) Size of blocks must be same (sum of all block sizes ~~is~~ is power 2
provided given blocks are valid)

(iii) The first network id should be divisible by size of total aggregated block.

Ex: Consider supernetting of below 4 networks

200.1.0.0/24

200.1.1.0/24

200.1.2.0/24

200.1.3.0/24

Sol:

Addresses are contiguous

size of all blocks are same i.e., 2^8

Size of total aggregated block = $2^8 \times 2^2 = 2^{10}$

∴ Starting IP add 200.1.0.0 is divisible by 2^{10}

i.e., least significant 10 bits are 0's.

∴ supernetting is possible.

Now after supernetting the block is represented as
Supernet id : $200.1.0.0/22$ ~~$255.255.252.0$~~

Now the router will have only one entry instead of 4 entries.

For this block we have supernet mask

$$\text{Supernet Mask: } \cancel{200.1.} 255.255. \boxed{1111100} . \boxed{0000000} \\ = 255.255.252.0$$

→ The internal router will have 4 entries
 external router will have 1 entry

Eg: $200.1.32.0/24$
 $200.1.33.0/24$
 $\vdots$
 $200.1.47.0/24$

(i) Contiguous

(ii) sizes are same, i.e., $2^8 \times 16 = 2^{12}$

(iii) ID of 1st network

$$200.1. \boxed{00100000} . \boxed{00000000}$$

size of supernet: 2^{12}

Mid 1st network is divisible by 2^{12}

∴ Supernetting is possible.

⇒ Supernet id: $200.1.32.0/20$

$$\rightarrow 24 - \log_2(16) = 24 - 4 = 20$$

Supernet mask: $200.1. \boxed{} . \boxed{}$

$$255.255. \boxed{11110000} . \boxed{00000000}$$

$$255.255.240.0$$

*

Eg: $100.1.2.0/25$

*

$100.1.2.128/26$

$100.1.2.192/26$

(i) Contiguous

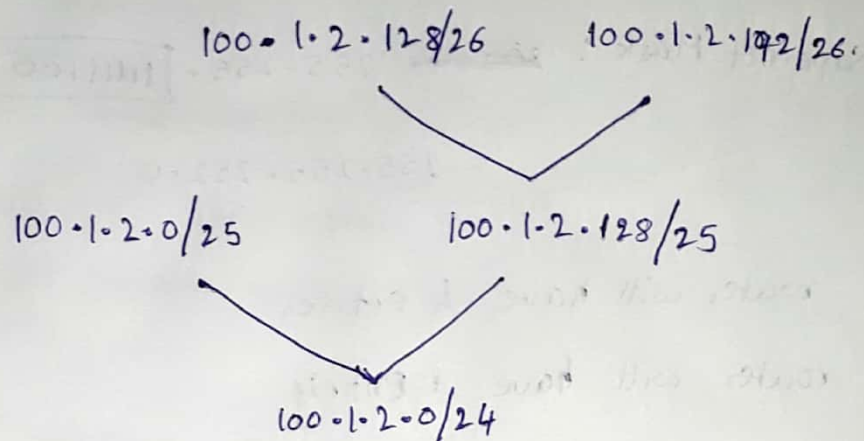
* (ii) Though size is not same, we can first supernet the 2 small networks and then supernet with the larger one.

(ii) ~~1st~~ size of supernet

$$\dots 2^7 + 2^6 + 2^6 = 2^8$$

~~1st~~ 1st N/w id is divisible by 2^8

$\therefore$ Supernetting is possible



Supernet id: 100.1.2.0/24

Supernet mask: 255.255.255.0

Q3/6-12 An Internet service provider has the following chunk.....

Sol:

The two variants possible are:

(i) 245.248.128.0/21 $\rightarrow A$

(ii) 245.248.136.0/22

(iii) 245.248.140.0/22

(i) 245.248.128.0/22

(ii) 245.248.132.0/22

(iii) 245.248.136.0/21 $\rightarrow A$

Flow Control Method

Delays in Computer Networks:

Transmission Delay (T_t)

It is time taken by the host to put that data packet on outgoing link.

Eg: If bandwidth = 1 bps

then for 10 bit data, transmission delay = 10 sec

If Data is L bits and bandwidth is B bits/sec then

$$\text{transmission delay} = \frac{L}{B}$$

Note:

Whenever k is given with data, it is 1024.

k is given with bandwidth, it is 1000

Eg: Silly for M & A

Eg: $L = 1000$ bits $BW = 1$ kbps

$$\Rightarrow T_t = \frac{1000}{1000} = 1 \text{ sec}$$

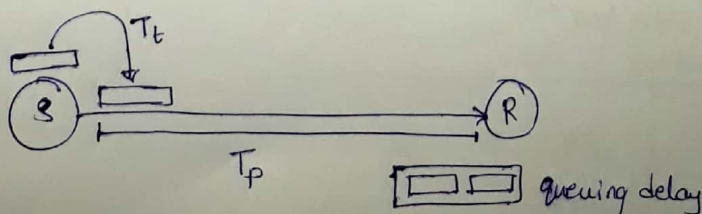
$L = 1$ kb

$BW = 1$ kbps

$$\Rightarrow T_t = \frac{1024}{1000} = 1.024 \text{ sec}$$

Propagation Delay:

It is amount of time required for data to travel from source to destination after data being placed on the link.



If d is the distance b/w the ~~sent~~ hosts and v is the velocity of signal then

$$T_p = d/v$$

Generally velocity of signal in optical fibre is 70% of velocity of light

$$\Rightarrow v = 2.1 \times 10^8 \text{ m/s}$$

Total time to send a packet = transmission delay + Propagation delay

$$= T_t + T_p$$

Queuing delay:

The packets that are sent are not processed immediately by the receiver. The sent packet will wait in a queue. The amount of time the packets wait in the queue, before they are processed, is called queuing delay.

Processing delay:

The amount of time required by the receiver to process the packet is called ~~pro~~ processing delay.

→ Queuing delay & processing delay depend on the speed of the receiver. In numerical, if not given, queuing delay and processing delay are considered 0.

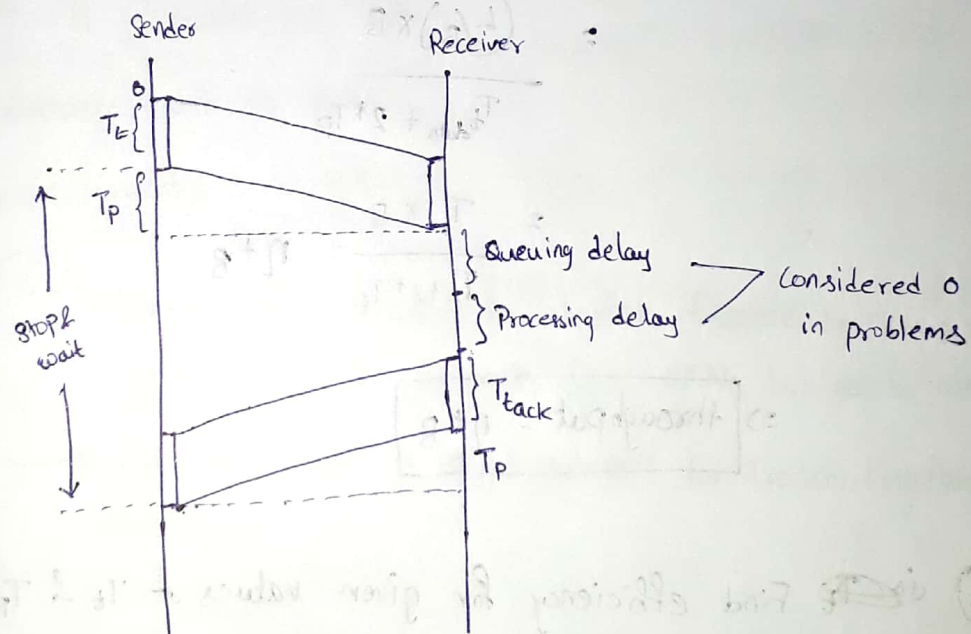
Flow Control Methods:

→ If receiver is slow and sender is fast, then packets sent by sender may get lost.

So the speed at which sender has to send the data depends on receiver. This is known as closed loop protocol.

Stop & Wait Protocol:

→ Here sender sends a packet and waits for the acknowledgment from receiver



∴ Total time to send one packet

$$= T_{t_{data}} + T_p + T_{ack} + T_p$$

$$\therefore \text{Total time in stop \& wait} = T_{t_{data}} + T_{ack} + 2 * T_p \cong T_{t_{data}} + 2 * T_p$$

↳ negligible compared to $T_{t_{data}}$ (without piggy backing)

$$= T_{t_{data}} + 2 * T_p$$

$$\text{efficiency} = \frac{\text{useful time}}{\text{total cycle time}} = \frac{T_{\text{data}}}{T_{\text{data}} + 2 * T_p} = \frac{1}{1 + 2 \left(\frac{T_p}{T_{\text{data}}} \right)}$$

$$= \frac{1}{1 + 2a} \quad \left(a = \frac{T_p}{T_{\text{data}}} \text{ This just for simplicity} \right)$$

throughput: no of bits (effective) sent per second.

↳ also known as effective bandwidth / bandwidth utilization.

$$\text{throughput} = \frac{L}{T_{\text{data}} + 2 * T_p}$$

L is size of data

$$= \frac{(L/B) * B}{T_{\text{data}} + 2 * T_p}$$

$$= \frac{T_t * B}{T_t + 2 * T_p} = \eta * B$$

$$\Rightarrow \boxed{\text{throughput} = \eta * B}$$

Q4) Find efficiency for given values of T_t & T_p

(i) $T_t = 1 \text{ ms}$ $T_p = 1 \text{ ms}$

Ans: $\frac{1}{3} \Rightarrow 33.33\%$

(ii) $T_t = 2 \text{ ms}$ $T_p = 1 \text{ ms}$

Ans: $\frac{1}{2} \Rightarrow 50\%$

Q5) Find relation b/w T_p & T_t if min efficiency is 0.5

sol:

$$\eta \geq 0.5$$

$$\frac{T_t}{T_t + 2T_p} \geq \frac{1}{2}$$

$$2T_t \geq T_t + 2T_p$$

$$T_t \geq 2T_p$$

Factors affecting efficiency in stop & wait:

$$\eta = \frac{1}{1 + 2\left(\frac{T_p}{T_t}\right)}$$

$$\eta = \frac{1}{1 + 2\left(\frac{d}{v}\right) + \left(\frac{B}{L}\right)}$$

for a given medium v & B are fixed

So η depends on d & L

distance, $d \uparrow \Rightarrow \eta \downarrow$

size of packet, $L \uparrow \Rightarrow \eta \uparrow$

$\therefore$ Stop & wait is good for shorter distance transmissions
 $\therefore$ It is good for networks like LANs but not for WANs
 Also stop & wait is good ~~while~~ for transmitting larger packets.

Note:

→ If sender doesn't receive ~~a packet~~ acknowledgment it may be due to 2 reasons

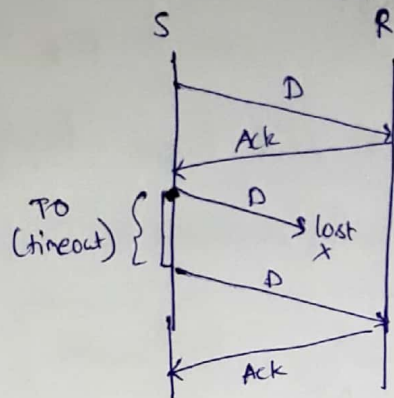
- (i) Data is lost
- (ii) Ack is lost

Data packet lost Problem:

Assume a case where sent packet is lost. Then receiver won't send ack and sender assumes data is lost.

So sender waits for a fixed amount of time; timeout and ~~resends~~ resends the same data.

This variant of stop & wait is called Stop & Wait ARQ



Automatic Repeat Request

→ without using this variant, the sender & the receiver may go to deadlock (sender waits for ack & receiver waits for data)

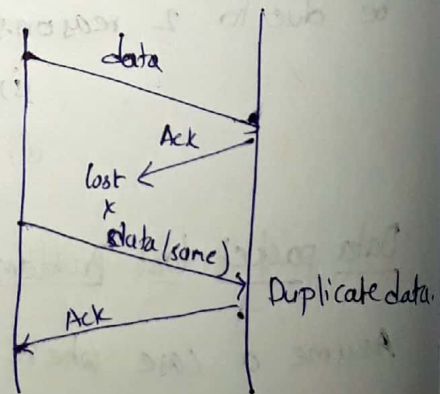
Duplicate Packet Problem:

→ This problem occurs when ack sent by receiver is lost.

→ In this case, sender assumes data is lost and resends it.

→ Now receiver receives the same packet again. This problem is called duplicate packet problem.

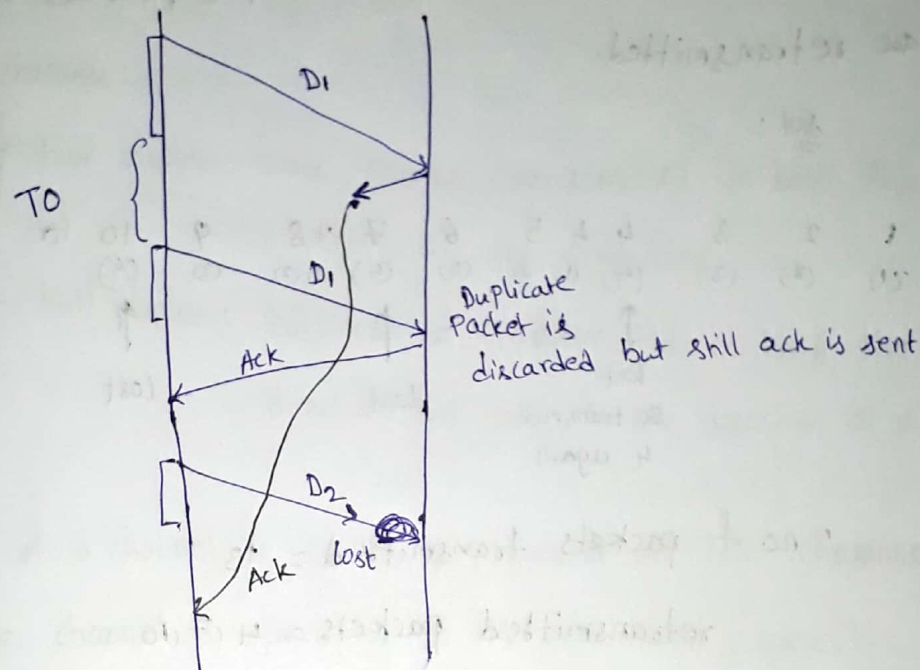
→ To solve this problem we use sequence number for every packet.



→ So here we have timeout along with sequence number.

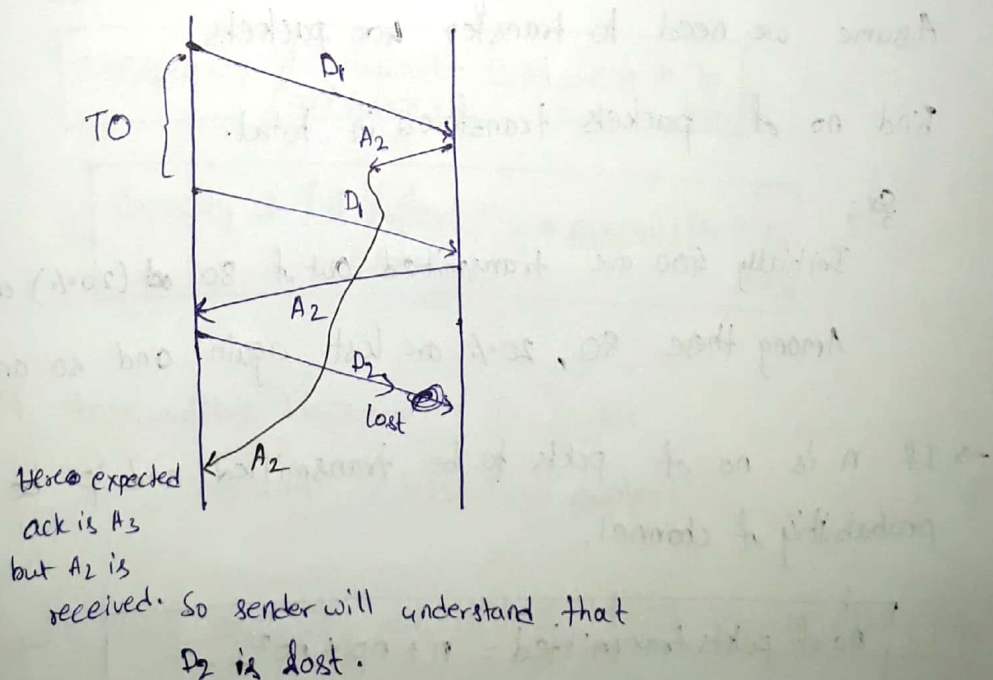
Delayed Acknowledgment (Missing packet problem):

→ Here ack is not lost but it is delayed such that timeout occurs and sender retransmits the data.



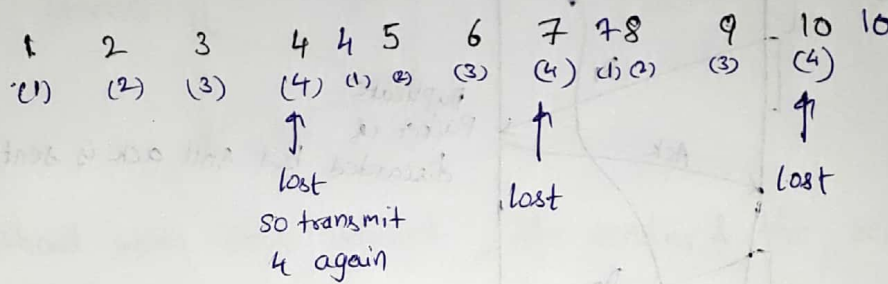
→ Here even though D_2 is lost, sender gets the ack of D_1 and thus sender thinks that D_2 is received by the receiver.

→ To avoid this problem we give sequence number for ack also.



Q6) Consider using stop & wait protocol and transmitting 10 packets. Assume every 4th packet that is transmitted is lost. Find total no of packets that are transmitted and also find the packets that are retransmitted.

Sol:



∴ no of packets transmitted = 13

retransmitted packets = 4, 7, 10

Note:

→ Consider a channel b/w source & destination in which error probability of channel = 0.2

Assume we need to transfer 400 packets.

Find no of packets transferred in total.

Sol:

Initially 400 are transmitted out of 80 (20%) are lost.

Among these 80, 20% are lost again and so on...

→ If n is no of pkts to be transmitted and ' p ' be error probability of channel,

$$\begin{aligned} \text{no of pkts transmitted} &= n + np + np^2 + \dots \\ &= n \left(\frac{1}{1-p} \right) \end{aligned}$$

Here $n=400$; $p=0.2$

no of pkts transmitted = $400 \left(\frac{1}{1-0.2} \right) = 500$ pkts.

Capacity of channel/wire/link:

types of channels:

- Full duplex: Data can be transmitted in both the directions at the same time.
- Half duplex: Data can be transmitted in both the directions but only in one direction at a time.

→ Capacity of a channel is no of bits present on the channel when the channel is operating at its maximum capacity.

→ After a bit is placed on the channel it takes T_p time (propagation delay) to reach the other end. That means all the bits placed on the channel during this time T_p are present on the channel.

$$\therefore \text{Capacity of channel (half duplex)} = \text{Bandwidth} * T_p \text{ bits}$$

$$\text{Capacity of full duplex Channel} = 2 * \text{Bandwidth} * T_p \text{ bits}$$

Eg: If bandwidth = 1 bps and $T_p = 10$ sec

capacity = 10 bits (half duplex)

→ Channels with high capacity are called thick channel/thick pipe

→ One more disadvantage of stop & wait, it is not good with thick channels. But it is good with thin-pipes

∴ stop & ^{wait} thick channels → less efficiency

stop & wait, thin pipe → high efficiency.

$$\eta = \frac{1}{1 + 2 \times \frac{T_P}{T_t}} = \frac{1}{1 + \frac{2 \times T_P \times B}{L}} = \frac{1}{1 + \frac{\text{Capacity}}{L}}$$

Capacity ↑ ⇒ efficiency ↓

Pipelining / Sliding Window Protocol:

→ This is a technique used to increase efficiency.

$$\eta = \frac{1}{1 + 2a}$$

This means only 1 unit of time is used in (1+2a) units.

which means we can increase efficiency by transmitting packets in that 2a units of time also.

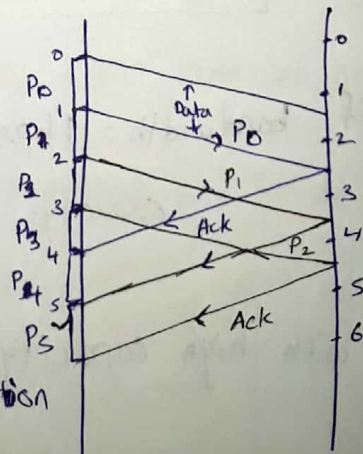
This is known as pipelining.

Eg: Consider $T_t = 1 \text{ ms}$ $T_P = 1.5 \text{ ms}$

$$\eta = \frac{1}{1 + 2a} = \frac{1}{1 + 2\left(\frac{1.5}{1}\right)} = \frac{1}{4}$$

Here ack of P_0 is received at ~~end~~ after 4 units of time.

so sender has to save P_0 until that time so that retransmission can be done if P_1 is lost



$P_3 \ P_2 \ P_1 \ P_0$

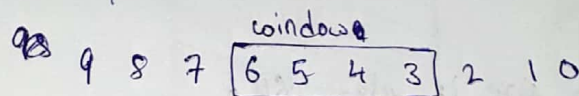
So minimum window size required = 4

↳ group of packets saved by sender so that retransmission can be done if needed.

→ Packets in window are called outstanding packets.

→ After 4 units of time, packet P_0 will be discarded from buffer (window) and P_4 will be stored.

→ Packets in the window are those that are waiting for ack.



As the time progresses, the window slides towards left.

* → Minimum size of window required = $1 + 2a = \frac{1}{n}$ packets
 * (ws) ↳ (ceil if not integer)

→ Sequence number has to be stored in the header of packet.

So we cannot use arbitrarily large no of bits for seq. num.

Initially pkts in window are P_3, P_2, P_1, P_0

later when P_0 is discarded, we can again use sequence number 0.



* Thus no of bits needed for representing seq. num = $\lceil \log_2 (1 + 2a) \rceil$

(Q7) $T_t = 1 \text{ ms}$; $T_p = 49.5 \text{ ms}$; Find min window size req & min no of bits req in seq num.

Ans: 100 & 7

→ But sometimes due to protocol overhead, ~~max~~ no. of bits in seq. num. field may be less.

i.e., for example in (Q7) no. of bits may be just 6, but not 7 in this case we won't get max efficiency.

$$\text{So here efficiency} = \frac{\text{no. of pckts sent}}{\text{max possible no. of pckts that can be sent}} = \frac{64}{100} \approx 64\%$$

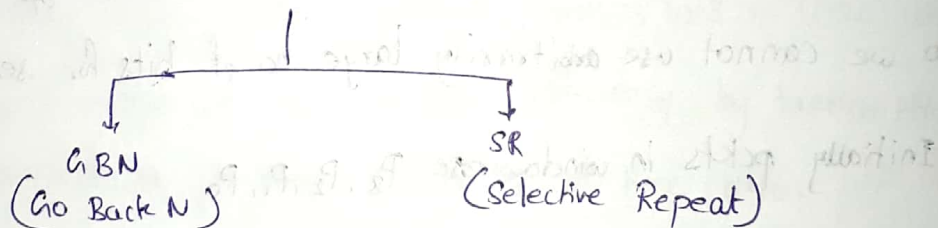
So here window size is also 64.

→ If size of seq. number is n bits, then

$$\text{window size} = \min(1+2a, 2^n)$$

04/12/20

→ Sliding window protocol is a theoretical concept. It can be implemented in 2 ~~two~~ ways:



Go Back N; ($N > 1$)

i) Sender window size in Go Back N is N and $N > 1$

If $N=1$ it is just stop & wait.

Q: Consider using GB 10 and $T_t = 1\text{ms}$ $\uparrow$ $T_p = 49.5\text{ms}$, $BW = 40\text{Mbps}$. Find η

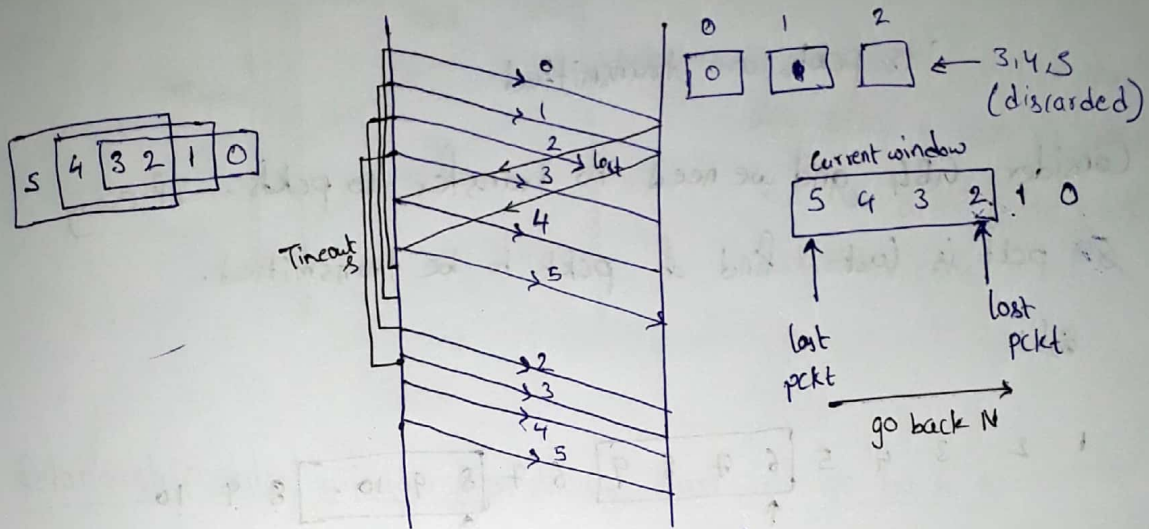
sol:

$$\eta = \frac{\text{no. of pckts sent}}{\text{max possible}} = \frac{10}{1+2a} = \frac{10}{100} \text{ i.e., } 10\%$$

$$\text{throughput} = \eta * B = \frac{10}{100} \times 40 = 4\text{ Mbps}$$

ii) Receiver window size = 1

Eg: Consider below situation & let sender window size = 4



→ Consider a situation where receiver receives packet 0 & 1 but packet 2 is lost. By the time timeout of packet 2 occurs sender transmits packets 3, 4, 5.

~~After the timeout~~

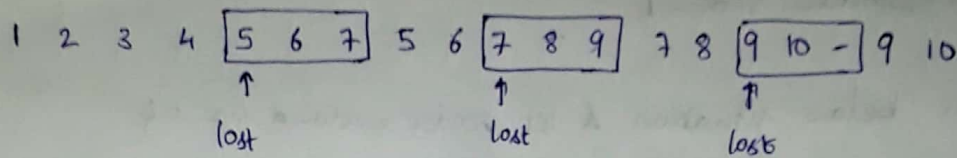
→ Here receiver first receives packets 0, 1 and waits for packet 2. packet 2 is lost and receiver will reject packets 3, 4, 5.

→ So considering this, after timeout of packet 2, sender again sends packets 2, 3, 4, 5 by going back 4.

→ Here the window slides once the ack of oldest packet of window is received

* Eg: In GB3, if every 5th packet that is being transmitted is lost and if we have to send 10 packets, then how many transmissions are required.

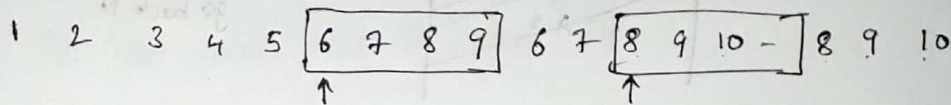
Sol:



∴ 18 pkts are transmitted

Q6) Consider GB4 and we need to transfer 10 pkts. If every 6th pkt is lost, find # pkts to be transmitted.

sol:



∴ 17 pkts are to be transmitted.

(iii) Go Back N uses cumulative acknowledgment:

Ack is of two types:

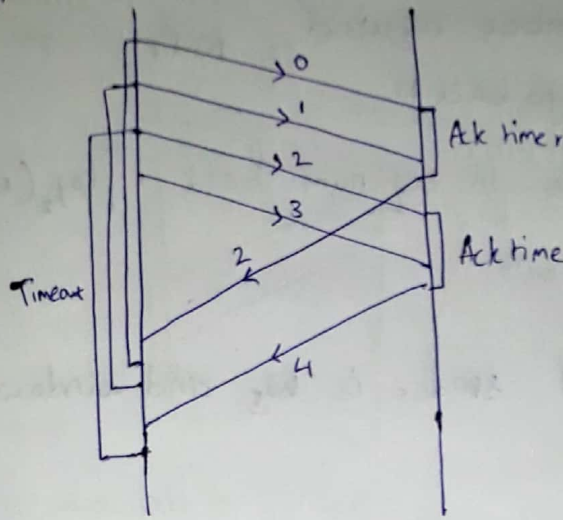
- Cumulative^{ve} ack: One ack is sent for group of packets
adv: less traffic
- ~~indep~~ indep: less reliable (∵ even if one pkt is lost, ack is not sent and all has to be retransmitted)
- independent ack: one ack is sent is for each packet.
adv: more traffic
disadv: more reliable

→ Receiver has an acknowledgment timer. Once a pkt is received the receiver starts timer and once the timer expires receiver send ack for all the pkts received in that time.

→ Ack time should not be so large that time out occurs on sender side.

∴ timeout timer > ack timer.

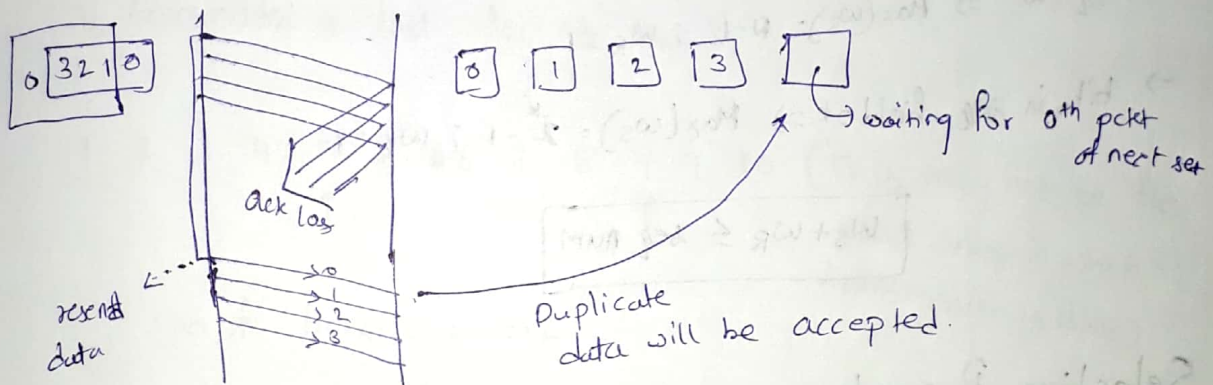
→ Also ack timer should not be too small.



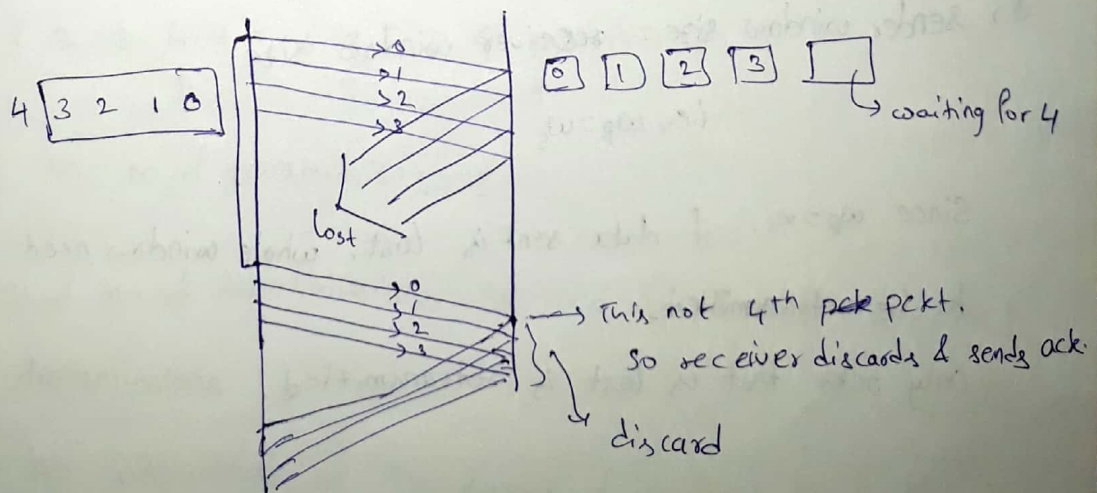
Ack timer → new ack timer starts only after a pkt is received but not after the previous ack timer ends

Relationship b/w window size & seq num in go back N:

Consider GB4 and let no of seq numbers available = 4.



But if take ~~seq~~ no of seq numbers = 5 then we will not have this problem



so here no of seq numbers required $\leq N+1$
in go back N

$$\text{no of bits in seq num field} = \lceil \log_2(N+1) \rceil$$

Note:

slly if window size of sender is w_s and window size of receiver is w_r ,

$$\text{no of seq numbers req} = w_s + w_r$$

$$\text{no of bits in seq num field} = \lceil \log_2(w_s + w_r) \rceil$$

Note:

In GBN,

$$\rightarrow w_s = N \quad w_r = 1 \Rightarrow \text{seq} = N+1$$

$$\rightarrow \text{seq} = N \Rightarrow \text{Max}(w_s) = N-1 \quad ; w_r = 1$$

$$\rightarrow \text{bits in seq field} = k \Rightarrow \text{Max}(w_s) = 2^k - 1 \quad ; w_r = 1$$

$$\boxed{w_s + w_r \leq \text{seq num}}$$

Selective Repeat:

(i) Sender window size > 1

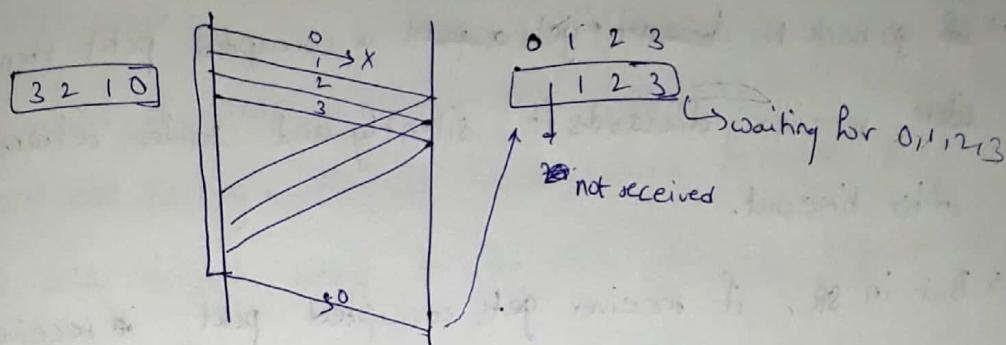
(ii) sender window size = receiver window size

$$\text{i.e., } w_r = w_s$$

Since $w_r = w_s$, if data sent is lost, whole window need not to be retransmitted.

only pkt that is lost is retransmitted.

Eg: let $w_R = w_S = 4$



Assume data pkt 0 is lost.

Still receive can accept pkts 1, 2, 3 'Cuz it has sufficient window.

So here no of retransmission req will be less.

Eg: Consider we need send 10 pkts where every 5th pkt that is transmitted is lost. let $w_S = w_R = 3$

1 2 3 4 5 5 6 7 8 9 9 10 (This may not be the exact order in which transmission is done)

$\therefore$ no of transmission = 12

but go back N required 18 transmission.

Eg: Consider 10 packets to be transmitted and every 4th pkt is lost.

1 2 3 4 4 5 6 7 7 8 9 10 10

Here no of transmissions = 13

→ In terms of no of transmissions SR and stop & wait have same no of transmissions

→ So SR has advantages of Stop & wait & go back N. But there are some disadvantages too.

3) SR uses independent acknowledgment

In ~~the~~ go back N ~~sender~~ receiver gets ~~a~~ corrupted pkt then, ~~the~~ receiver discards it silently and sender retransmits after time out.

→ But in SR, if receiver gets corrupted pkt, receiver sends negative ack to sender so that sender ~~trans~~ retransmits the corrupted pkt even before the time out.

Comparison b/w the protocols:

	Stop & Wait	GBN	SR
Efficiency	$\frac{1}{1+2a}$	$\frac{N}{1+2a}$	$\frac{w_s}{1+2a}$
Buffer req (sender + receiver)	1+1	N+1	$w_s + w_r$
Min seq num required needed	1+1=2	N+1	$w_s + w_r$
Retransmission per pkt loss	1	N	1
BW req/ BW consumption	low	high	moderate
CPU requirement	low	moderate	high
Implementation difficulty	low	moderate	high
ack	independent	cumulative	independent

→ BW requirement is high for GBN, ~~we need~~ because of more no. of retransmissions

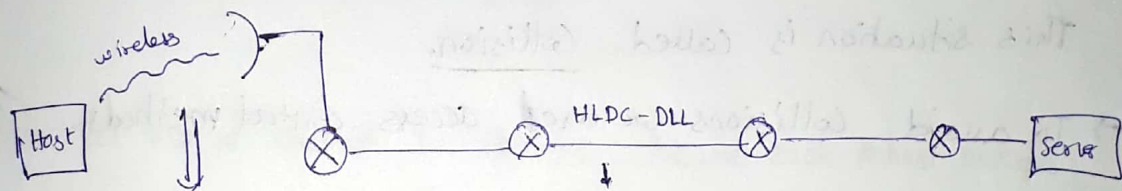
→ In SR, out of order pkts are also accepted. so it needs to perform ~~sort~~ sorting. Also it has to search for lost pkt.

But GBN doesn't need to do this. so CPU requirement in SR is high.

→ If BW is ~~low~~ high, CPU is less efficient, buffers are less then GBN is used

If BW is moderate, CPU is more available, buffers are more then SR is used

Example:



BW ↓
error ↑
out of order ↑
CPU ↑ (∵ it is not used for routing)

BW ↑ (∵ wired)
error ↓ (∵ wired)
out of order ↓ (∵ wired)
CPU ↓ (∵ CPU is used for routing) ↓ avail

so for end to end connection, we used SR protocol

so b/w two router (link to link) GBN is used

→ A system may have several processes running.

Each process has its own buffer. These buffers are operated with SR protocol.

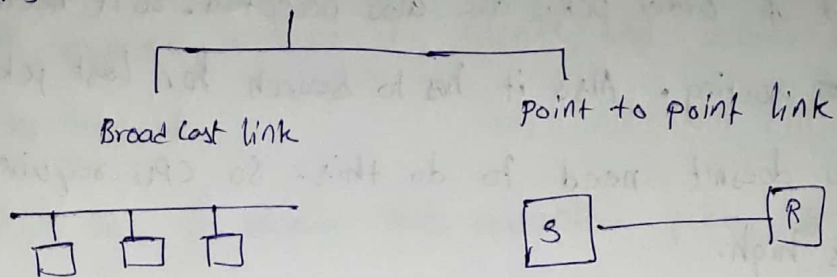
All the packets (from diff processes) will be sent to DLL. At this layer, the buffers are operated with GBN.

so for higher level layers SR is used and for lower level layers GBN is used.

TCP — (SR (75%), GBN (25%))

Access Control Methods:

→ Links are of 2 types



All hosts connected to same link

Dedicated link is present b/w two systems.

→ In broadcast link, there may be a chance that multiple station may transmit data at the same time

This situation is called Collision.

→ To avoid collisions we used access control methods.

Time Division Multiplexing (TDM):

→ It is an access control method.

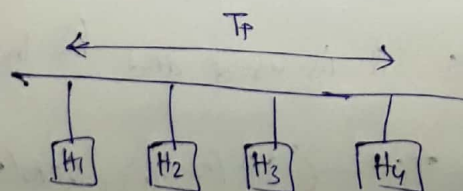
→ Here we divide timeline into slots and each host transmits in its allocated slot in round robin fashion.

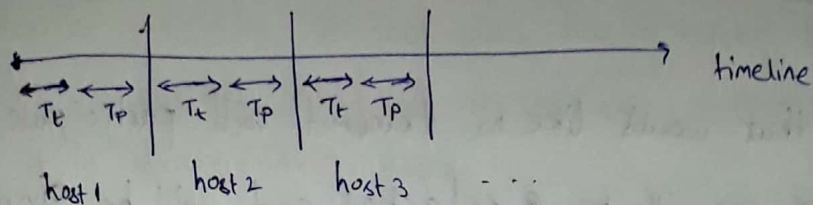
→ Allocated slot should be large enough that a host can transmit data.

i.e., time slot $= T_t + T_p$

Assuming that every station send same amount of data

Propagate delay in the worst case. i.e., when sender and destination are at two different ends of the channel.





$\Rightarrow$ efficiency, $\eta = \frac{\text{Useful time}}{\text{cycle time}} = \frac{T_t}{T_t + T_p} = \frac{1}{1+a}$, $a = \frac{T_p}{T_t}$

Ex: $T_t = 1\text{ms}$, $T_p = 1\text{ms}$ & $BW = 4\text{Mbps}$. Find η & effective BW (throughput)

$$\eta = \frac{1}{1 + \frac{T_p}{T_t}} = \frac{1}{2} = 50\%$$

$$EBW = \eta \times BW = 2\text{Mbps}$$

Ex: Let BW of channel be 2 Mbps. Assume each host needs BW of 2 kbps. Then find max no of hosts possible satisfying this requirement using TDM.

Sol:

$$N \times 2\text{kbps} = 2\text{Mbps}$$

$$\Rightarrow N = 1000$$

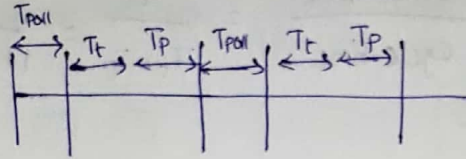
Disadvantages:

$\rightarrow$ If a station doesn't want to transmit data, then the slot reserved for that station is wasted.

$\rightarrow$ This disadvantage is overcome using polling

Polling:

- The system that would like to transmit will participate in polling
- From these one will be selected and will be given time to transmit.



$$\eta = \frac{T_t}{T_{poll} + T_t + T_p}$$

↳ taken as 0 if it is negligible.

Disadv:

- Time for polling is a wastage.

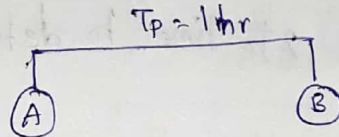
CSMA/CD : (Carrier Sense Multiple Access Collision Detection)

- Every host, before sending, senses the carrier and if it is free then it transmits data.
- However a host can sense only the part that it is connected to the channel.
- Also two stations may sense that the channel is empty and initiate transmission at the same time.
- CSMA/CD doesn't use acknowledgement since it is mostly used in LANs. So we need to detect that collision has occurred without using acknowledgment.
- Collision produces a signal with different frequency from data. So a device can detect collision if it sees this signal.

→ A device thinks ~~it~~ collision has occurred and its data is corrupted only if it senses collision signal while it is transmitting data.

→ So we make sure that every device transmits long enough that even in the worst case the collision signal will reach the device.

For example consider



let $t = 10:00$ AM

let A & B both sense that channel is ~~empty~~ free and started sending data.

Then collision occurs at 10:30

and both A, B will detect ^{collision} signal at 11:00 AM

so this collision can be detected if $T_{tA} > 1\text{hr}$.

however this not the worst case.

Consider A has transmitted data to B and when it's just about to reach B (after 1hr) B has started transmission.

Then this collision will be detected by A by 11 after 1hr.

A transmission initiation: 10:00 AM

collision: 11:00 AM

detection by A: 12:00 PM

∴ To detect any collision, $T_t \geq 2T_p$

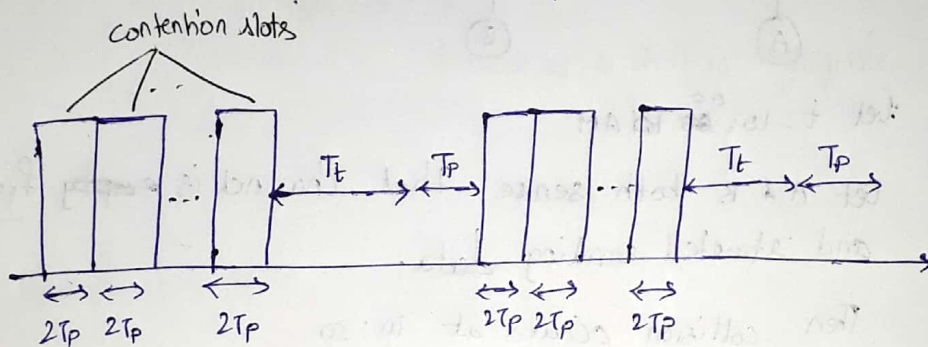
i.e., min data to be transferred, $L \geq 2 \times T_p \times B$

→ If we don't have sufficient amount of data to transfer then we need to ~~pad~~ pad extra bits.

Efficiency of CSMA/CD: ↳ (Ethernet)

→ Before a successful transmission, a series of collisions may occur. (we don't know the no of collisions)

In the worst case it takes $2T_p$ time to detect collision



$$\text{efficiency} = \frac{T_t}{C * (2T_p) + T_t + T_p}$$

$C \rightarrow$ no of collision slots in each cycle.

~~The~~ Finding C :

Assume we have n stations & every station transmits ~~data~~ with probability p .

So there will no collision if only one station transmits the data.

$$\Rightarrow P_{\text{success}} = n C_1 \times p \times (1-p)^{n-1} = np(1-p)^{n-1}$$

$$\begin{aligned} \frac{dP}{dp} &= np(n-1)(1-p)^{n-2}(-1) + n(1-p)^{n-1} \\ &= n(1-p)^{n-1} - n(n-1)p(1-p)^{n-2} = 0 \\ &= n(1-p)^{n-2} [(1-p) - (n-1)p] = 0 \end{aligned}$$

$$\Rightarrow (1-P) - (n-1)P = 0$$

$$\Rightarrow np - P - 1 + P = 0 \Rightarrow \boxed{P = 1/n}$$

$$\Rightarrow P_{\max} = n \times \frac{1}{n} \times \left(1 - \frac{1}{n}\right)^{n-1}$$

$$P_{\max} = \left(1 - \frac{1}{n}\right)^{n-1}$$

If n is sufficiently large

$$P_{\max} = \lim_{n \rightarrow \infty} \left(1 - \frac{1}{n}\right)^{n-1}$$

$$\boxed{P_{\max} = 1/e}$$

$\Rightarrow$ no. of times we should try (collisions) before getting the

$$\text{first success} = \frac{1}{P_{\max}} = e$$

i.e., e collisions

$\therefore$ value of $c = e$

$$\therefore \text{Efficiency, } \eta = \frac{T_t}{(2e+1)T_p + T_t} = \frac{1}{1 + 6.44a}$$

$$\eta = \frac{1}{1 + 6.44 \left(\frac{d}{v}\right) \left(\frac{B}{L}\right)}$$

$d \uparrow \Rightarrow \eta \downarrow$

$\therefore$ CSMA/CD is good for ~~small~~ LANs

$L \uparrow \Rightarrow \eta \uparrow$

$\therefore$ CSMA/CD has good efficiency for larger packets.

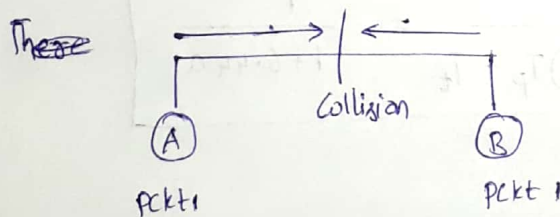
Backoff Algorithm:

- This algorithm is used to give waiting time (back off time) to stations that involved in collision.
- This is also known as binary exponential back off algorithm.
- This algorithm applies only for 2 stations.
- Every packet is given a collision number.
i.e., the number collisions the pkt has involved in.
- After a pkt gets collided, its collision number is incremented.
- ~~Once a collision~~ After this both the hosts select a number in the range $[0, 2^n - 1]$
where n is collision number.

Let the selected number be k .

Then waiting time = $(k * \text{time slot})$

Eg: Consider a case where two stations A & B want to transmit data



Collision number
for pkt1 = 1

Collision number
for pkt1 = 1

choose a num b/w
 $(0, 2^1 - 1)$ ~~(0, 1)~~
 $\approx (0, 1)$

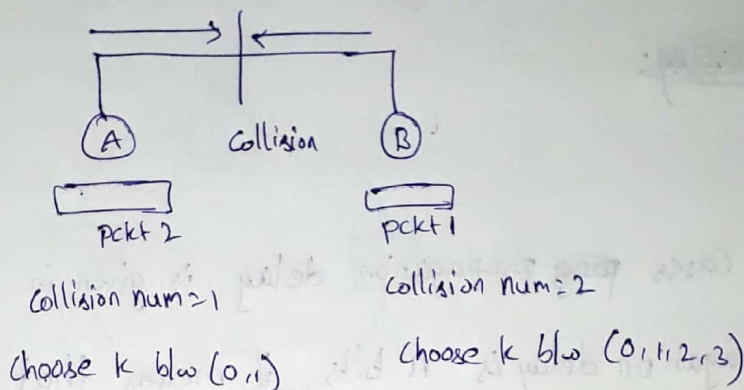
choose a num
b/w $(0, 1)$

A	B	
0	0	→ collision
0	1	→ A transmits
1	0	→ B transmits
1	1	→ collision

let $P(A)$, $P(B)$, $P(\text{collision})$ be probabilities that A transmits, B transmits, collision occurs

$$P(A) = 1/2; P(B) = 1/2; P(\text{collision}) = 2/4$$

Assume A has transmitted here and it is ready with packet 2 and B is ready with packet 1



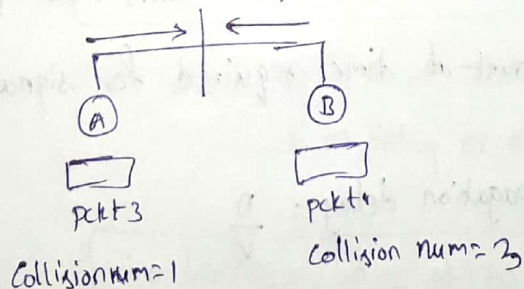
A	B
0	0 → collision
0	1 → A
0	2 → A
0	3 → A
1	0 → B
1	1 → A
1	2 → A
1	3 → A

$$\Rightarrow P(A) = 5/8$$

$$P(B) = 1/8$$

$$P(\text{collision}) = 2/8$$

Now if A is successful again, we have below scenario



$$\Rightarrow P(A) = 13/16$$

$$P(B) = 1/16$$

$$P(\text{collision}) = 2/16$$

observations:

→ As collision number ~~is~~ increases, the probability of collision is decreasing exponentially

→ If a system wins in transmitting ~~success~~ successfully then its probability of winning for further transmission increases exponentially while the probability of other system decreases exponentially. This is a disadvantage.

This is known as capturing effect.

Token Passing.

Note:

→ In some cases ~~prop~~ propagation delay is given in bits.

If propagation delay is n bits, it means that ~~it is~~ ~~amount~~ ~~to~~ ~~prop~~ propagation delay is equal to transmission delay of n bits.

$$\text{i.e., propagation delay of } n \text{ bits} = \frac{n}{B} \text{ sec}$$

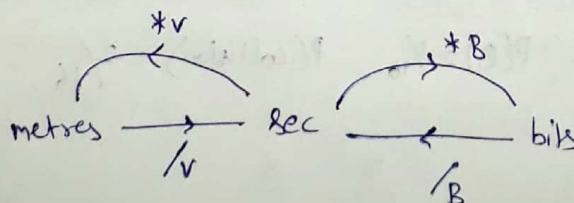
$B \rightarrow \text{Bandwidth.}$

⑤

→ In some cases, ~~prop~~ propagation delay is given in meters.

If propagation delay is n metres, it means that propagation delay is equal to amount of time required for signal to travel n metres.

$$\text{i.e., propagation delay} = \frac{n}{v}$$

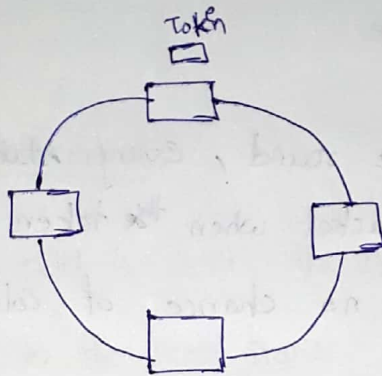


Token Passing:

→ It is an access control method.

→ All the hosts are connected in a ring topology.

A token is present and this token moves ~~across~~ around the ring. This is known as token ring whichever host has the ~~token~~ ^{can} transmit the data.



Ring latency: it amount of taken for a bit to travel around the ring and come back to the same point.

A bit while travelling around the ring, the bit has to be read by every station.

$$\therefore \text{Ring latency} = \frac{d}{v} \text{ sec} + (N \times b) \text{ bits}$$

where $N \rightarrow$ no of stations

$b \rightarrow$ delay at each station in bits

$$\Rightarrow \text{ring latency} = \left(\frac{d}{v} + \frac{N \times b}{B} \right) \text{ seconds}$$

$\hookrightarrow$ Bandwidth

(or)

$$\text{ring latency} = \left(\frac{d}{v} * B + N \times b \right) \text{ bits}$$

Token holding time: It is amount of time for which a token is held at any station.

$$\text{Cycle time} = \left(\frac{d}{v} + N * THT \right)$$

$\downarrow$ $\downarrow$
time req for a token to travel around the ring for one time (T_p) token holding time

time req for a token to travel around the ring for one time

→ when token make one round, every station transmits exactly one ~~pack~~ packet when the token comes to it.
So here there will be no chance of collisions.

Efficiency, $\eta = \frac{\text{useful time}}{\text{Cycle time.}}$

$$\eta = \frac{N * T_t}{T_p + N * THT}$$

→ There are 2 mechanisms for token passing.

i) Delayed token reinsertion

ii) Early token reinsertion → Default consideration

i) Delayed token reinsertion:

After getting the token, system transmits data and waits until data returns to the same system. Once data comes back, token is passed to next ~~has~~ station.

Here $THT = T_t + \text{ring latency}$

$$= T_t + T_p + N * b$$

$$= T_t + T_p \text{ (assuming } b=0)$$

so in this strategy

$$\text{efficiency, } \eta = \frac{N + T_t}{T_p + N(T_t + T_p)}$$

$$\eta = \frac{1}{1 + \left(\frac{N+1}{N}\right)a}, \quad a = T_p/T_t$$

(ii) Early Token Reinsertion:

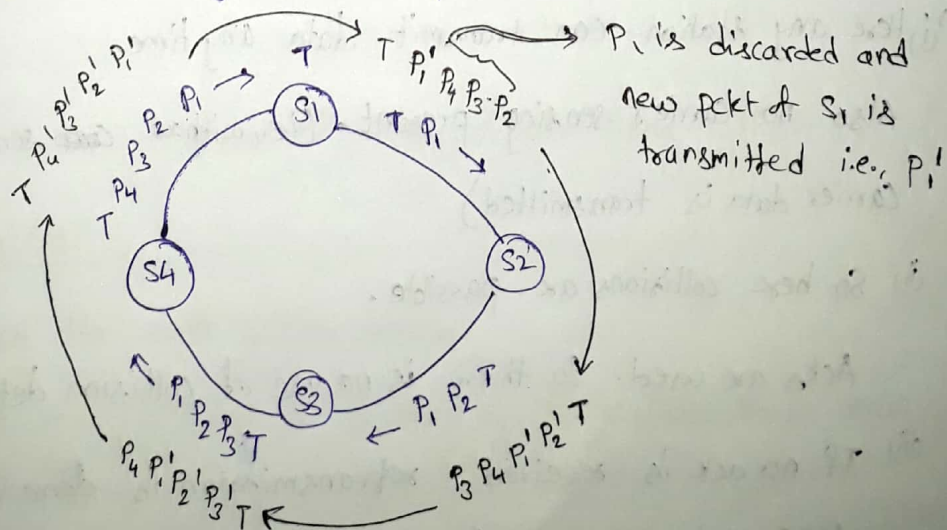
As soon as pkt is sent, the station ~~sends that to~~ passes the token to the next station.

→ Assume token is with S_1 . So S_1 sends P_1 and then places the token.

Now S_2 after receiving P_1 & T , S_2 forwards P_1 then it sends its data P_2 and then finally forwards T .

Similarly S_3 forwards P_1 then P_2 then its pkt P_3 then the token T .

Also, in token ring ~~then to data~~ sender has to remove the pkt from ring once the pkt comes back to the sender.



So here, $THT = T_t$ (i.e., token is held until pkt is transmitted)

So efficiency, $\eta = \frac{N * T_t}{T_p + N * T_t}$

$$\eta = \frac{1}{1 + \frac{a}{N}}, \quad a = T_p / T_t$$

- For efficiency it is clear that early token reinsertion is good

→ ETR is efficient but less reliable ($\because$ more than 1 pkt is present at a time on the channel)

→ DTR is less efficient but more reliable

→ In ETR, at any given time n number pkts are present in the ring.
↓
no. of hosts

In DTR, at any given time only one pkt is present. ~~at any given time~~

ALOHA:

→ It is another access control method.

→ (i) Here any station can transmit data any time.

Also no carrier sensing present. (i.e., without ~~carrier~~ sensing the carrier data is transmitted)

(ii) So here collisions are possible.

Acks are used. So there is no use of collision detection.

(iii) If no ack is received, retransmission is done after some random amount (back off time) of time.

ALOHA is of 2 types:

- (i) Pure aloha
- (ii) Slotted aloha

Pure aloha:

→ All the 3 rules apply here.

→ If a transmission has to be done ~~no~~ without collision, no one should ~~be~~ have transmitted before T_t time and no one should transmit for next T_t time.

∴ This is known as vulnerable time.

Here vulnerable time = $2T_t$ (neglecting T_p)

Efficiency, $\eta = G * e^{-2G}$

where $G \rightarrow$ no. of stations who wants to transmit in T_t slot.

$$\frac{d\eta}{dG} = 0 \Rightarrow G = 1/2 \rightarrow \text{i.e., only 1 station transmits in vulnerable time.}$$

$$\Rightarrow \eta_{\max} = \frac{1}{2} \times e^{-1}$$

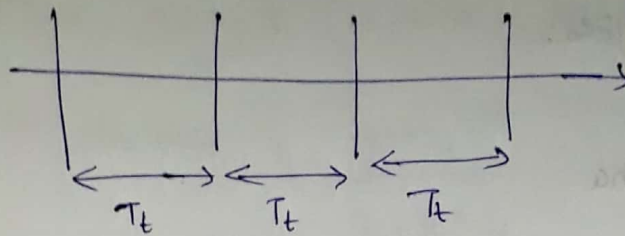
$$\Rightarrow \eta_{\max} = \frac{1}{2e} \approx 0.184$$

∴ Max efficiency of pure aloha = 18.4 %

Slotted ALOHA:

→ Here also the same 3 rule apply.

→ But here the timeline is divided in time slots where each slot is T_t .



Here every station is allowed to transmit only at the beginning of a time slot.

$$\therefore \text{vulnerable time} = T_t$$

$$\text{efficiency, } \eta = G * e^{-G}$$

$$\frac{d\eta}{dG} = 0 \Rightarrow G = 1$$

$$\eta_{\max} = e^{-1} = \frac{0.368}{1} = 0.368$$

$\therefore$ Max efficiency in slotted ALOHA = 36.8%

5/12/20

Error Control Methods:

Error Detection

- Detects & req for retransmission

Eg: (DTP), parity check

CRC, checksum

send data twice 2 times.
and if they are same then no error

Error Correction

- Error is detected and corrected

Eg: Hamming Code

In Hamming code, if d data has to be sent then $d/2$ more data has to be sent. All it requires lot of computation. (not used practically)

Cyclic Redundancy Check (CRC):

→ Here both sender and receiver will have a common number called CRC generation.

→ ~~If~~ Initially, send pads $n-1$ bits to data (on right end) if CRC is n -bits.

→ Now perform XOR as shown below.

Let data on sender side be 1011011

Let CRC generator be 1101

CRC generator is 4 bits.

So pad 3 bits to data

1011011000

Now perform XOR as shown below

start XOR again from bit 1 from left side

1101	1011011000	
→ 1101	↓ ↓ ↓ ↓ ↓	
	0110011000	
	1101	
	000111000	
	1101	
	001100	
	1101	
	0001	

Here we stop the procedure
cuz we have only 1 bit

CRC

So append it
to data

i.e. Data to be transmitted = 1011011 001

data CRC

After obtaining data, receiver does the same procedure with received data. If data received is Crc, CRC will be 0.

$$\begin{array}{r}
 1101 \overline{) 1011011001} \\
 \underline{1101} \\
 0110011001 \\
 \underline{1101} \\
 000111001 \\
 \underline{1101} \\
 001101 \\
 \underline{1101} \\
 0000
 \end{array}$$

CRC=0

∴ Correct data is received.

Assume data has got corrupted and received as 1001011001
↓
Error

$$\begin{array}{r}
 1101 \overline{) 1001011001} \\
 \underline{1101} \\
 0100011001 \\
 \underline{1101} \\
 010111001 \\
 \underline{1101} \\
 01101001 \\
 \underline{1101} \\
 00000001
 \end{array}$$

remainder $\neq 0$

∴ There is an error. So req for retransmission.

→ Sometime CRC generator will be represented as a polynomial.

If degree of CRC generator polynomial = $n-1$, then CRC generator is of n bits and CRC is of $n-1$ bits.

Ex: CRC generator: $x^3 + x + 1 \approx 1011$

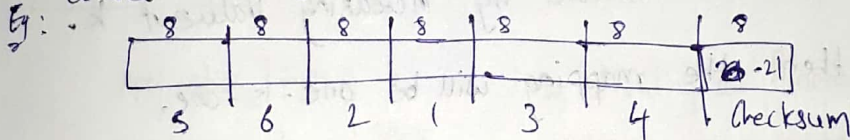
Checksum:

- If we need to compute n-bit checksum, then data is divided into parts each of size n-bits.
- Now convert each part into its decimal equivalent and add all these values.
- Now negate the result obtained and place it in the checksum field.

Note:

while performing above steps, if data part has checksum then we take its decimal equivalent as 0.

Eg: Consider below 8-bit checksum



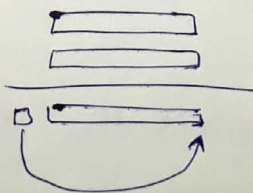
$$\text{checksum} = 5 + 6 + 2 + 1 + 3 + 4 = 21$$

$$\therefore \text{checksum} = -1$$

- Now if the data received by receiver is correct then checksum sum calculated by receiver is zero.

Note:

Also while adding two numbers, if there is an overflow, then wrap around carry and add it.

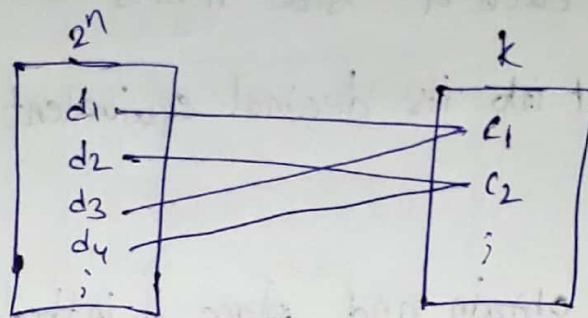


Meaningful Errors: Sometimes errors are possible in such a way that corrupted data appears as a valid data. i.e., both data & detection bits are corrupted in such a way that they form a valid combination.

Note:

Let data be of size of n bits and CRC/checksum is k bits.

$$k \ll n$$



d_1 & d_3 produces same CRC/checksum.

So if d_1 is corrupted to d_3 , then this error won't be detected.

→ This problem can be minimized by increasing value of k .

If $k = n$ then the mapping will be one-to-one.

~~still errors are~~

Even if mapping is 1-1, meaningful errors are possible.

ISO/OSI Stack

Functions provided by Computer networks

Mandatory

1. Error Control
2. Flow Control
3. Access Control
4. Multiplexing & Demultiplexing
5. Addressing etc.

Optional

1. Encryption
2. Checkpointing (while transferring large files checkpoints are used)
3. Routing

These functions are implemented by ISO-OSI, TCP/IP, ATM, ... etc.

ISO-OSI Layers

- Application layer }
 Presentation layer } User Interactivity } achieve Encapsulation & abstraction
 Session layer }
 Transport layer - More functionalities are present here (thick) } (ii) Dividing layers makes testing easy because we can test only a specified layer
 Network layer - Complex functionalities are provided by Network layer (Routing)
 Data link layer - Contains H/W & S/W
 Physical layer - Contains H/W

→ A host need not to contain network layer. Network layer is generally implemented on routers.

But transport layer is present on every host

Physical Layer:

Physical layer deals with electrical, mechanical, functional and procedural characteristics of physical links.

→ Depending on propagation medium signals has to be converted appropriately
 i.e., Copper - Electrical signals; optical - light; wireless - electromagnetic waves

→ Functional properties means types of transmission modes.

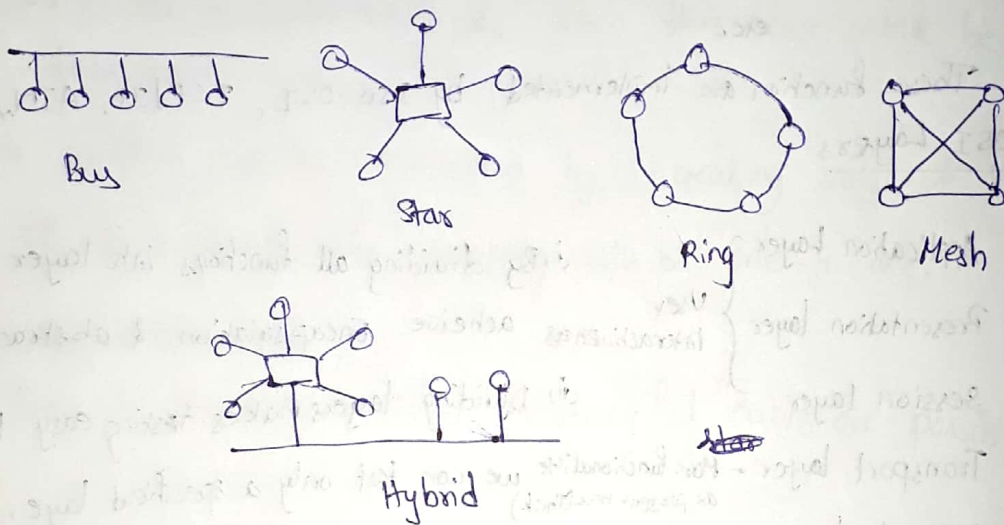
Simplex: Communication is one way

half duplex: Communication is possible in both way, but only one a time.

full duplex: Communication is possible in both ways at same time.

(In gate for all questions we consider full duplex by default)

→ Physical layer also deals with topologies



→ Physical layer also does the job of encoding:

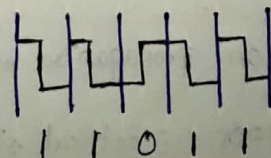
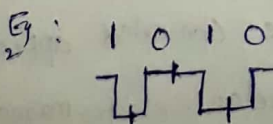
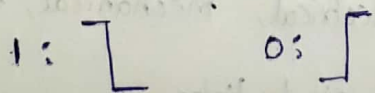
~~The~~ i.e., converting bits into electrical signals

we have 2 types of encodings:

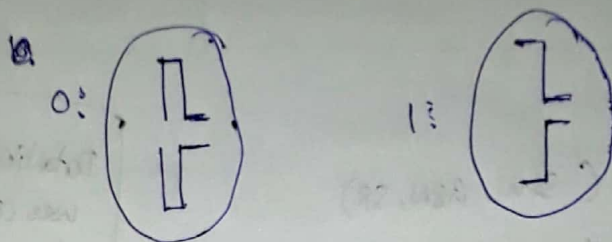
i) Manchester encoding

ii) Differential Manchester encoding.

i) Manchester Encoding:

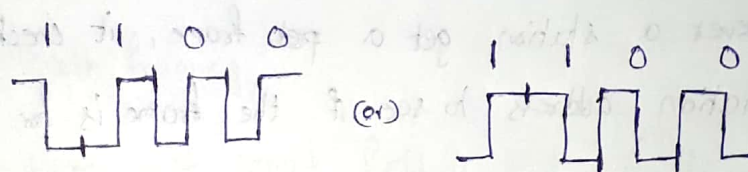
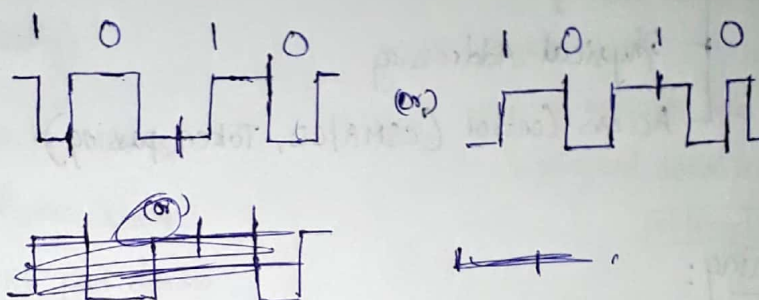


(ii) Differential Manchester Encoding



Here ~~two~~ we have 2 representations for 0 & 1

eg:



Based on the representation we use for the 1st bit we get 2 different encodings.

$$\text{Baud rate} = 2 \times \text{Bit rate}$$

Baud rate is no. of voltages sent per second.

For each bit 2 voltages are sent.

→ PL also provides bit synchronization, bit rate control.

Data Link Layer:

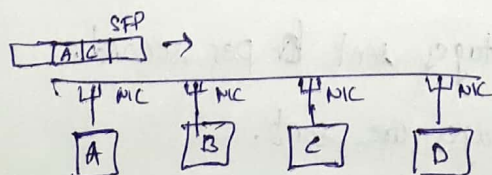
Functionalities

- Flow Control (S/W, GBN, SR)
- Error Control (CRC, Checksum)
Used in TCP/IP
- Framing
- Physical Addressing
- Access Control (CSMA/CD, Token passing)

Data link layer
uses CRC as it
is more efficient
to implement at
H/w level

Framing:

- Generally in LANs stations are connected with bus topology.
- Whenever a station gets a frame, it checks ~~for~~ the destination address to see if the frame is for ~~this~~ it or not.
- So for this, rather than all the stations monitoring the channel, we used SFD (Starting Frame Delimiter) at the beginning of ~~for~~ every frame and it will be detected by NIC and NIC will alert to station to check the destination address of the frame



SFD is generally of
for $(10)^*11$

There will be no problem if data
match with SFD because one SFD
is found
frame is
read till
end

- Also there may be multiple frames on a channel at a time.
So a station should read only the frame meant for it.

For this purpose we should be able to detect the ending of frame.
This detection is based on the framing technique we use.

Framing is of 2 types:

Fixed length Framing

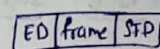
Variable length Framing

→ Here, knowing the starting of frame is enough. (Ending is known implicitly)

→ Disadv: If data to sent is less than the frame size then we need to pad dummy bits.

→ Here starting is identified using SFD. Also we need to know the ending. This can be done in 2 ways:

- using length field
- using end delimiter (ED)



→ This is the mostly used framing

→ In variable length framing,

- the problem with length field is that, if the length field gets corrupted, then the end will be identified incorrectly.

However in LANs error probability is less and hence we can use it.

- the problem with End delimiter is that, there is a chance that data pattern may match ED. This problem is dealt in two ways:

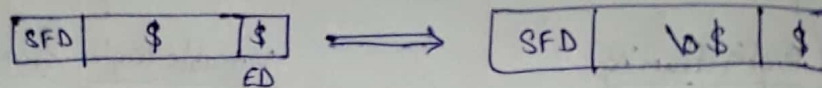
(i) Character stuffing / Byte stuffing

(ii) Bit stuffing

Character Stuffing:

→ For every pattern in data, that matches with ED with add a null character as a prefix to it.

~~Ex: if~~ For example if ED is \$ and data has \$, then sender will add NULL and receiver will remove the null.



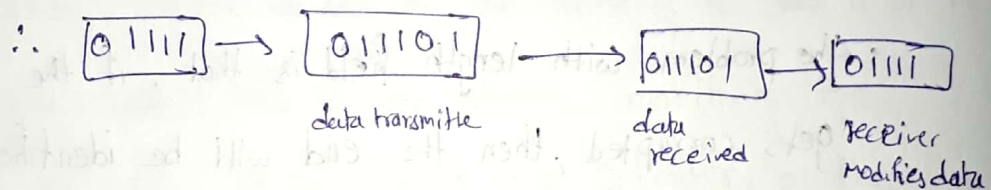
→ If data has \$ \ 0\$ then sender will change it to \ 0\ 0\$
i.e., for every null add a null and for every \$ add a null

Disadv: Adding character requires more space.

(ii) Bit Stuffing:

Let ED be 01111

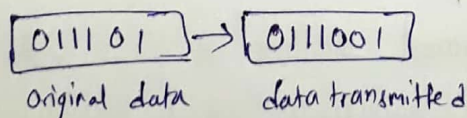
If ~~00~~ 0111 is found in data then sender will add 0 in this position.



But consider the case where data transmitted itself is 011101. In this case also receiver removes the 0.

So to deal all possible cases, we come up with a strategy where we ~~add~~ add a zero after 0111 ~~is found~~ and receiver removes zero after 0111 is found.

So here sender adds 0 even in the cases where there is no ED pattern in data.



→ Similarly if ED is 011111, then we add 0 after every 01111

87
Eg: If ED = 01111 and data is 011100011110

Find data that should be transmitted.

01110 000111010

↑
Here bit is

shuffled even

without match

Eg: If ED is 10000, then we add 1 after every 1000

Physical Addressing:

logical address: It ~~is address unique~~ It is an address which is unique across the world

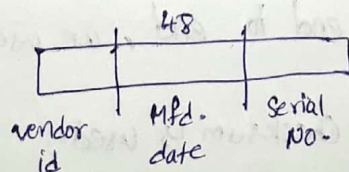
Physical address: It is an address which is unique within a network.
i.e., two system in two different Net ~~can~~ may have same physical address.

→ IP address is a logical address. It is a 32 bit number.

→ MAC address is a physical address. It is a 48 bit number.

↳ ENCODED in ROM of NIC.

MAC address is 48-bit address



Even though MAC is unique, IP add. is used in communication. Because IP add. has fields (PID, SID, HAD) that help in routing.

→ Physical address is constant and doesn't change.

Generally MAC is used as physical address even though it is a logical address.

→ DLL is further divided into 2 sublayers

i) Logical Link ~~Layer~~ Control (Flow control)

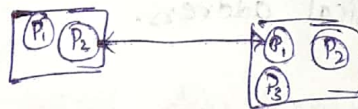
ii) Medium Access Control (Framing, access control, physical addressing)

} Error Control

Transport Layer:

Functions:

- End to End Connection: It is used to establish end to end connection, i.e., process to process



It uses port numbers for this. This is known as Service Point Addressing

- Flow Control: Since it is end to end, we use SR protocol.

- Error Control: ~~It is~~ Mainly Checksum is used.

- Segmentation & Reassembly: Data received from upper layers may of different sizes. This is ~~changed~~ segmented into different sizes.

- Multiplexing & ~~Demuxing~~ Demultiplexing

Transport layer on sender side has to take

message from many processes and send it through a single channel.

Also TL on the other side take data from one channel and give it to different processes.

— Congestion Control

Network Layer:

Functions:

— Host to Host Connectivity: It transmits data from host to host (but not from process to process)



— Logical Addressing: Identifying hosts

— Switching: Switching is process of connecting various networks.

— Routing: Routing is building ~~routing~~ routing tables.

Later using this routing table is called switching

— Congestion Control:

— Fragmentation: Different networks may support different maximum allowable data size.

So in this case fragmentation is used.

Session Layer:

Functions:

— Authentication & Authorization

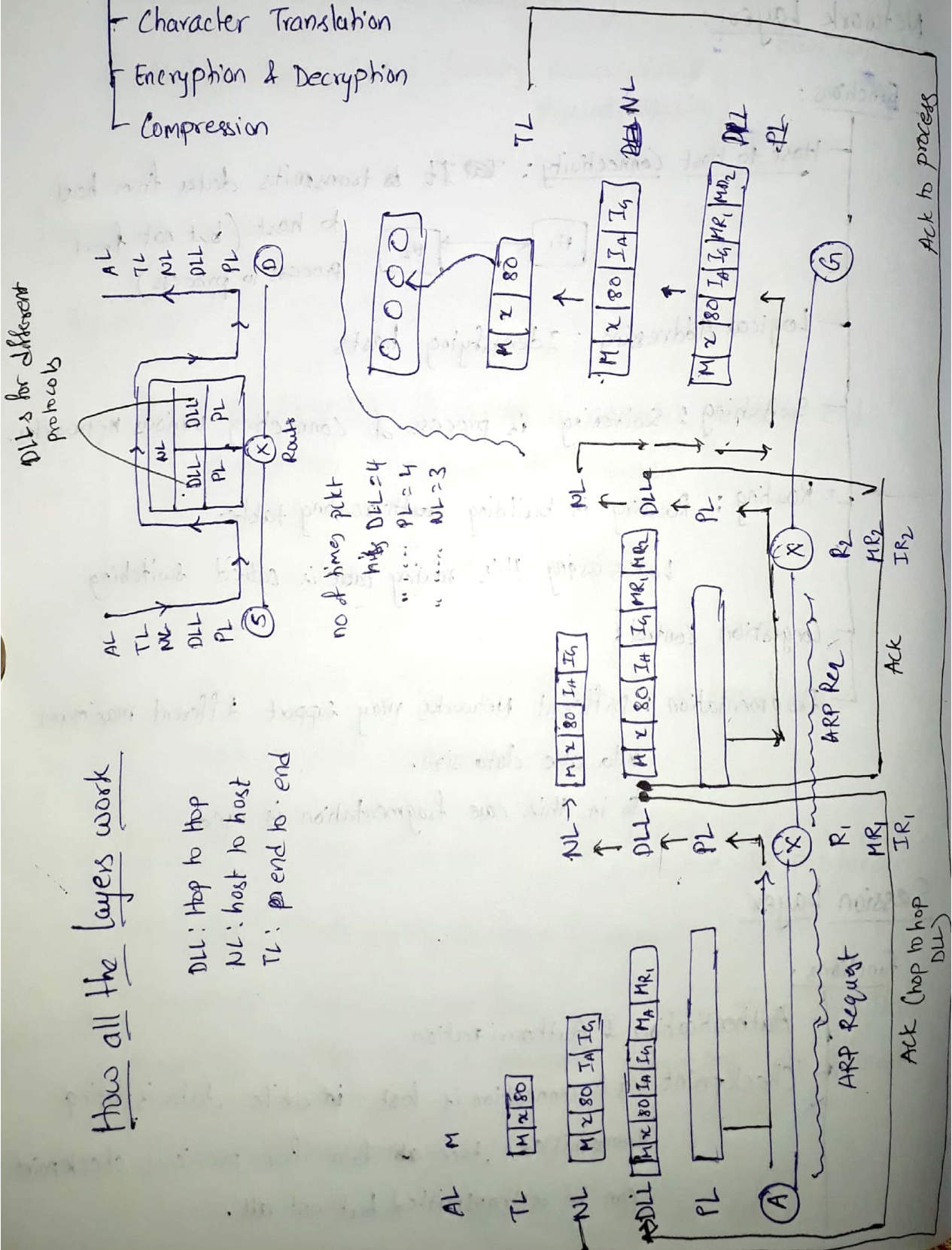
— Checkpoint: If connection is lost while data is being transmitted, then data from previous checkpoint can be retransmitted but not all.

- Synchronization : Eg: matching video & audio
- Dialog Control :
- Logical grouping
- Connection establishment, maintenance, termination (session)

Presentation Layer:

Functions:

- Character Translation
- Encryption & Decryption
- Compression



on sender side:

In TL, port num of source & Destination are added
↳ well known port.

In NL, source IP & Destination IP are added
↳ found using DNS

In DLL, source MAC & Destination MAC are added
↓
↳ found using ARP
MAC of the default gateway.

Now this moved to PL and from there it will be sent to default gateway router

At Router R₁:

- Routers have only 3 layers PL, DLL, NL
- Based on the type of NLs router is connected it may have several DLLs and several PLs but only one NL
- ~~In~~ Before router forwards to next router, it changes source MAC & destination MAC.
- But source IP and destination IP are kept same.
- Also DLL of R₁ sends ack to DLL of host

At G:

- NL uses UDP protocol. So no ack will be sent.
- TL sends ack to the sender.
- Using port number the pkt is sent to appropriate process.

07/12/20

LAN Technologies

Ethernet (IEEE 802.3)

It is one of the LAN technologies.

→ Topology: Bus

→ Access Control: CSMA/CD

→ No acks are used

However if an application needs ack then it may send ack as if it is data.

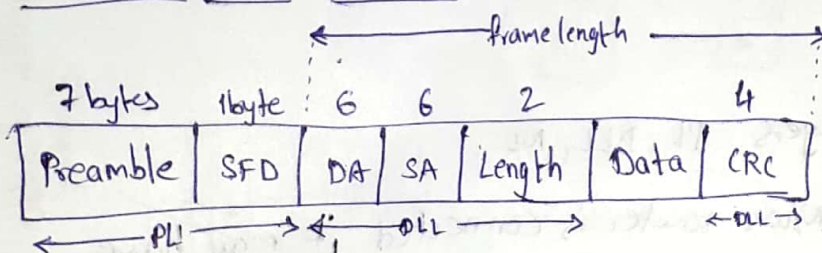
→ Data rate/Bandwidth: 10Mbps, 100Mbps, 1Gbps

↓
Fast ethernet

↓
Gigabit ethernet

→ Encoding technique: Manchester

Ethernet Frame Format:



Preamble: 10101010...1010

SFD: 10101011

• Preamble & SFD are not added to the frame.

PL just sends preamble & SFD just ~~before~~ before sending it.

• Preamble & SFD ~~alerts~~ alerts other stations indicating start of the frame.

• Preamble & SFD also provides synchronization.

• DA & SA are MAC address of destination & source.

∴ It is 6 bytes

Data at diff layers:

AL - Message

TL - segment

NL - Datagram

DLL - Frame

PL - Single Protocol

- Data Unit (IPDU)

Types of MAC addresses:

i) Unicast: ~~Least~~ Least significant bit of 1st byte is 0.

SA is always a unicast address. Otherwise the frame is invalid.

ii) Multicast address: Least significant bit of 1st byte is 1.

For multicasting, we go assign MCA (Multicast Address) to a set of stations of the group.

Now all stations after reading DA, if the DA matches with their unicast address ^{or} multicast address, then they will read the data.

iii) Broadcast address: All the bits are 1's.

When a station sees all bits as 1's, then it will accept it.

→ Length field is used to tell the length of the frame. ~~It~~ It is 2 bytes.

Ethernet uses variable frame length. So we used length field.

Even though frame length is variable, since ethernet uses CSMA/CD, the frame must be of some minimum size.

$$L \geq 2T_p$$

$$L \geq 2T_p * BW$$

$$L \geq 64 \text{ bytes (from standard value of ethernet)}$$

↳ from DA to CRC

Also maximum data (not frame) that can be sent is 1500.

This restriction is made so that one user won't be sending large frames and use the line.

i.e., to avoid monopolization.

	Min	Max
Data	46B	1500B
Frame	64B	1518B

→ CRC is 4 bytes i.e. 32 bits

∴ we use ~~2048~~ CRC polynomial of degree 32

Disadvantages:

- It is not applicable for real time application.
i.e. in applications where sending data within time is important.
- The minimum size of data to be sent is 46B.
so it is not applicable for interactive applications.
- No priorities are present among stations.
so it is not good for client-server application where server has to be given more priority.

Token Ring (IEEE 802.5)

- It is another LAN technology that overcomes the drawbacks of Ethernet. But it has its own disadvantages.
- Topology: Ring
- Access Control: Token passing
- Data sent: ~~is~~ unidirectional (clockwise or anticlockwise)
∴ links used are simplex
- Data rate: 4Mbps, 6Mbps
- Piggy backing acknowledgments are used.
- Encoding: Differential Manchester encoding.

Sender-side Problems:

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In token ring, once data is placed on the link, it is removed by the sender only. Due to this there are 2 problems possible.

i) Orphan packet Problem:

If a packet is placed on link and if the sender down by the time the packet comes back, the packet will never be removed from the link.

ii) Stray packet Problem:

By the ~~sent~~ time sent packet comes back to the sender, if the packet is corrupted enough that sender cannot recognize it, then the packet will remain on the link.

To solve the above two problems we introduce new station called monitor in the ring. Monitor is ~~also~~ one of stations in the ring.

~~If sender doesn't remove~~

~~itself~~

i) A monitor bit is maintained, which is initially 0.

When this packet passes through the monitor, it sets the bit to 1. When packet comes to the monitor for second time, the packet will be removed.

ii) CRC is present in every packet. Whenever the packet is corrupted, monitor can detect it. ~~CRC will be changed~~. Monitor removes the packet if it detects this change.

Problems on Destination:

i) Destination is down:

In this case sender should not resend.

ii) Destination is busy:

In this case destination buffers may be full or destination may be ~~by~~ busy. So ~~send~~ sender has to resend the exam.

iii) Packet corrupted:

In this case pkt is corrupted & sender has to resend.

iv) Copied: Here destination receives pkt and hence there is no problem

To overcome these problems we use 3 special bits ~~A, C, E~~ in header

A - Available (availability of destination)

C - Copied

E - Error

A C

0 0

— Initial

1 1

— Destination available & pkt is copied

1 0

— E=0, Destination busy

E=1, pkt is erroneous

0 0

— Destination is down

0 1

— Invalid

→ This A & C are kind of acknowledgments.

So we say it is piggy backing acknowledgments

→ Also while retransmitting, sender has to reset monitor bit otherwise monitor will remove the pkt.

→ A & C are used ~~used~~ only for unicasting.

Token Problem

is A station send large amount of data without releasing the token. This will lead to a problem of monopolization.

This is known as Captured token.

So to overcome this, we impose restriction on maximum THT.

Default value of max THT = 10 ms

Bandwidth = 4 Mbps

→ Maximum frame size that can be sent with ETR

$$= \text{THT} \times \text{BW}$$

$$= 10 \times 10^{-3} \times 4 \times 10^6$$

$$= 40000 \text{ bits}$$

→ Maximum frame size that can be sent with DTR

let THT = 10 ms BW = 4 mbps

RL = 9 ms

within THT (10 ms) transmitting and getting the packet back should happen.

$$\therefore \text{THT} = T_t + \text{RL}$$

$$\Rightarrow T_t = 10 - 9 = 1 \text{ ms}$$

$$\therefore \text{Max data sent} = 10^{-3} \times 4 \times 10^6 = 4000 \text{ bits}$$

while solving problems take ring latency ~~as~~ pro. as

$$RL = T_p + \frac{N \times b}{B}$$

If bit delay is not given then take $RL = T_p$

~~$\therefore$ In ETR, transmission can be do~~

$\therefore$ In ETR, $T_t = \text{THT}$

In DTR, $T_t = \text{THT} - \text{RL}$

(ii) Token is Lost :

Assume a case where a station takes a token and the station ~~is~~ went down.

In this case monitor will ~~also~~ generate a new token.

For that monitor has to be sure that token is ^{lost} ~~not lost~~ but not delayed;

In best case

minimum token return time = RL

In worst case

maximum token return time = $RL + N \times THT$
(TRT)

$\therefore$ If token doesn't return to the monitor within $RL + N \times THT$, monitor will generate new token.

Eg : $RL = 10 \text{ ms}$; $THT = 10 \text{ ms}$; $N = 10$;

Max TRT = $10 + 10 \times 10$

= 110 ms

(iii) Token is Corrupted :

In general, token size is 3 bytes. So since it is small we don't use any CRC for it.

So if a corrupted token comes to monitor, monitor assumes it ^{is} some ~~data~~ ^{pckt} which ~~split~~ has split from ~~to~~ some data and monitor discard.

In this case ~~also~~ also monitor generates token after maximum token return time.

Monitor Problems

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i) If monitor goes down, there will be lot of problems with stray pkts, orphan pkts etc.

Due to this communication will halt at some point.

To overcome this problem, monitor sends heartbeat message periodically saying that it is present.

This heartbeat messages are implemented using

AMP frames

↳ Active Monitor Presence

Every station expects AMP frames in regular interval of time.

~~If monitor~~

If monitor goes down now, using polling, one of the existing hosts will be selected as monitor.

(ii) Monitor is hacked (Monitor Malfunction) :

In this case monitor is present ~~but~~ but as it hacked it sends AMP frames without doing any work.

The only ~~problem~~ solution for this problem is human verification.

If communication is found to ~~be~~ halt then we will check if monitor is malfunctioning.

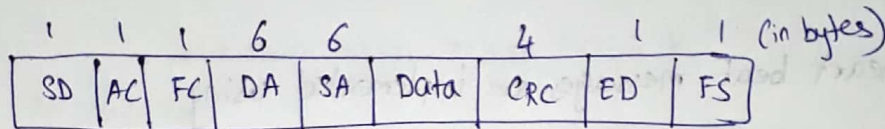
Advantages of Token ring:

→ It is applicable for real time applications since there are no collisions

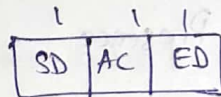
- It is also suitable for interactive applications as there is no limitation on minimum size of data that can be sent
- It is also applicable for client-server applications by giving priorities to stations.

Token Ring Frame Format:

Data Frame:



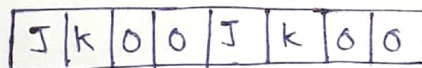
Token Frame:



SD: Used for alerting that frame is being transferred

and also performs synchronization

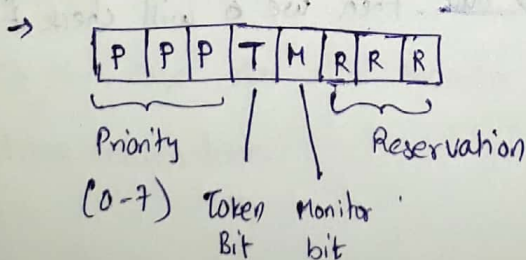
(Start Delimiter)



Manchester Encoding.

Access Control:

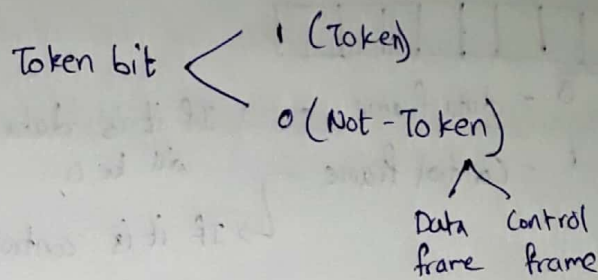
→ This field is of 1 byte size



* 0-7, eight levels of priorities are possible.

J & k doesn't represent any data. They are just invalid patterns. So using it in SD, we can make sure that SD never occurs in data.

→ Token bit is used to say whether the frame is token frame or data frame



Priorities & Reservations:

Using these we implement priorities.

→ Every host is assigned a priority.

→ If a host has to transmit it will put its priority in reservation field, saying that it needs that token.

A host can update reservation field only if its priority is more than the content in reservation field.

→ Assume DTR is being used.

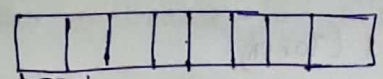
Sender sends data packet and waits until it comes back. As data packet passes through all the hosts each host if needed will modify the reservation field.

When sender gets back the data field, it copies the reservation field of AC to reservation field of token.

Now this token can be held by a host only if its priority is greater than or equal to the content in the reservation field.

→ In Client Server applications, server will be given priority 7 and all other host will be given a priority of 0.

Frame Control:



0 0 - data frame → If it is data frame then all the 8 bits will be 0
 1 1 - Control frame → If it is control frame then the remaining 6 bit will say which type of control frame it is.

Examples of control frames:

- AMP
- Polling - used at the time of polling
- purge - used when some maintenance is going on so that no one will send data
- beacon - ~~It~~ It is used find if there is any cut in the frame.

DA & SA:

byte
 6 MAC addresses

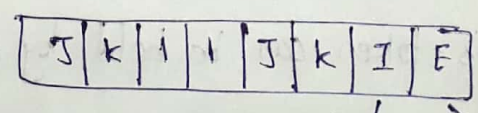
CRC:

4 bytes

∴ CRC polynomial of degree 32

End Delimiter:

Used to detect end of the frame.



→ Information bit > 1 → there is some of data following.

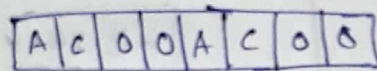
As there is restriction on max THT, a station may ^{not} be able

to send all the data in one THT

So it uses information bit to tell the destination that some more data will be sent.

→ If destination detects any error then destination will set F.

Frame Status:



→ why 2 copies of AC?

* CRC is computed only on field that are left to ^{CRC field} but not on FS & ED.

It is because AC bit will be changed on receiver side.

So to have more reliability we maintain 2 copies of AC.

→ Max size of data depends on max THT.

→ If ETR is used then priorities ^{are} implemented differently as

token has to be relayed as soon as sender sends the data.

So here based on the latest packet (packet in last cycle) seen

by the sender, sender gets the reservation details and puts it

on the AC field of the token.

Minimum length of token Ring:

Assume a case where all the hosts are down.

In this case, as ~~soon~~ monitor places token and receives it quickly. So there is a chance that monitor gets 1st bit of token back before it finishes the transmission.

In this case collision is possible.

To overcome this we impose restriction on min length of ring. The min frame sent is token. Its size is 24 bits

Propagation delay $\geq$ transmission time of 24 bits

Capacity ≥ 24

$T_p * BW \geq 24$ ($\because$ simplex)

$$\Rightarrow \frac{d}{v} \geq \frac{24}{B}$$

$$\frac{d}{v} \times BW \geq 24$$

$$\Rightarrow \boxed{d \geq \frac{24 \times v}{B}}$$

$$\boxed{d \geq \frac{24 \times v}{BW}}$$

Eg: $BW = 4 \text{ Mbps}$; $v = 2 \times 10^8 \text{ m/sec}$

$$\Rightarrow \text{Min length of ring} \geq \frac{24 \times 2 \times 10^8}{4 \times 10^6} = 1200 \text{ m} = 1.2 \text{ km}$$

But having this large link may not be possible.

~~In that~~ Assume we have 1 km link. In this case we add a delay device.

The delay to produce by this device should be equal to delay produce by a 200m link.

$$\therefore \text{delay req} = 200 \text{ m}$$

$$= 200 / v \text{ sec}$$

$$= 200 \times 2 \times 10^8 \text{ sec}$$

$$= 10^{-10}$$

$$= \frac{200}{2 \times 10^8} \text{ sec}$$

$$= \frac{200}{2 \times 10^8} \times BW \text{ bits} = \frac{200 \times 4 \times 10^6}{2 \times 10^8}$$

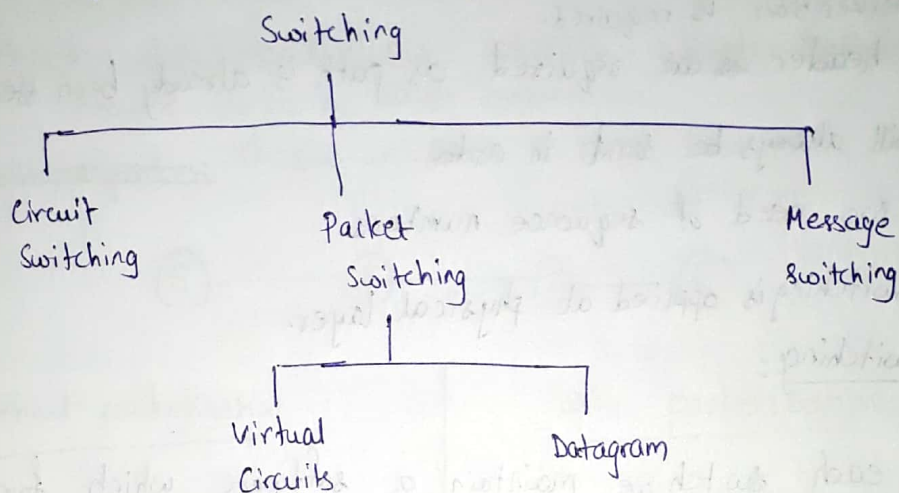
$$= 4 \text{ bit times}$$

Now assume that every station adds 1 bit delay, then
 min no of stations to be present in the ring = 4

08/12/20

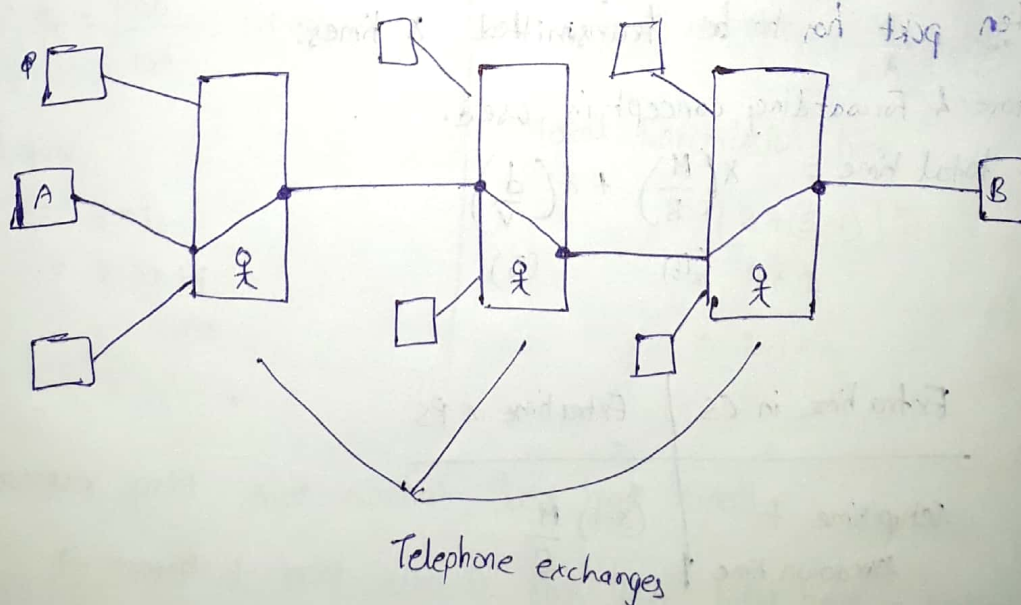
Switching:

Switching is process of connecting different networks.



Circuit Switching:

By ~~Physical~~ Connection and disconnection is made physically.



$$\therefore \text{Total time req} = \text{setup time} + \frac{M}{B} + x \left(\frac{d}{v} \right) + \text{teardown time.}$$

$(T_s) \quad (T_p)$

$M \rightarrow$ size of message

$B \rightarrow$ Bandwidth

$x \rightarrow$ no of hops

$d \rightarrow$ distance b/w two hops

$v \rightarrow$ velocity of signal.

setup time $\rightarrow$ time to setup connection

teardown time $\rightarrow$ time to remove connection

$\rightarrow$ Human intervention is required.

$\rightarrow$ Here no header are required as path is already been setup.

$\rightarrow$ Data will always be sent in order.

$\therefore$ No need of sequence numbers.

$\rightarrow$ Circuit switching is applied at physical layer.

Packet Switching:

$\rightarrow$ Here at each switch we maintain a software which forwards packet to appropriate switch.

$\rightarrow$ Here pkt has to be transmitted at each switch.

$\rightarrow$ If there are x no of hops b/w source & Destination then pkt has to be transmitted x times.

$\rightarrow$ Store & Forwarding concept is used.

$$\therefore \text{total time} = x \left(\frac{M}{B} \right) + x \left(\frac{d}{v} \right)$$

(T_E) (T_P)

Extra time in CS	Extra time in PS
setup time + teardown time	$(x-1) \frac{M}{B}$

Thus for large data CS is ~~better~~ better
for small data PS is better

Packetization in packet switching (pipelining):

→ Here data to be transmitted is divided into packets so that pipelining can be obtained.

By this two switches will be transmitting parallelly.

Ex: Consider data = 1000 B ; BW = 10^6 MBPS ; Header = 100 Bytes.

Assume $T_p = 0$ for easier comparison

~~without packetization~~ Consider we have 3 hops b/w sender & receiver



without packetization

$$T_t = \frac{1000}{10^6}$$

Data to be transmitted

$$= 1000 + 100 = 1100 \text{ B}$$

$$\therefore T_t = \frac{1100}{10^6} = 1.1 \text{ ms}$$

Total time

$$= 3 \times T_t$$

$$= 3 \times 1.1$$

$$= 3.3 \text{ ms}$$

with packetization

Consider we ~~transmit~~ divide data into 5 pkts.

$$\Rightarrow \text{Size of each pkt} = \frac{1000}{5} = 200$$

$$\text{Size with header} = 200 + 100 = 300$$

$$\therefore T_t \text{ of a pkt} = \frac{300}{10^6} = 0.3 \text{ ms}$$

Total transmission time

$$= [3 + (5-1)] T_t$$

$$= 7 \times T_t$$

$$= 2.1 \text{ ms}$$

→ However pkt size cannot be too small.

For example if pkt size is 50 B then total time = 3.3 ms and this equal to original value.

→ So we need to use optimal pkt size (can be found by differentiating)

There are 2 types of packet switching

(i) Virtual circuits (Eg: ATM)

(ii) Datagram (Eg: IP)

In both the types data is divided into packets.

Virtual Circuit

- (i) Here all the packets follow same path
- (ii) As the 1st packet is transmitted all the remaining packets follow the path taken by 1st packet. So as the 1st packet moves along the path it makes reservations at each switch for CPU, BW & buffers.
- (iii) Connection oriented
- (iv) 1st packet has global header and remaining packets have local header. Global header helps in finding path from source to destination whereas local header just helps the packet follow the 1st packet
- (v) Same path is followed and hence packets arrive in order

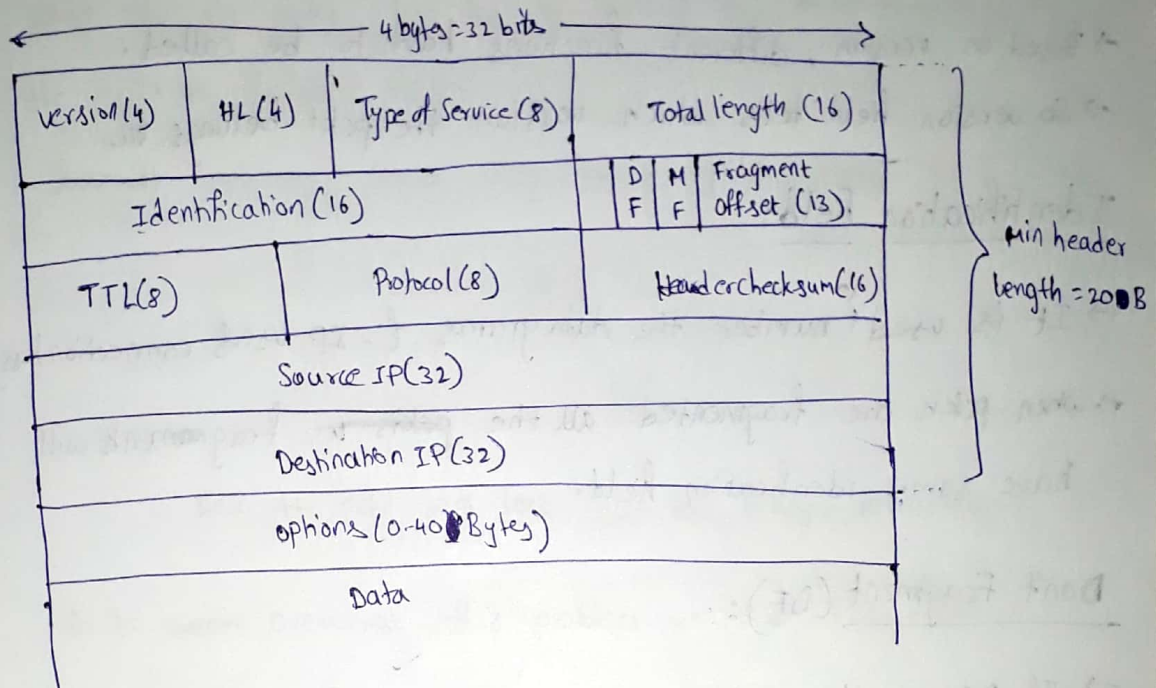
(vi) Reliable
(vii) Costly

Datagram

- (i) Here each packet follows different path and is transferred independently.
- (ii) Here no reservations are made and path taken by each packet may be different.
- (iii) Connectionless
- (iv) All the packets must have header
- (v) Different paths are followed and hence packets may arrive out of order.
- (vi) Not reliable
- (vii) Not costly

Internet Protocol:

IP4 Header:



Min header = 20 Bytes; Max header = 20 + 40 = 60 Bytes

Header length (HL):

Max value possible in HL is $2^4 - 1 = 15$

But max header length is 60

So to obtain header length, we multiply header length field with 4

$$\text{Header length} = 4 * \text{Header length field}$$

Range of header length: 20 - 60

Range of header length field: 4 - 15

In exam,
Based on value given,
we understand which is
given

Note:

If header length is 30 then Header length field = $\frac{30}{4} = 7.5$

So in this case we put 8 in HL field and pad 2 bytes to the header.

→ In worst case we may need to pad 3 bytes.

Version:

- IP has various versions (IPv4 to IPv6)
- Based on version, different functions have to be called.
- So version field tells which version the pkt belongs to.

Identification Field:

- It is used ^{to} number the datagrams ($\because$ IP uses connectionless)
- when pkts are fragmented all the ~~pkts~~ fragments will have same identification field.

Don't Fragment (DF):

- If $DF = 1$, then routers are not allowed to fragment the pkt.
- In this case if router cannot forward it, the router will discard the pkt and will send an ^{icmp} error message to sender.

More Fragment (MF)

- If $MF = 1$, it means that more fragments are following.

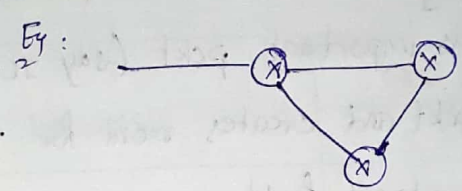
Fragment offset:

- when packet is fragmented, ~~each~~ ^{data bytes} the fragment offset say no of ~~fragments~~ which are ahead of this fragment.

Time to live (TTL):

→ when a pkt is being routed, if a router don't ~~know~~ know which n/w the pkt has to be forwarded to, it forwards the pkt to default router.

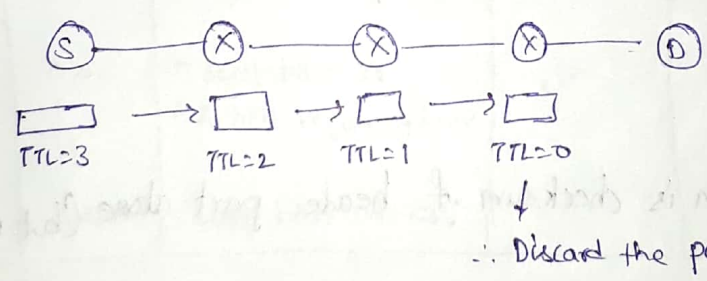
~~Some~~ Sometime there may be a cycle



Here the pkt will loop b/w the 3 hops infinitely.

So to ~~over~~ overcome this problem we use TTL field.

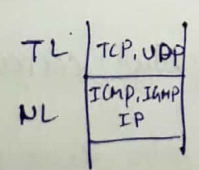
→ The value in TTL say max no of hops the pkt can take.
After every hop the value in TTL is decremented.



→ Destination also decrements TTL

→ The main purpose of TTL is to ~~not~~ discard pkts that go into infinite loop.

Protocol:



The datagram may follow ICMP (or) IGMP (or) TCP (or) UDP.

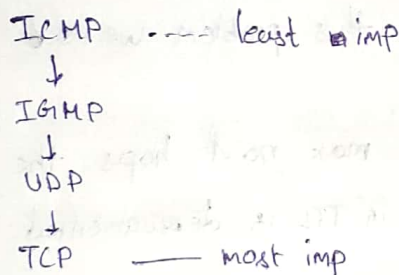
To indicate which protocol is being followed we used the protocol field.

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Actually identifying the protocol that's being followed is possible by looking into pkt.

But routers can't do that because we don't have transport layer in routers.

→ Also when router buffer is full it discards new incoming packets. However if ~~an~~ incoming packet is more important (say TCP) and router's buffer has less important packet (say ICMP) then router will discard ICMP packet and creates room for TCP packet. So to do this we need protocol field.

→ The order in which packets are discarded is



Header Checksum:

→ Header checksum is checksum of header part alone. (but not of data)

→ Finding checksum:

i) Divide header part into smaller parts each of size 2 bytes.

ii) Treat each part as a number and add them.

iii) Now negate the result and store it in the checksum field.

while computing the header checksum, we take value corresponding to header checksum is 0.

→ At every router checksum has to be recomputed as value of TTL, ~~is changed~~ (fragment offset, MF, total length), (options, header length) may change.

Hence checksum is computed only header. If it were to be computed ~~by~~ on data, every router has to do lot of computation.

→ However the protocol of the packet will compute the checksum on the data part (on sender side)

Source IP & Destination IP

IP add		Description	used as	
NID	Host		Source IP	Dest IP
✓	✓	Valid IP add	✓	✓
✓	0's	Network id	X	X
✓	1's	Directed Broadcast	X	✓
1's	1's	Limited Broadcast	X	✓
1's	0's	Network Mask/Subnet mask	X	X
0's	✓	Host within same N/w	✓	✓
0's	0's	I don't have IP (A host requesting for IP)	✓	X
127	✓	Loop back address	X	✓

Options:

→ This field is optional and it provide some options

i) Record Route:

This is used to find the path followed by the packet.

→ Every router adds its IP address if a packet passes through it.

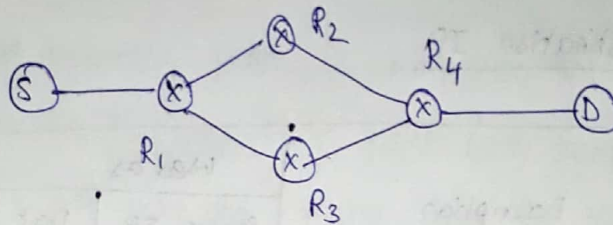
Size of IP add is 4B and option field is 40B.

so max no of router address possible is 10, but we also need to mention what kind of option we are storing.

So in practice max no of router addresses possible to be stored = 9.

(ii) Source Routing:

Using this option sender can select the path that has to be followed by the pkt. This is known as source routing.



Source routing is ~~2 types~~ said to be strict source routing if entire path to be followed is given. Otherwise it is called loose source routing.

strict source routing: Eg: R₄R₂R₁

loose source routing: Eg: R₁

→ This option is used by N/w administrator to test if the path is working or not.

→ Also both options record route source routing ~~are~~ ^{are} not allowed to be used by user. They are generally used by N/w administrator.

(iii) Padding:

^{size of}
If options added is not a multiple of 4, the extra bits are padded.

(iv) Time Stamp: Using this option, we record in-time and out-time of a pkt at each router in the path. Using this we can know the delay at each router.

Total length:

① This specifies length of ^{datagram} ~~packet~~ including header.

This is 16-bit field.

$$\therefore \text{Max possible length} = 2^{16} - 1 = 65,535 \text{ (Data + Header)}$$

Min header size = 20B

$$\therefore \text{Max possible size of data} = 65,515$$

$\therefore$ Maximum segment size at transport layer = 65,515

Also TL has 20B header.

So max payload at TL = 65,495.

But App. layer may provide data of any size to TL. So

TL does the job of segmentation

AL

TL

20 | 65,495

- Segmentation

↓

NL

20 | 65,515

- Fragmentation

DLL

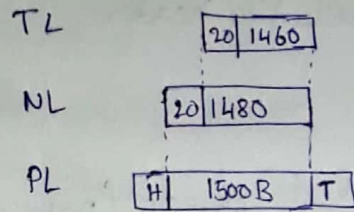
- Framing (adding header & trailer)

PL

→ However if the DLL is ethernet then max frame length is possible is 1500B. So for this reason NL does the job of Fragmentation.

→ In some cases DLL will be able to transmit frame of any size. If not, performing segmentation followed by fragmentation is waste of time. So it is better the TL finds least frame size / least datagram size and do segmentation accordingly

In this case segmentation done by TL is as shown below



Here only segmentation is done but not fragmentation

∴ Fragmentation is not done at sender side. Segmentation itself is done such that there will be no need of fragmentation.

→ The maximum allowed size of frame ^{in a N/w} is called ~~Maxi~~ Maximum Transmittable Unit (MTU).

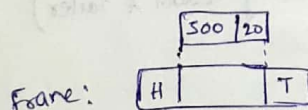
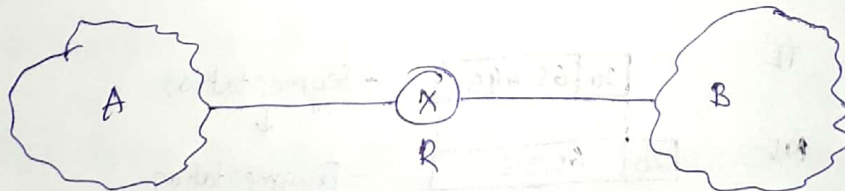
09/12/20

Fragmentation:

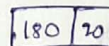
→ Fragmentation is done at routers but not sender.

MTU may be different from network to network.

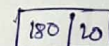
Consider 2 networks A & B with $MTU_A = 520$ & $MTU_B = 200$



MF=0



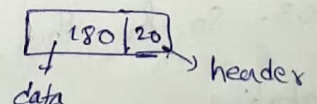
MF=1



MF=1

In N/w B MTU is 200

i.e., structure is



→ So the router R has to perform fragmentation before it sends it to B

→ After fragmentation, the fragments are routed independently since it is datagram service. So the fragment may be received out of order.

- Identification number of ~~all~~ ^{of a datagram are} the fragments is same.
- The fragment offset field is used to know the order of fragments.
- For the last fragment MF is set to 0. ~~which means that~~
For remaining ~~packets~~ ^{fragments} MF is set to 1.

Assigning fragment offset to fragments:

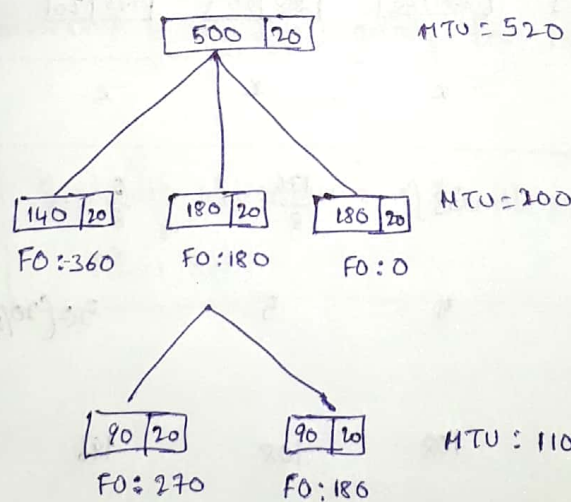
Assigning.

~~Assign~~ fragment offset sequentially from 0 won't ^{be} scalable.

For example, consider a case where pkt P is fragmented into 3 packets P_1, P_2, P_3 and ~~the~~ fragment offsets are 0, 1, 2 respectively. If we need to fragment P_2 again then we can't assign fragment offset to it. So we number fragments in a different way.

- Fragment offset is given such that, fragment offset is equal to number of data bytes ahead of the fragment.

Ex:



FO → Frag offset

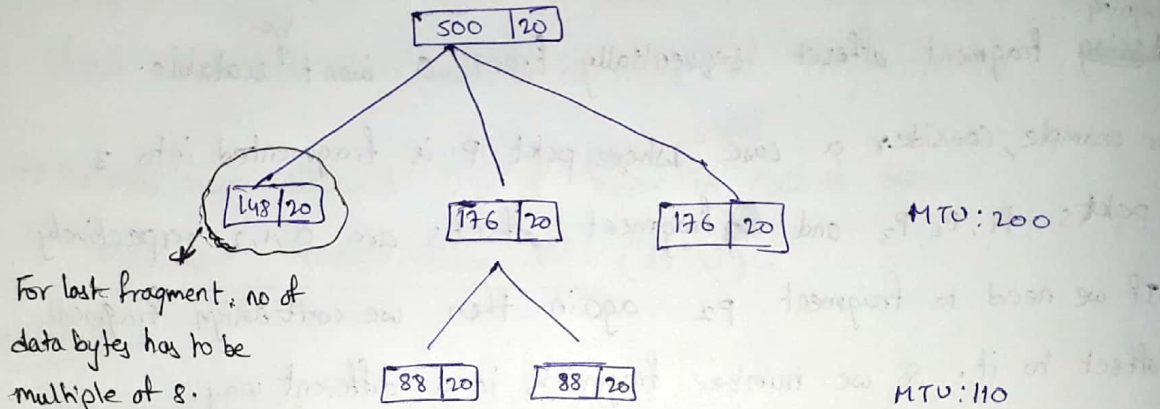
∴ Final fragment offsets are (0, 180, 270, 360)

- But here we have a problem.

Fragment offset field has 13 bits and total length of ~~the~~ ^{field} ~~packet~~ ^{possible} has 16 bits. In worst case if last fragment has 1 byte, then fragment offset has to be $2^{16} - 20 - 1 = 65,514$

To meet this problem, we ~~store~~ divide fragment offset with 8 ($\because \frac{2^{16}}{2^{13}} = 8$) and store it in the fragment offset field.

Now this brings a new restriction that ~~fragment~~ original fragment offset has to be a multiple of 8. It means data bytes in each pkt should be a multiple of 8. (except last fragment)
Now we perform fragmentation as shown below



Now the fragments are

Identification field	x	x	x	x
Fragment offset	44	33	$\frac{176}{8} = 22$	$\frac{0}{8} = 0$
Header length field	5	5	5	$5 \leftarrow (20/4)$
Total length	168	108	108	196
MF	0	1	1	1

→ Here we are totally transmitting 4 fragments.

So we transfer 4 headers.

~~actual~~ data to transfer = $500 + 20 = 520$

actual data that is transfer = $500 + 4 \times 20 = 580$

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∴ 60 bytes is overhead from network layer.

$$\text{Network layer overhead} = (\text{no of fragment} - 1) \times (\text{Header length})$$

$$\therefore \text{Efficiency} = \frac{\text{useful data sent}}{\text{total data sent}} = \frac{500}{580}$$

$$\Rightarrow \text{Bandwidth utilization} = \eta \times B$$

(Effec. Bandwidth)

Consider 3 networks



To find bandwidth utilization we take least bandwidth (bottleneck bandwidth) among the networks.

$$\text{Bandwidth utilization} = \eta * \text{bottleneck Bandwidth}$$

(Effec. Bw)

Note:

- Fragmentation is done only at routers, but not at source.
- Reassembling is done only at destination, but not at router.
- Reassembling is ~~done~~^{not} done at routers because all fragments may not meet at the same router. Also even if they meet, there may be a need for fragmentation again.

→ For fragmenting or refragmenting, the given fragment and its header information is sufficient. No other extra information is needed.

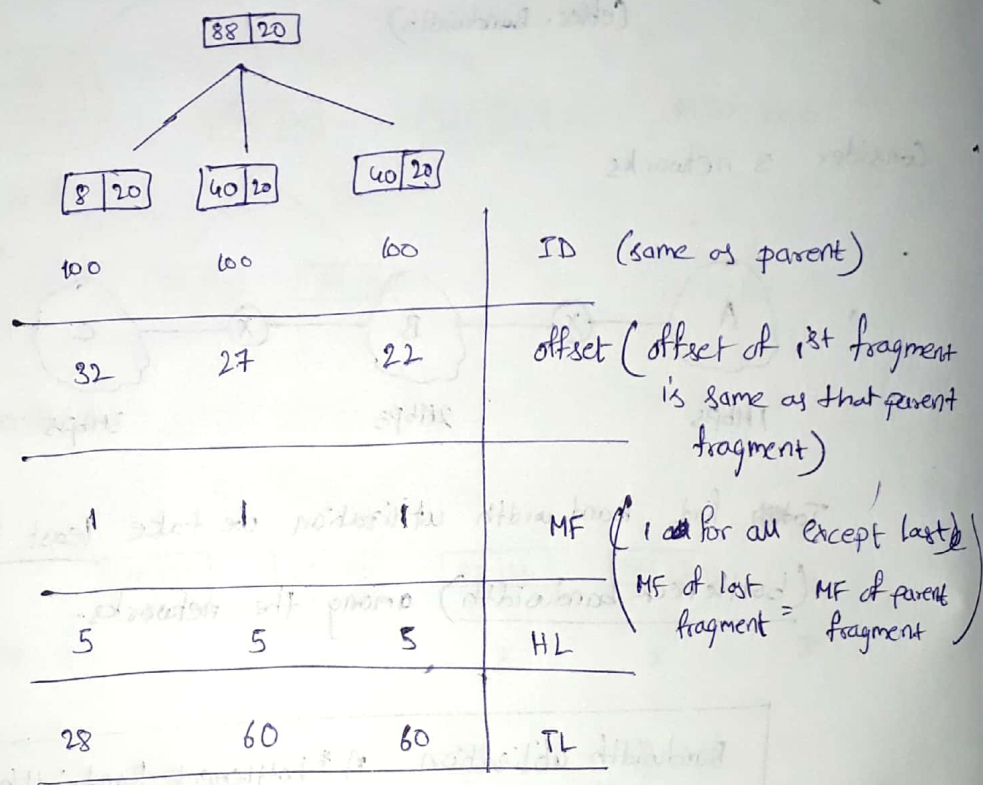
Consider fragment

88	20
----	----

 with

frag offset = 22; MF = 1; header length = 5; total length = 108; Id = 100;

Fragment the pkt if its passed through N/w with MTU = 60



Reassembling Algorithm:

<u>MF</u>	<u>offset</u>	
1	0	→ 1st fragment
1	not 0	→ intermediate fragment
0	not 0	→ last fragment
0	0	→ No fragmentation is done.

}

Fragmentation done

No fragmentation

Algorithm

- i) Destination should identify that fragmentation is done (using MF, off)
- ii) Destination should identify all fragments belonging to the same datagram using identification field
- iii) Identify 1st fragment (MF=1 & offset=0)
- iv) Identify subsequent fragments until MF=0 using (MF, TL, HL, offset)
i.e. if f_i is a fragment, then we need to identify f_{i+1}

$$\text{offset of } f_{i+1} = \left(\text{offset of } f_i + \frac{TL_i - HL_i * 4}{8} \right)$$

IF $MF_i = 0$ then we don't find f_{i+1}

(v) Repeat (iv) until MF=0

Eg: Consider fragment

	20 176	20 88	20 88	20 148
offset	0	22	33	44
MF	1	1	1	0
HLF	5	5	5	5
TL	196	108	108	168
Id	100	100	100	100

Identify 1st fragment (MF=1 & off=0)

$$\text{offset of 2nd fragment} = 0 + \frac{196 - 5 \times 4}{8} = 22$$

and 2nd fragment with offset 22 is present

offset of 3rd fragment

$$= 22 + \frac{108 - 5 \times 4}{8}$$

$$= 22 + 11$$

$$= 33 \quad (\text{exists})$$

offset of 4th fragment

$$= 33 + \frac{108 - 5 \times 4}{8}$$

$$= 44$$

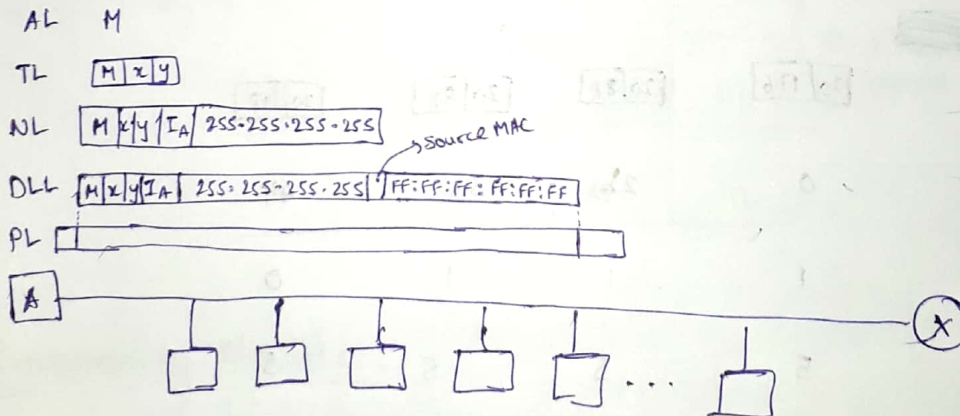
MF of 4th fragment = 0

$\therefore$ Reassembling is finished

Protocols & Concepts at Network Layer:

Implementation of broadcasting:

Limited Broadcasting:



Here

For limited broadcasting destination IP = all 1's

destination MAC = all 1's

→ Every NIC is configured such that it accepts ~~per~~ packet if destination MAC is all 1's

→ when the packet finally reaches Router R, (where the N/w ends) the router R will ~~accept~~ and discard the packet.

Directed Broadcasting:

Destination IP = ~~all 1's~~ Nid + (all 1's in tid)

Destination MAC = MAC of gateway router

→ Now this packet is routed until it meets the router which is directly connected to the destination N/w.

→ ~~At~~ this router forwards packet into ~~to~~ the destination N/w.

Before forwarding it sets destination IP to all 1's
Destination MAC to all 1's

→ ~~A~~ Like in the limited broadcasting this packet will also ~~not~~ be discarded by the router of the network.

Address Resolution Protocol

→ ARP is used to find MAC address of a destination given its IP add.

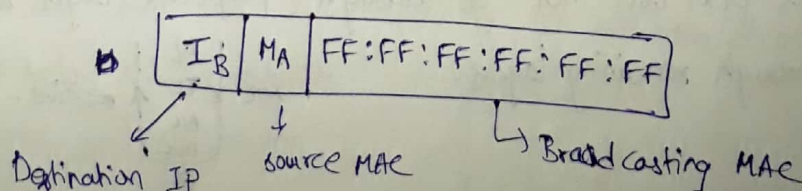
~~Receiver in same N/w~~

Receiver in same N/w:

→ On sender side, ARP can find whether receiver is on the same N/w ^{or} not using subnet mask of sender and destination IP.

→ If it is found to be on same N/w,

sender ^{broadcasts} ~~sends~~ an ARP request packet which contains destination IP and MAC of sender. whichever destination has the IP matched will send its mac address to A.



Receiver on different N/w:

with dest IP = IP of router

- In this case sender ~~sends~~ ^{broadcasts} ARP packet ~~to router~~ ^{default} to know the MAC of the router.
- After this original data pkt is sent to router from which is sent to the destination

Note:

- ARP request is broadcast message
- ARP reply is unicast message
- ARP is ~~app~~ used in below cases

(i) Host needs MAC of Host

(ii) Host " " " Router

(iii) Router " " " Host

(iv) Router " " " Router

- If source and destinations are in diff network then source can never know the MAC of destination and destination can never know the MAC of source.

Special address 127:

- The ID 127 of class A is reserved for special purpose.

It is used for testing self connectivity.

- If a system needs to check if its NIC is working properly or not then it can set destination add. as 127.0.0.1
- This pkt will not go through physical layer but goes ~~to~~ through remaining layers.



→ However the addresses 127.0.0.0 & 127.255.255.255 should not be used.

→ Usage: ping 127. . . .

If NIC is not working then we get timeout message.

→ Since pkt comes back to same system this address is called loop back address.

→ One more application is that

if we are implementing server on a host then to test if the server is working or not we also put a client processes on the same host and we can start communication b/w them.

Here the processes are identified using port numbers

message	source port	dest port	source IP	loop back add
---------	-------------	-----------	-----------	---------------

eg: let IP add is I_A .

port num of server is 80

port num of client is 90

M	80	90	I_A	127.0.0.1
---	----	----	-------	-----------

RARP (Reverse ARP)

→ This is used to know IP add of a host given MAC add of the host.

→ when a system is turned off or newly brought into N/w, it doesn't know its IP address.

→ RARP server contains MAC add & corresponding IP addresses of the systems. The below shown table is maintained at RARP server

MAC	IP
M_1	IP_1
$\vdots$	$\vdots$

→ Now ~~the~~ the host sends RARP request packet with

~~destination~~ ^{source} IP = 0.0.0.0 and dest IP = 255.255.255.255

• source MAC = MAC of the host

destination MAC = All 1's (i.e. Broadcast)

→ Looking at IP = 0.0.0.0 remaining hosts in N/w discards this

but RARP server replies the host with the host's IP.

Disadvantages:

→ But for this protocol to work, there must be RARP server at every network (∵ we are broadcasting the RARP req packet)

Due to this the data is distributed across different RARP servers and if there is same data then updations has to be done at every server.

→ The IP addresses assigned are static. Even if some hosts are not active, the IP addresses are kept assigned.

∴ no of IP add ≥ no of hosts

However ~~this~~ RARP is not currently under use.

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BootP : (Bootstrap Protocol)

→ This also used to know IP address of a host given its MAC.

→ ~~Like~~ Here also we have a BootP server. This server will have a static table of MAC & IP addresses

→ Here also packet is sent in the same way requesting for IP address.

→ The main difference b/w RARP & BOOT is that RARP ^{server} operates at network layer (and may not contain other ^{higher} layer) where as BOOTP ^{server} operates at application layer

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→ Relay agent is used to obtain IP addresses if BootP server is not present in the network.

If a station needs to find its IP add, it broadcasts the request pkt. Since BootP server is not in the N/w relay agent ~~the~~ accepts this message and unicasts this to bootP server on the other N/w. Then BootP server replies to relay agent and relay agent ~~replies~~ replies to the station.

Adv:

→ we can have only one bootP server and hence data is centralized

Disadv: Data is static

i.e., Mapping b/w MAC & IP is static

DHCP (Dynamic Host Configuration Protocol)

→ Its working is same as BootP. Here we have DHCP server. Here also we have relay agents.

→ The main difference is that ~~static~~ mapping b/w MAC & IP is ~~dynamic~~ ~~both~~ has 2 parts

is Static is Dynamic

Given to stations which runs forever

Given to station that runs only for some time.

MAC	IP
⋮	⋮

Static

MAC	IP	Lease time
M ₁	I ₁	10 min
⋮	⋮	⋮

Dynamic

→ For dynamically assigning,

a pool of IP addresses is maintained. whenever a host requests, an ~~an~~^{IP} address is assigned and an ~~entry~~ entry is created in the table. After the lease time finishes, the station has to renew request if it needs IP for some more time. Otherwise, the IP address will be kept back in the pool and ~~the~~^{the} entry is deleted.

Adv: (i) only one DHCP server is required.

(ii) Dynamic table

∴ no of IP add = no of hosts online

(iii) DHCP is also compatible with BootP request.

so for this purpose port numbers of DHCP & BootP are same.

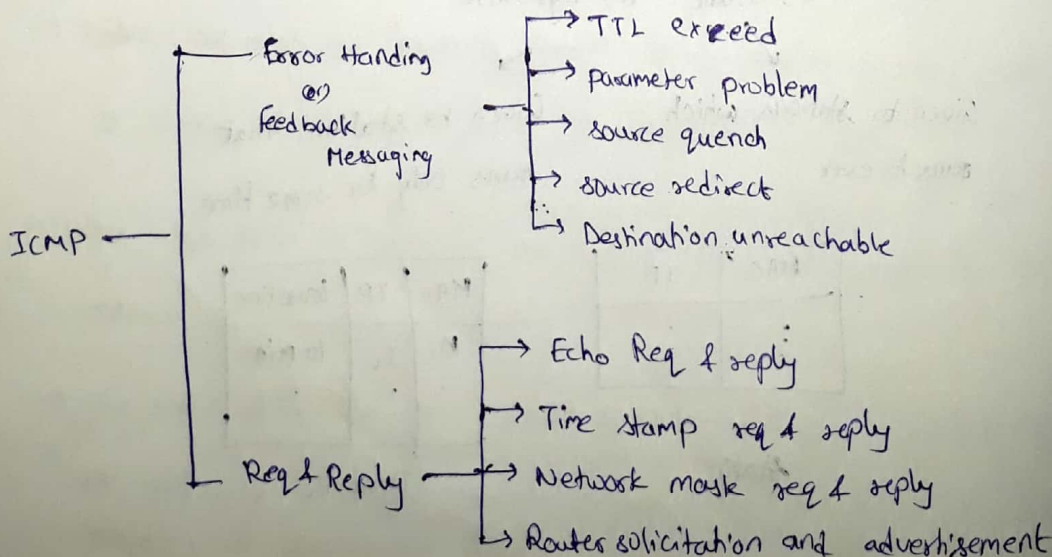
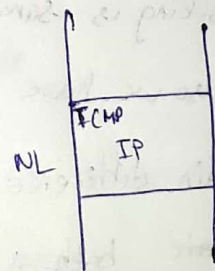
ICMP (Internet Control Message Protocol)

→ ICMP packet is sent to sender if the sent packet is discarded at router or destination.

→ ICMP packet is also used for req & reply.

Here ICMP packet is sent as request and

an ICMP packet is obtained as reply.



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→ when IP pkt is discarded, an icmp pkt is sent.

~~when~~ But if this generated icmp packet is discarded again, then no ICMP packet will be generated again. and in this case sender will not know that its pkt is discarded.

∴ (IP+ICMP) is still not reliable. However TL (TCP) is reliable.

ICMP Error Messages:

TTL exceed:

when TTL exceeds router discards the pcks and sends icmp packet.

Here icmp type = TTL exceed

Source Quench:

when a source (system or router) sends lot of p pcks to a ~~single~~ router and if the receiving router can't handle all the data, then source quench icmp pkt will be sent to source.

Seeing this packet source will reduce the transmission

Parameter Problem

Assume we are using strict source routing, if a router given in the path is found to be down at the time of routing then ~~ICMP~~ this ICMP message will sent.

Also this message is sent if the packet sent is corrupted

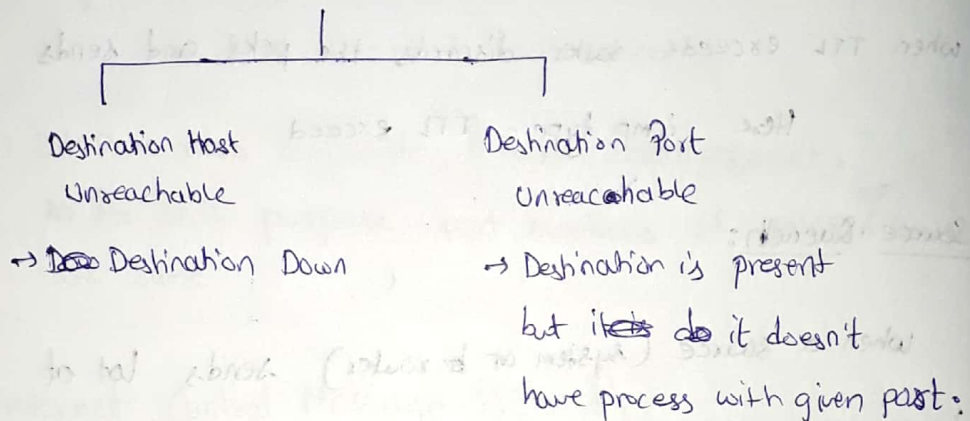
Destination Unreachable



↓
Destination is down
This router tries to
obtain MAC of D. But D
doesn't respond.

So R2 sends destination host unreachable message

Destination Unreachable

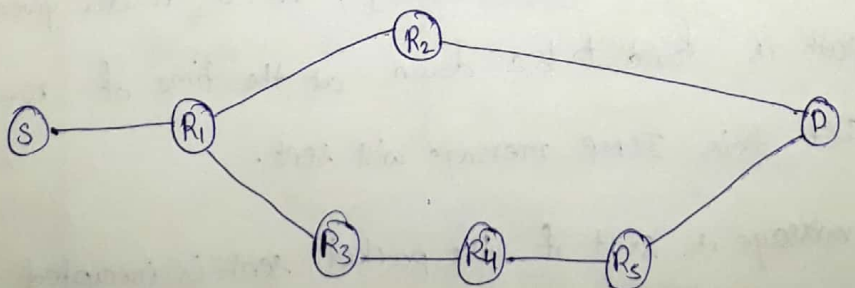


→ Also destination unreachable may occur when DF=1

In this ICMP message, it is specified that fragmentation is required and DF=1 and MTU of the network.

Source Redirect:

Consider



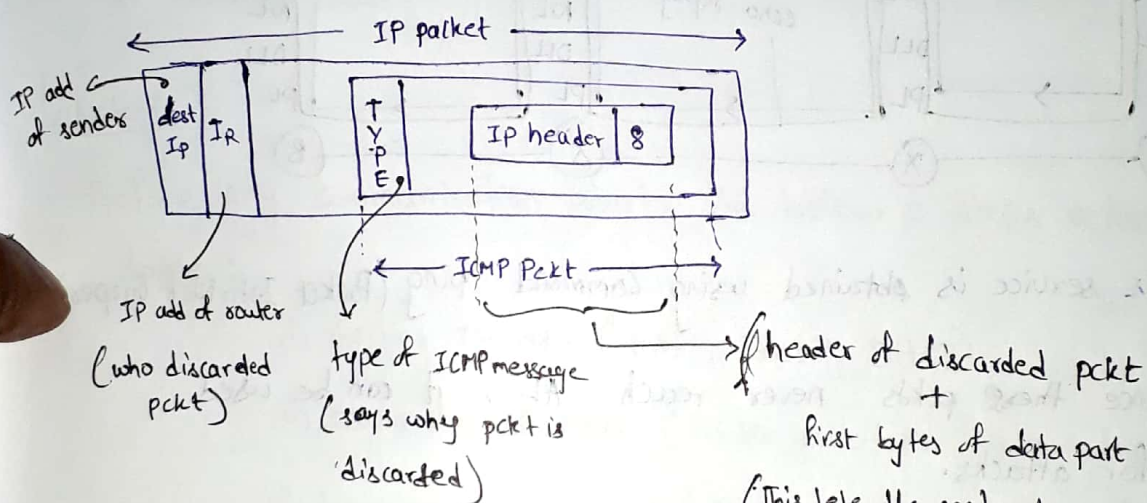
Here the best path is S-R1-R2-D

But consider R_1 has forwarded pkt to R_3 .

Incase if R_3 knows that there is better path, then R_3 sends icmp ~~msg~~ pkt to R_1 (warning message) saying that there is a better path.

However R_3 doesn't discard the pkt. and from next time onwards R_1 forwards to R_2 .

ICMP message format:



(This lets the sender know which pkt is discarded.)

Also the 1st 8 bytes are sent so that if it is TCP protocol then port numbers will be known and the ~~ip~~ source process will be known that the pkt is discarded.

→ ICMP is generated only if the discarded pkt is either TCP or UDP.

→ If the datagram has several fragments, ~~then it is~~ and if it is discarded then ICMP is generated only for 1st ~~pkt~~ fragment.

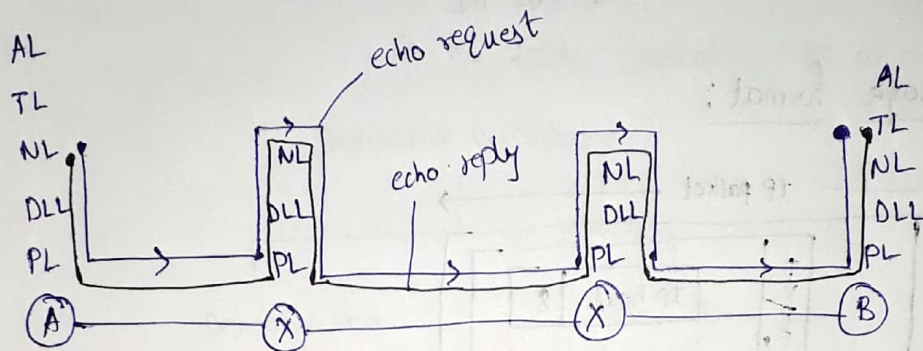
Even if 1st fragment is transmitted correctly and if 2nd fragment is discarded, then also ICMP will not be generated.

ICMP request and reply:

Echo request & reply:

It is used to see if the destination is ~~present (online)~~ ^{switched} or not.

The ICMP packet never meets Application layer & transport layer



→ This service is obtained using command ping (Packet InterNet Groper).

→ Since these packets never reach AL, it can be used for attacks.

For example we can send lot of pings to a server and keep it busy with echo replies and thus deny other services..

Router Solicitation:

→ This ICMP packet is sent by a station to know ~~the~~ who is the default router.

→ So this ~~per~~ ICMP packet (router solicitation ICMP packet) is broadcasted and all the ~~a~~ routers in the N/w will reply.

→ One among these is used as default.

Router advertisement:

Whenever a new router is brought into network, this router ~~sends~~ broadcasts router advertisement ICMP packets ~~saying~~ that you can use me as default router.

Network Mask Req & Reply:

⊗ This ICMP msg is sent by a host to know its N/w mask or subnet mask.

Note:

Before any communication starts the below 3 steps ~~are~~ has to be done:

- (i) Getting IP add (RARP, BootP, DHCP)
- (ii) known default router (Router solicitation / Router advertisement)
- (iii) knowing Network mask (Network mask Req & reply)

Time stamp req & reply

- Two stations which are communicating may be in different time zones. So we need to synchronize the communication.
- Time stamp req & reply is used to know the time at destination and destination uses this to know the time at sender.
- However this is highly unreliable. and there are better ways to synchronize time.

Trace Route:

- This is an application of ICMP.
- This is used to know the path (routers involved in the path) of communication.
- The option record route is used to know the path ~~by~~ for destination.

But trace route is used to know the path for sender.

Implementation:

- Here we send a packet with $TTL = 1$.

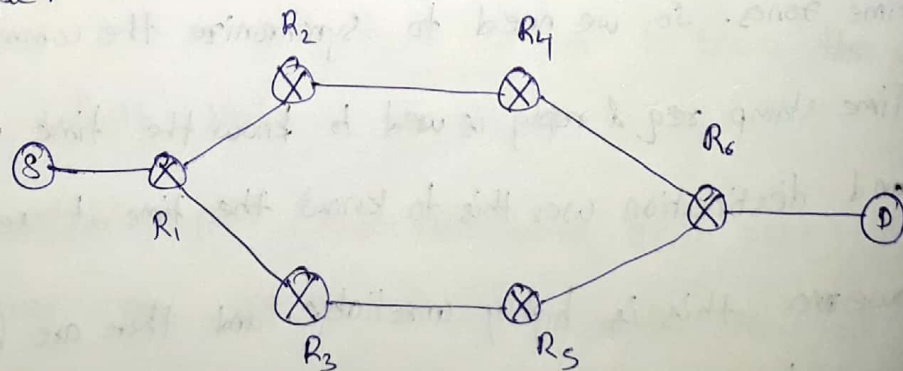
At ~~router~~ first router TTL becomes 0 and we can know the first router. ($\because$ router sends TTL exceeded ICMP)

Similarly we do ~~that~~ ^{the} same with $TTL = 2$ and know the 2nd router in the path.

We continue this process until we get ICMP packet from the destination. (To get ICMP packet from destination we ~~intentionally~~ ^{intentionally} put unreachable port number in the packet)

- However in some ~~case~~ case route obtained may be wrong.

For example,



$TTL = 1 \Rightarrow R_1$

$TTL = 2 \Rightarrow R_2$

$TTL = 3 \Rightarrow R_5$

$TTL = 4 \Rightarrow R_6$

$TTL = 5 \Rightarrow D$

$\therefore R_1 - R_2 - R_5 - R_6 - D$ is not a valid path

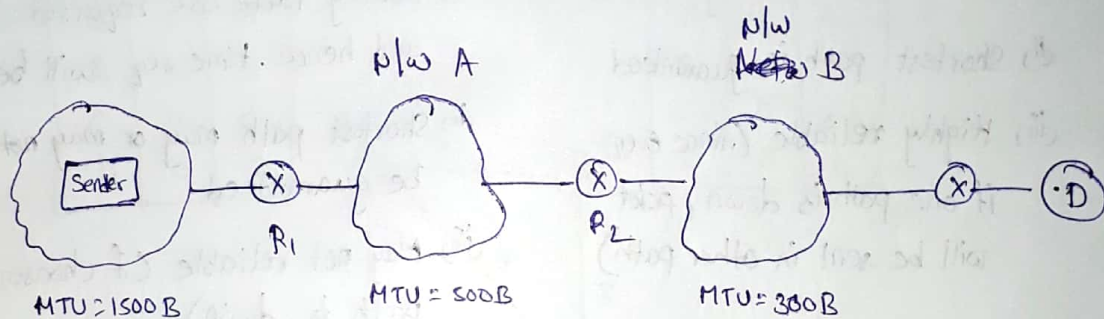
(But this is generally least probable case cuz routes don't change that fast)

PMTUD (Path MTU Discovery):

- It is another application of ICMP
- It is used to know ~~the~~ MTU along the path.
- Thus, using this, we can know least MTU in the path and we can send datagram of that size and thus avoid overhead of fragmentation.

Implementation:

Consider below scenario



- Initially we send pkt with maximum allowed size in sender network with $DF=1$.

Once it reaches N/w A, destination unreachable ICMP pack is sent by Router R₁ to sender. After this sender reduces the size and sends again.

This process is continued until pkt reach destination.

(To know that pkt has reached destination we put invalid port num in destination port and thus destination sends ~~invalid~~ destination port unreachable message to the sender.)

- However here also there is a chance that path followed for each packet may be different.

Routing

- Routing is process ^{of} preparing routing table ~~that~~ and this routing table is used ^{for} switching
- ~~without~~ If there is no routing then we ^{use} flooding.
- Flooding is process of sending obtained packet ~~to~~ to all the links except to the link the ~~packet~~ packet has arrived on.

Advantages of ~~the~~ Flooding:

- (i) No need of routing
- (ii) Shortest path is guaranteed
- (iii) Highly reliable (since even if one path is down, packet will be sent in other path)

Disadv of Flooding:

- (i) Many duplicate packets are received at destination
- (ii) More traffic

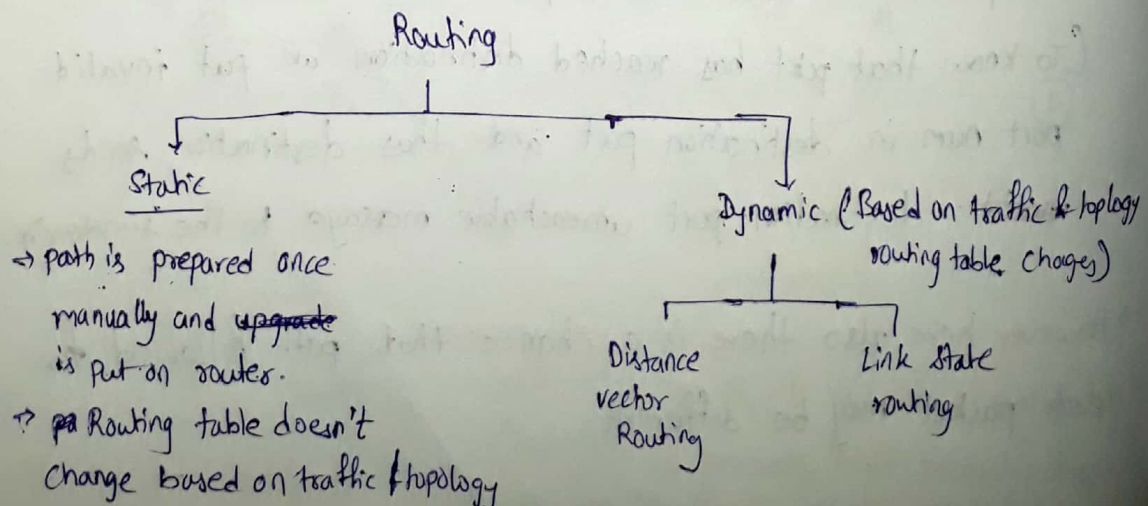
Disadvantages of Routing

- (i) Routing table are required and hence time req. will be more.
- (ii) Shortest path may or may not be guaranteed
- (iii) May not reliable (if chosen path is down)

Advantage of Routing

- (i) No duplicate packets will be received.
- (ii) Low traffic.

Types of Routing Algorithms:



Distance Vector Routing (DVR)

Every router has a routing table with below structure :

Destination	Distance	Next hop
⋮	⋮	⋮

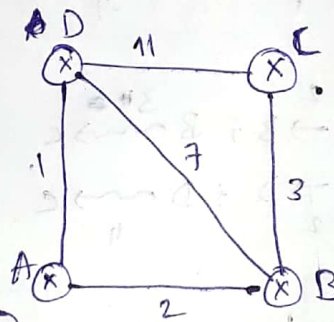
Distance vector

If a router is not directly connected then distance is ∞ .

Step 1: Based on the local information every router builds routing table as shown below

Des	Dis	NH
A	1	A
B	7	B
C	11	C
D	0	D

Des	Dis	NH
A	∞	-
B	3	B
C	0	C
D	11	D



Des	Dis	NH
A	0	A
B	2	B
C	∞	-
D	1	D

Des	Dis	NH
A	2	A
B	0	B
C	3	C
D	7	D

Step 2: Every router sends its distance vector to adjacent routers. (DVR)

At A: DV received from B, D

At B: DV received from A, C, D

At C: DV received from B, D

At D: DV received from A, B, C

All this sharing will happen at once in parallel ($\because$ the channels are full duplex)

Using these distance vectors of neighbouring routers, each router builds new routing table.

At A:

From B

2
0
3
7

From D

1
7
11
0

New routing table (while building new routing table old table shouldn't be used)

A	0	A
B	2	B
C	5	B
D	1	D

$$A \rightsquigarrow B = \min \begin{cases} A \xrightarrow{2} B + B \xrightarrow{0} B \\ A \xrightarrow{1} D + D \xrightarrow{7} B \end{cases}$$

$$A \rightsquigarrow C = \min \begin{cases} A \xrightarrow{2} B + B \xrightarrow{3} C \\ A \xrightarrow{2} D + D \xrightarrow{11} C \end{cases}$$

$$A \rightsquigarrow D = \min \begin{cases} A \xrightarrow{1} D + D \xrightarrow{0} D \\ A \xrightarrow{2} B + B \xrightarrow{7} D \end{cases}$$

→ : edge
~ : path

Shortcut

	A	B	C	D
B:	2	0	3	7
	↓ AB (i.e., 2)			
	4	2	5	9

	A	B	C	D
D:	1	7	11	0
	↓ AD (i.e., 1)			
	2	8	12	1

Pick Minimum

A	0	A
B	2	B
C	5	B
D	1	D

(since if A to A it is 0 but not min of above two)

At B :

From A

0
2
∞
1

$\xrightarrow{+AB}$
(2)

2
4
∞
3

From C

∞
3
0
4

$\rightarrow$

∞
6
3
14

From D

1
7
11
0

$\rightarrow$

8
14
18
20

A	2	A
B	0	B
C	3	C
D	3	A

At C :

from D

1
7
11
0

from B

2
0
3
7

$\xrightarrow{+3}$

5
3
6
10

A	5	B
B	3	B
C	0	C
D	10	B

At D :

A

$+1$

1
3
∞
2

B

$+7$

9
7
10
14

C

$+11$

∞
14
11
22

A	1	A
B	3	A
C	10	B
D	0	D

At the end of 2nd round we get shortest paths containing atmost 2 edges.

Since we have 4 routers, we need to go for 3rd round also for the final routing tables.

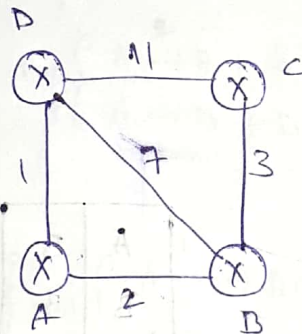
(But in exam we find out shortest path directly from the graph)

So the final routing tables are

Even after getting final routing table, ~~exchanging~~ ^{exchanging} DVs will continue forever periodically.

A	1	A
B	3	A
C	6	A
D	0	D

A	5	B
B	3	B
C	0	C
D	6	B



A	0	A
B	2	B
C	5	B
D	1	D

A	2	A
B	0	B
C	3	C
D	2	A

→ In routing table of D, C is not present as next hop for any entry. Similarly in routing table of C, D is not present as next hop for any entry.

This means the link DC is not at all used.

Similarly, the link BD is also not used.

shortcut for finding unused links:

A link PQ will be unused if there is ~~not~~ better path from P to ^{other} Q than the direct path b/w P & Q.

[Try this method for previous example]

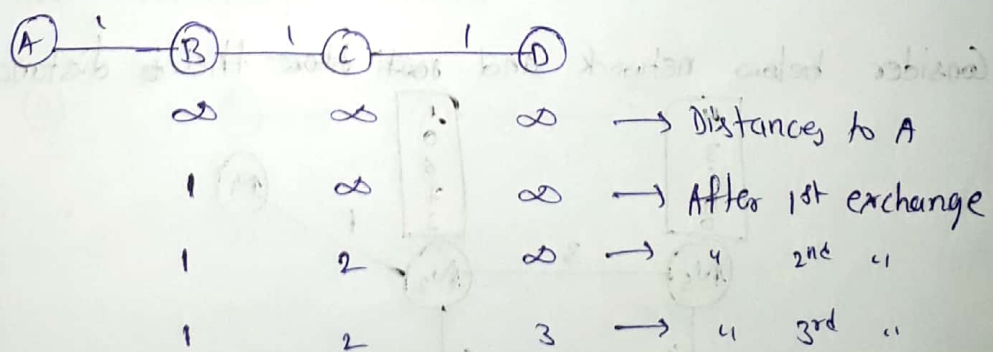
Count to infinity problem

→ This is a disadvantage of DVR

→ The problem is bad news ~~spread~~ spreads slow
good news ~~spread~~ spreads fast.

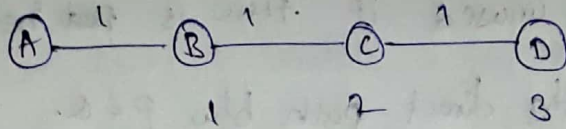
Good news (A new ~~host~~ ^{router} is on):

Assume Router A is initially ~~down~~ down and now it is up



Thus good news ~~spread~~ spreads fast.

Bad news: (when a router is down)

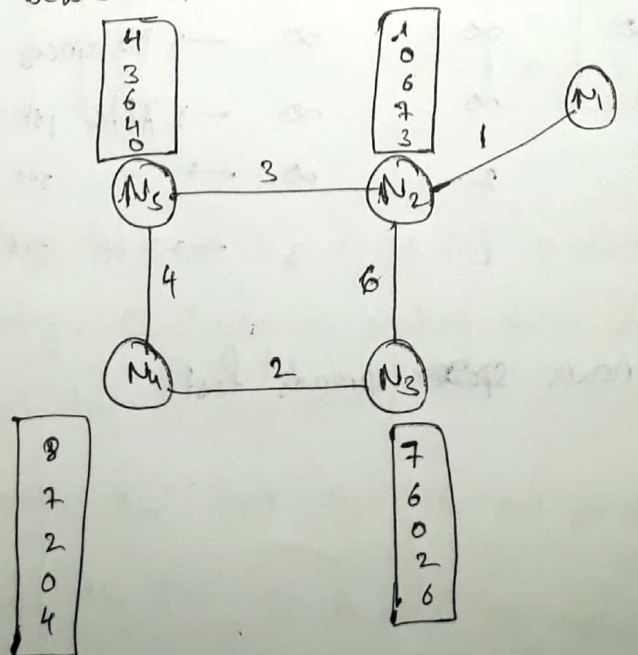


A	B	C	D
	1	2	3
	∞	2	3
3		2	3
3	4		3
5	4	5	
5	6	5	
7	6	7	
7	8	7	
9	8	9	
$\vdots$	$\vdots$	$\vdots$	
∞	∞	∞	

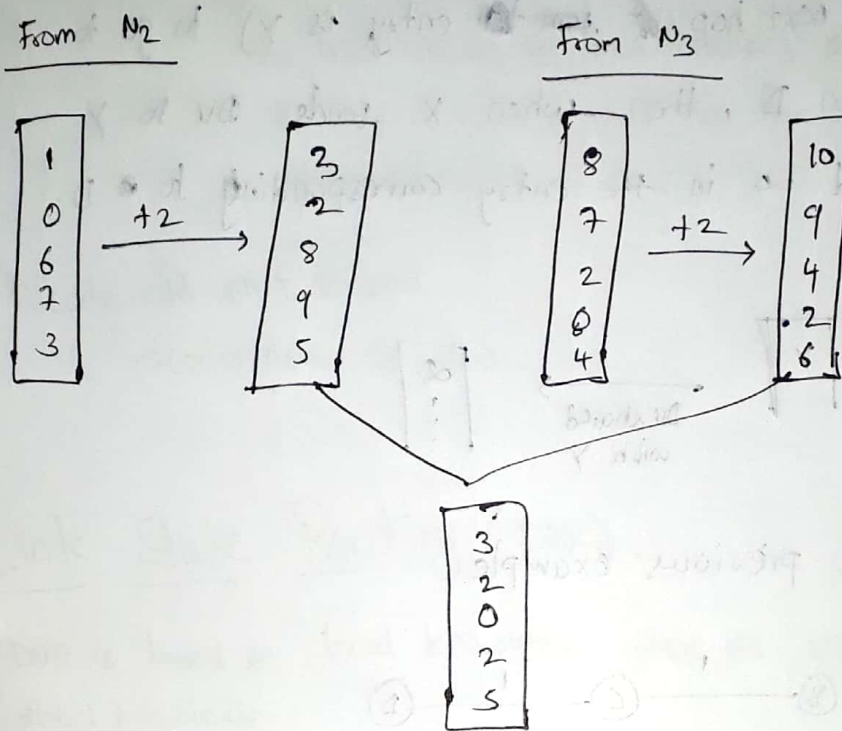
thinks
(Here B ~~thinks~~ that C has some other path to A)

This continues until distance reaches infinity and here infinity is value set by us.

Q) Consider below network and ~~reach~~ ~~Here~~ their distance reaching

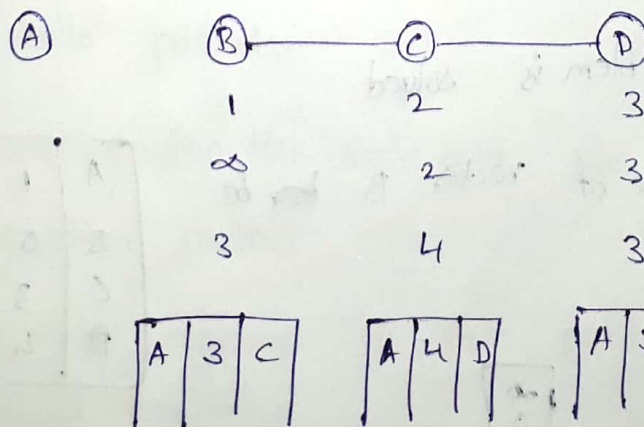


If somehow distance b/w N_2 & N_3 fall to 2, then what will the new routing table at N_3 after one exchange.
 eg:



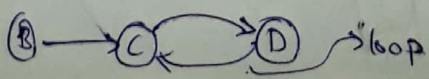
Split Horizon

→ Count to infinity problem • also causes a packet to loop in the network. For example consider



Now consider B wants to send a packet to A.

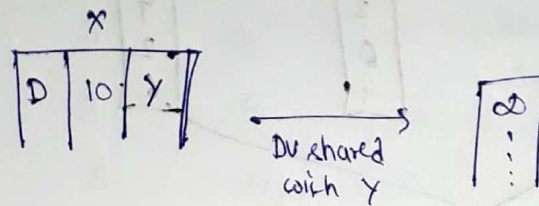
B sends it to C; C sends to D; D sends to C;
 C send to D; D sends to C; ...



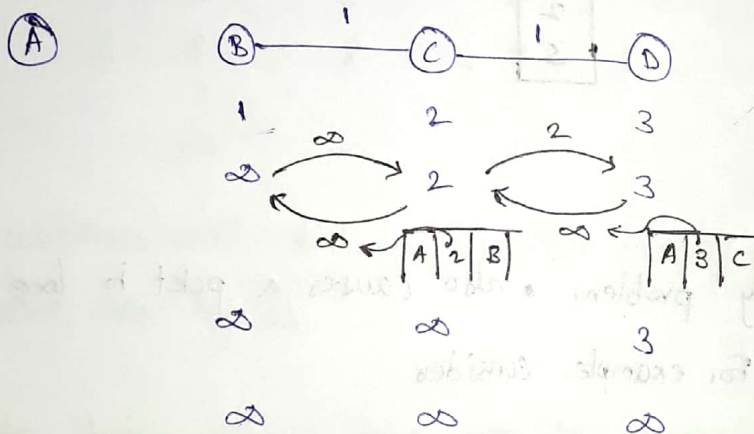
Split Horizon:

→ This is solution for count to infinity problem.

→ Split Horizon ^{says} if a router ~~A~~ x is depending on router y (i.e., next hop ~~is~~ entry is y) to go to some destination D , then when x sends DV to y it should send ∞ in the entry corresponding to D .



Now consider the previous example



And thus the problem is solved

Eg: Let routing table of router B be

A	1	A
B	0	B
C	3	A
D	4	D

Then

DV sent to A

∞
0
∞
4

DV sent to D

1
0
3
∞

Disadv without split horizon:

- i) Count to infinity
- ii) loops
- iii) Convergence is slow

i.e., new updates or modifications are not known quickly to routers that are far away from ^{the point} where the modification is done

Disadv with split horizon

→ convergence is slow.

Link State Routing (LSR):

→ DSR is based on local knowledge whereas LSR is based on global knowledge.

→ Here every station prepare link state pkts.

A link state pkt ~~can~~ of a router contain distances of its neighbouring routers.

The neighbours and the corresponding distances are found using 'hello' packets.

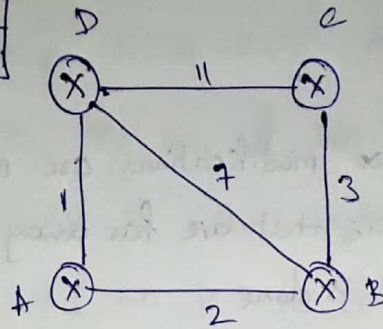
→ After creating the link state pkt, the pkt is flooded to every other router.

So every router receives link state pkt of every ^{other} router.
i.e., global knowledge

→ ^{From} For this information, a router ~~can~~ can build entire graph of the network.

D	
Seq	
TTL	
D	11
B	7
A	1

C	
Seq	
TTL	
D	11
B	3



A	
Seq	
TTL	
B	2
D	1

B	
Seq	
TTL	
A	2
D	7
C	3

→ Now each router applies Dijkstra's algorithm and knows shortest path to each router.

∴ Here convergence is faster.

→ Need of seq num:

Since flooding is used there is a chance that a router receives same pkt twice. ~~It is~~ Assume by the time 2nd copy arrives, the router has already obtained latest packet (from same router). But still this accepts & uses old pkt. To overcome this we use sequence number field.

Every router maintains latest seq num of each router's link state pkt

Router	latest seq num	life time
R ₁	10	10 min
R ₂	9	10 min
⋮	⋮	⋮

Thus using seq num old pkts are discarded and are no more flooded and thus seq num field even helps in decrease flooding.

→ Need of TTL field:

Since flooding is being used, there is a chance the pkt may loop infinitely in the network. To avoid this TTL is used.

→ Need of lifetime field:

~~Assume a case where seq num is 156~~

Assume a case where a link state packet with seq num 15 (00001111) is being transmitted and say due to a single bit error it is changed to 143 (10001111):

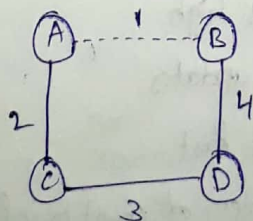
Now all the link state pkts upto seq num 143 will be discarded and ≥ 144 will be accepted.

To overcome this problem every entry has lifetime/validity after which we accept any link state pkt that arrives.

Problems in LSP:

The problems in LSP are ~~not persi~~ transient (non-persistent)

1) Black hole problem:



If the link AB is down then A & B will know ^{after} this ~~for~~ some duration of time.

So any packets sent by A to B will not reach B ^{during this time}.
After some time A will get to know that the link is down and will send pkts in different path.

(ii) Looping:

Here looping is present but for only some ~~long~~ duration.

→ Consider the previous case where the link AB is down.

After A knows the link is down, A chooses the path A-C-D-B.

But C knows that the link is down after some duration. So for C the path to B is ~~still~~ still C-A-B.

→ so: if C needs ^{to} send a pkt to B then it sends to A and A sends it to C will send it back to A again and this process continues until C discovers that the link AB is down/

DVR	LSR
1) used in 1980's 2) BW req is less 3) Based on local knowledge 4) Similar to bellmanford 5) Traffic is less 6) Periodic updates 7) Convergence is slow 8) Count to inf is present a) persistent looping b) Implementation: RIP	1) used in 1990's 2) BW req is more 3) Based on global knowledge 4) Dijkstra's algo 5) Traffic is high 6) periodic updates 7) convergence fast 8) No problem of count to inf 9) Transient looping 10) Implementation: OSPF

Routing Information Protocol (RIP):

→ This is implementation of DVR.

→ Here metric is hop count

∴ Every edge has weight 1

→ Here ∞ is equivalent to 16

→ Computation is simple (compared to OSPF)

Open Shortest Path First (OSPF):

→ Computation is complex.

~~Avoiding~~ Avoiding traffic of flooding:

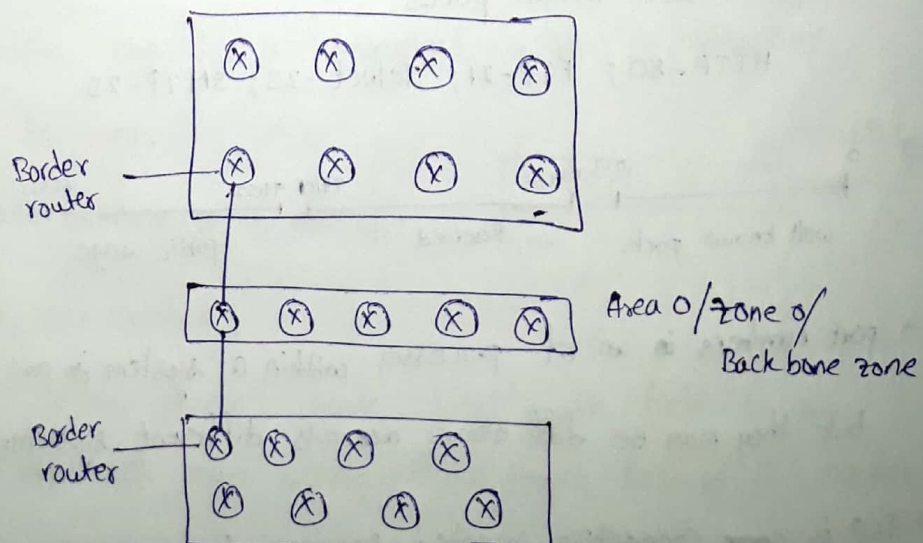
→ These routers are divided into several regions and each region has a border router.

→ All the border routers are connected to area 0 / zone / back bone

→ A border router summarizes the flooded information and sends it to area 0 and from there this packet will be forwarded to other regions.

Thus using this process traffic due to flooding is reduced.

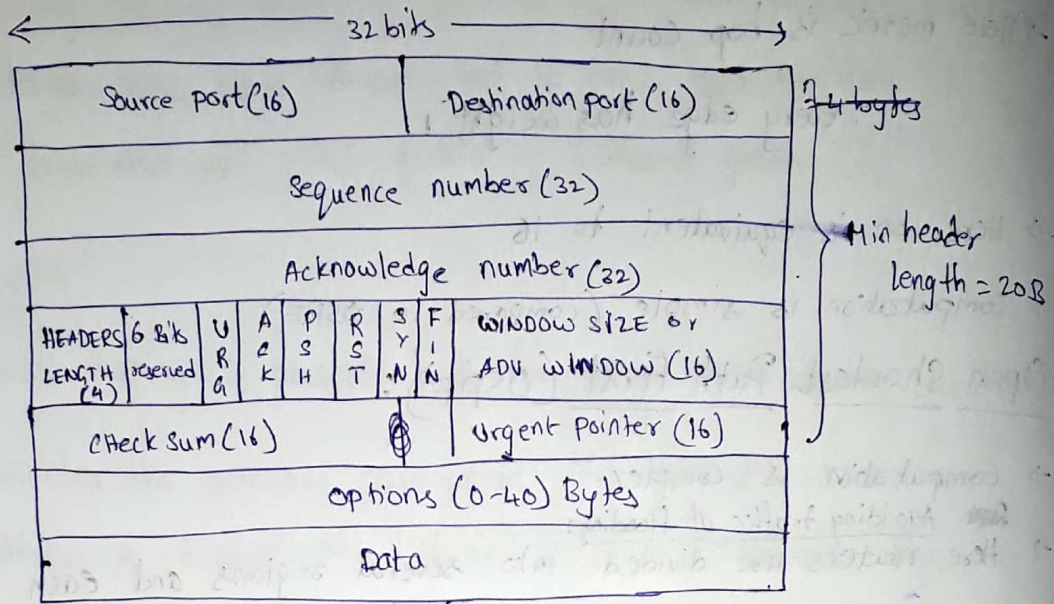
→ Metric is weight set by network administrator.



12/12/20

TCP

TCP Header:



$$\text{Max header length} = 20 + 40 = 60B$$

→ TCP is a transport layer ~~port~~ protocol that ensures end to end communication.

→ So, TCP is an end to end protocol.

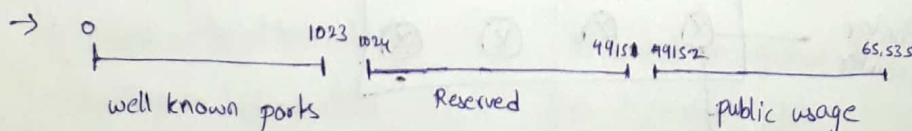
Source port & Destination port

→ Using port numbers TCP does the job multiplexing & demultiplexing.

→ port is a 16-bit number.

→ Example of well known ports

HTTP-80; FTP-21; Telnet-23; SMTP-25



→ port numbers ~~in~~ of processes within a system ~~are~~ are unique but they may be ~~the~~ same across different systems.

→ TCP is ~~conn~~ connection oriented service. For any connection oriented service, resources (BW, buffers etc.) are reserved.

→ Identifying a connection uniquely is not possible using only port or only IP. ~~is not possible~~.

→ So we use combination of IP add & port num called Socket to identify a ~~port~~ connection uniquely.

∴ Socket = IP + port

∴ Socket is 48 bits

Sequence Number:

→ TCP is a byte stream protocol

i.e., Every Byte is counted

IP is packet stream protocol

It ~~is~~ means logically we assume every byte is numbered.

→ The seq num field contains number given to the first byte in the segment

Acknowledge Number:

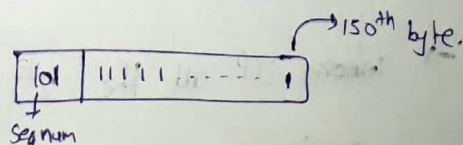
→ It is a byte number of next expected byte.

This number is sent as ack by receiver.

⊗ For example consider a segment with 50 bytes and

seq num is 101.

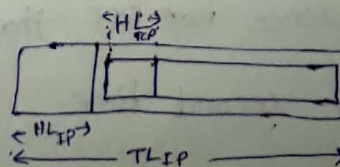
Then ack number is ~~101~~ 151



→ How to calculate ack number?

~~TCP~~ TCP header doesn't have total length field. So we calculate ~~ack~~ ack num using total length field of IP header

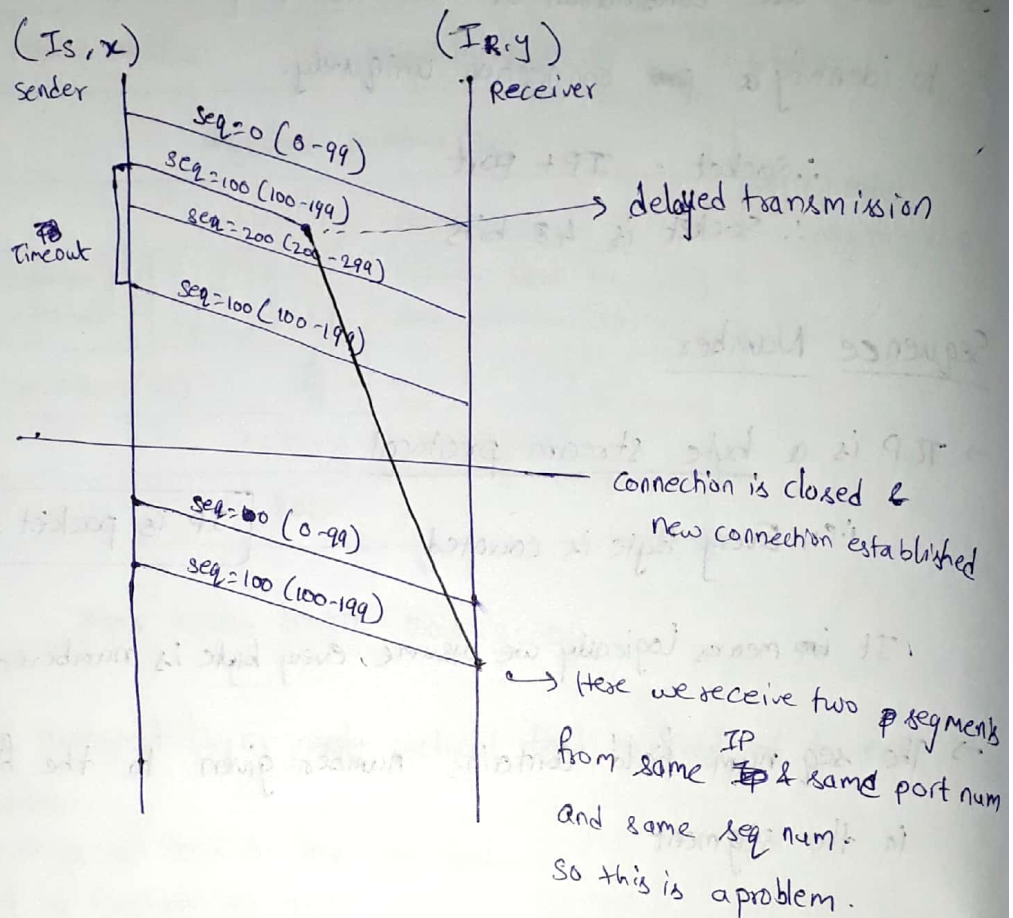
⊗ $TL_{IP} - HL_{IP} - HI_{TCP}$ gives no of bytes in segment and from that we calculate ack number.



Note:

Starting a seq num always from 0 has a problem.

~~For~~ Consider the below case.



→ To overcome this, TCP ~~uses~~ ^{uses} randomly generated numbers as starting sequence numbers.

However here also there is a chance of conflict but it is very negligible.

→ ~~when~~ If all the 2^{32} seq numbers are assigned then we again start numbering from 0. This is known as wrapping around.

Wrap around time: The amount of time take to use the sequence number that we started with (need not to be 0) for second time.

wrap around time depends on bandwidth.

Eg: If BW = 1 MBPS

then

10^6 seq num ——— 1 sec
are used

$\Rightarrow 2^{32}$ seq num ——— $\frac{2^{32}}{10^6}$ sec

i.e. ≈ 4296 sec

Since ~~to~~ wrap around time is this big, conflicts won't occur.

Lim

Life time: Maximum amount of time for which a packet can be in network.

Generally ^{it} is 3 min.

$\rightarrow$ For no conflicts to occur,

wrap around time $>$ life time

For example consider, let BW = 1 Gbps

$\Rightarrow$ wrap around time = $\frac{2^{32}}{10^9} \approx 4.29 \text{ sec}$

20)

Here ~~wrap~~ wrap around time $<$ lifetime

The problem for this soln is to increase ~~seq~~ bits in seq num field.

$\therefore$ given life time = 180 sec & BW = 1 Gbps we find no of seq num seq.

18 $\rightarrow$ 1 G seq num

1808 $\rightarrow$ 180 G seq num

$$\Rightarrow \text{no of seq num seq} = 18061$$

$$\Rightarrow \text{no of bits in seq num field} = \lceil \log_2 18061 \rceil = 42 \text{ bits}$$

However we have only 32 bits in the seq num field.

→ So the ~~exp~~ extra bits seq are kept in the options field.

These bits in the options field ~~are~~ ^{is} called timestamp

Header Length:

→ It is a 4-bit field

But max header length possible is 60

$$\therefore \text{Content in 4-bit field} = \frac{\text{original header length}}{4}$$

Q) Consider IP datagram with $TL = 1000$ & $HL = 5$ and consider segment within IP datagram with $HL = 5$ and $seq = 100$. Find acknowledgment number.

Sol:

~~no size of data bytes in segment~~

$$\begin{aligned} \text{Data size of IP datagram} &= 1000 - 5 \times 4 \\ &= 980 \end{aligned}$$

$$\begin{aligned} \text{Data size of TCP segment} &= 980 - 5 \times 4 \\ &= 960 \end{aligned}$$

$$\begin{aligned} \therefore \text{seq num of last byte in segment} \\ &= 100 + 960 - 1 = 1059 \end{aligned}$$

$$\Rightarrow \text{seq num} = 100 + 960 = 1060$$

Flags:

→ SYN - Synchronization Flag

Ack - Acknowledgement flag

→ TCP is connection oriented and it has 3 phases

(i) Connection Establishment

(ii) Data transfer

(iii) Connection Termination

SYN: This flag is ~~used~~ set, when we need to tell the other host that our starting sequence number is so and so.

The packet with this information is called a SYN packet.

SYN pkt consumes a seq num.

→ SYN is used to synchronize the sequence numbers.

Acknowledgement Flag:

In TCP, Acknowledgements are sent in two ways

(i) piggy backing

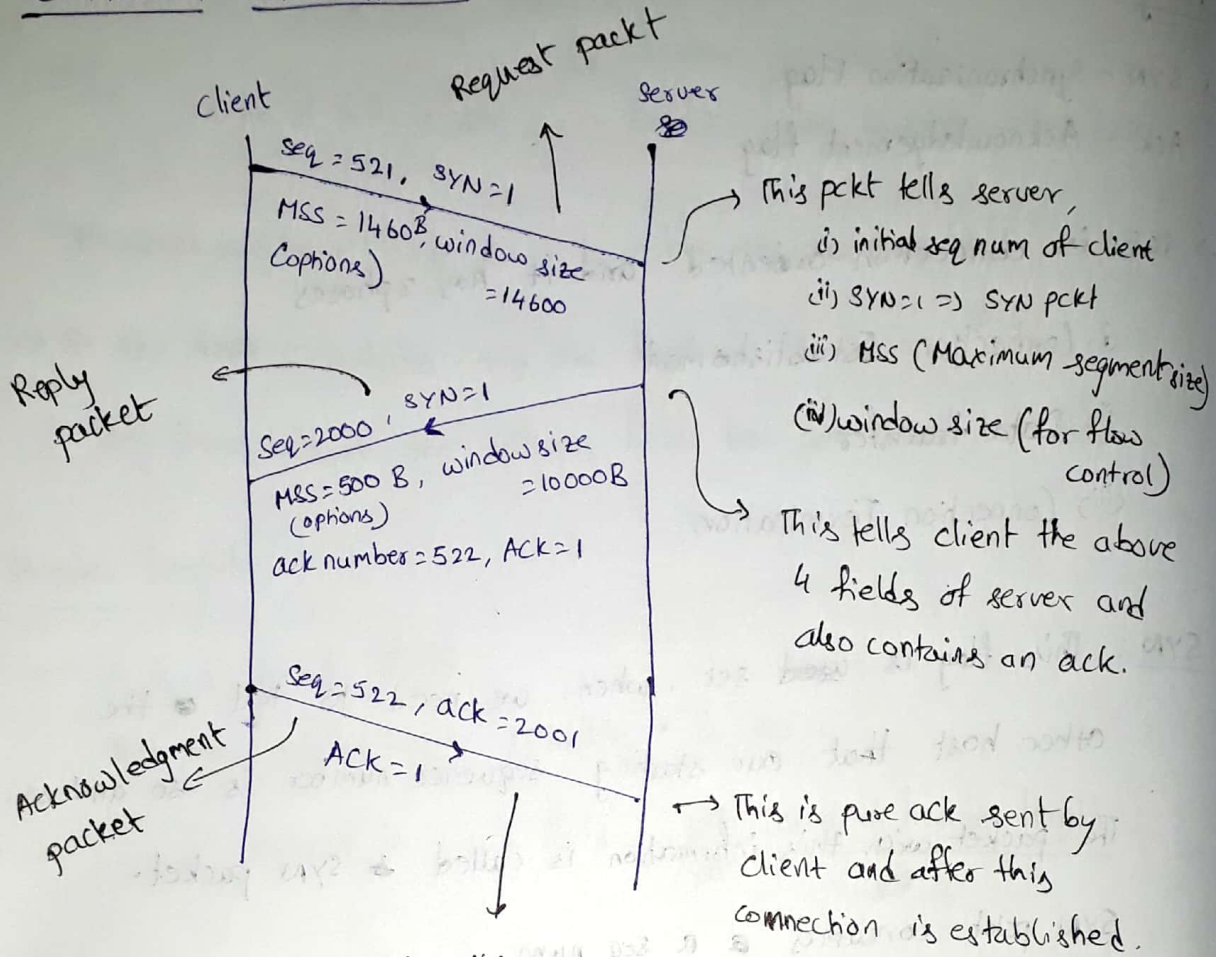
(ii) pure acknowledgement

For both acknowledgements the ack number is ^{put} in ack number field and Ack flag is set to 1. If Ack flag is 0 then no matter what value is present in ack number field, the pkt is considered not to have any acknowledgment.

When sending pure acknowledgement only header is sent.

→ when pure ack is sent, no seq num is consumed.

Connection Establishment :

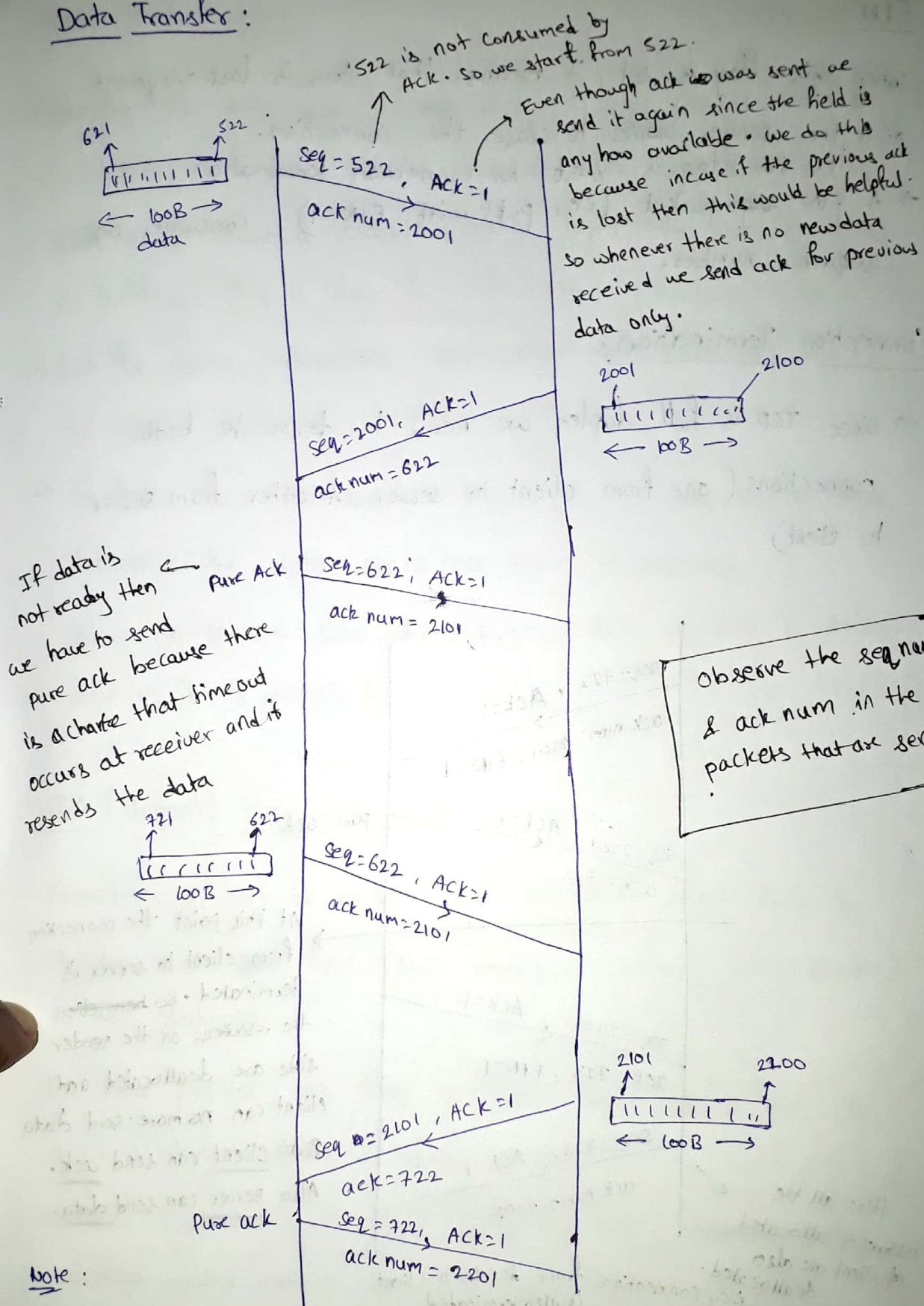


Since this is pure ack, the seq num 522 is not consumed

MSS: Maximum Segment Size is maximum DATA size in segment (i.e., excluding headers)

- The seq num 521 from client & seq num 2000 from server are generated randomly
- Both server and client knows MSS of each other and thus sends the datagrams of the size min which is minimum of the 2 MSS's
- This connection establishment is called 3-way handshake.
- As soon as connection is established resources (BW, buffers etc.) are allocated & reserved at both client & server.
- TCP is a full duplex connection.

Data Transfer:



Note:

<u>SYN</u>	<u>ACK</u>	
1	0	→ 1st segment / Request packet
1	1	→ 2nd segment / Reply packet
0	1	→ Ack is present in header
0	0	→ Invalid Combination

FIN:

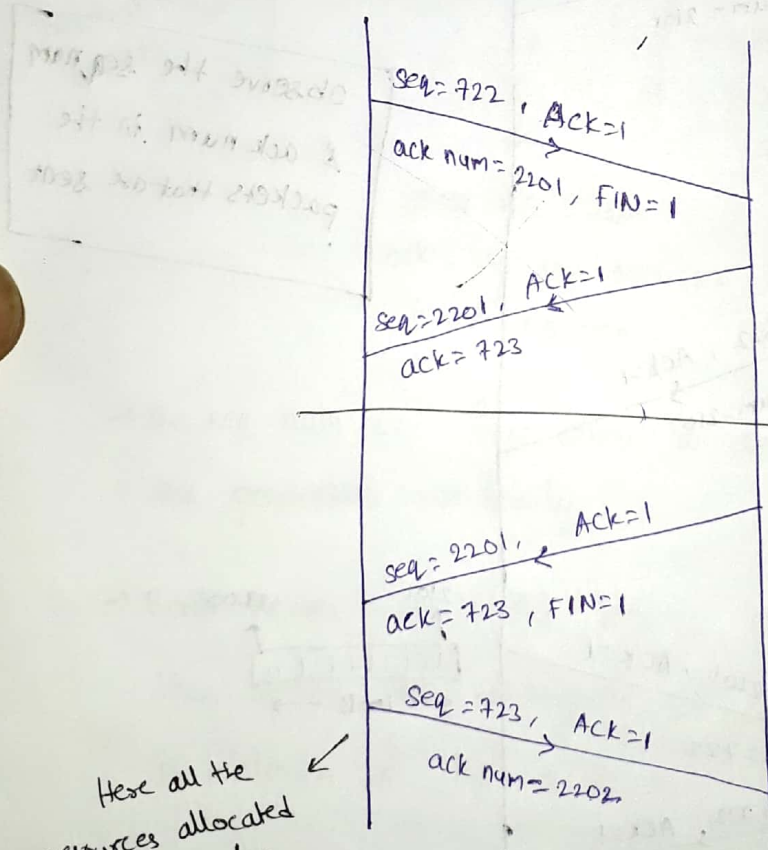
when this flag is set, it means that this is last segment and the sender wants to close the connection.

i.e., FIN flag is ~~request~~ for connection termination

→ A FIN ~~seg~~ packet (i.e., pkt with FIN=1) consumes one sequence number.

Connection Termination:

→ Since TCP is full duplex we need to terminate both connections (one from client to server & other from server to client)



Here all the resources allocated at client are also deallocated.

i.e., connection from server to client is also terminated

→ At this point the connection from client to server is terminated. So ~~here~~ then the resources on the sender side are deallocated and client can no more send data. But client can send ack. Also server can send data.

→ Thus connection termination requires 4 packets in the worst case. However by setting FIN in the 2nd pkt itself, we can terminate the connection ~~is~~ with 3 pkts.

PSH (push flag):

Generally TL waits ~~and~~ ^{until} it ~~also~~ receives large enough data (i.e., MSS) and sends all the data at once. ~~The~~ Until all the data is ~~not~~ obtained from application layer, the data is stored in buffers. This is done for efficiency.

→ But for some interactive application this technique won't be good.

→ In this case AL sends $PSH=1$ to TL ~~say~~ saying that transmit the data ~~as~~ as soon as it is received.

Also on receive side when $PSH=1$, data is sent to AL as soon as it is received.

URG (Urgent) Flag and Urgent pointer:

Sometimes it may be needed that ~~some~~ some data has to be sent ~~first~~ first (than other pkts sent by same sender) to the destination.

For this purpose URG flag is given. When $URG=1$ then the pkt is treated ~~as~~ as urgent pkt.

However router doesn't have TL and hence ~~we set priority~~ ~~priority~~ router cannot look into URG flag.

So when $URG=1$ we set priority = 7 in Type of Service field.

→ whether URG has to be set or not is decided by ~~AL~~ AL.

→ when urgent pkt is received, this ^{pkt is} sent to AL first.

Urgent pointer:

- This is used when only some part of segment is urgent, but not all
- Urgent pointer indicates till what part the data is urgent.

Urgent pointer ~~shows~~ tells the offset

$$\text{i.e., last byte of urgent data} = \text{Seq. num} + \text{Urgent pointer}$$

$$\therefore \text{no of bytes in urgent data} = \text{urgent pointer} + 1$$

Note:

- When $\text{PSH} = 1$, data is sent to AL as soon as it is received without buffering.

So the order in which pkts are received will not be changed

- when ~~URG~~ $\text{URG} = 1$, data is sent to AL even before the ~~pkts~~ pkts that are received earlier.

So the order in which pkts are received changes.

RST Flag (Reset):

This is used when there is anything wrong in connection and ^{it is} thus ~~is~~ used to make other host ~~can~~ cautious. This is used whenever something out of normal occurs.

- One situation where ~~is~~ this ^{is} used ^{is} if a receiver is expecting some seq num pkt and if a third party sends some other pkt, ~~then~~ ^{then} receiver assumes something is ~~was~~ wrong and sends a pkt to sender with $\text{RST} = 1$

Window size (or) Advertisement window

→ Used for flow control

→ At the connection establishment stage, ~~this is~~ window size

field is used by receiver to tell its window size to sender.

→ As the communication proceeds, this field is used to tell the sender the available amount of space in receiving window.

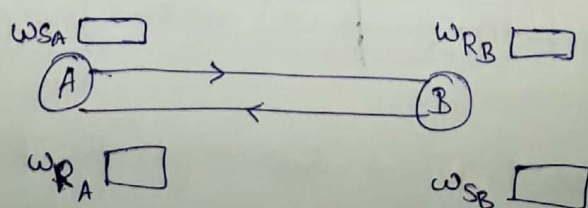
→ If the sender sends data more than the available space, then the data will be discarded.

→ If a window size field is found to be 0 by sender then sender starts a persistent timer and waits until the timer is over or until it ~~receives~~ receives a message from receiver saying its window is free.

→ If it ~~receives~~ sender receives message saying that receiver window is free, then sender sends data.

Otherwise, it ~~sends~~ waits under persistent timer finishes and sends exactly 1 byte data. If sender gets reply with adv as non-zero then it continues with communication, else it will wait again.

→ This persistent timer will be useful in the cases where the message (saying window size is available) sent by receiver is lost

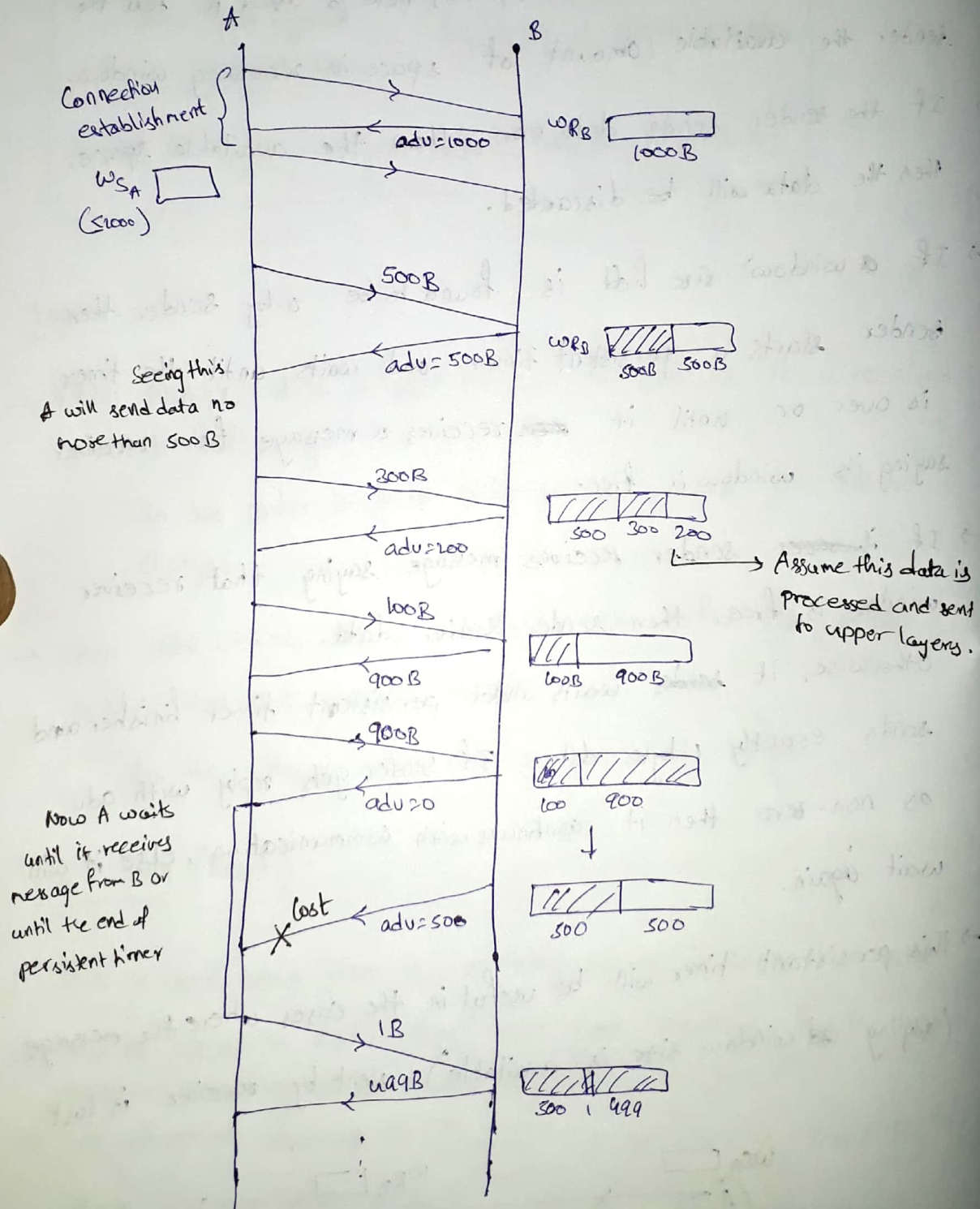


WR_A is known to B and WR_B is known to A at the time of connection establishment.

$$w_{SA} \leq w_{RB} \quad \& \quad w_{SB} \leq w_{RA}$$

Based on the values of w_{RA} and w_{RB} , the station B & A, respectively, ~~sets~~ ^{gender} sets their window sizes.

Consider below case where A sends data to B



Note:

with 16 bit window size field,

the max size that can be advertised is $2^{16} - 1$ Bytes

To overcome this we use extra bits from options.

For example if 1GB window is available

i.e., 2^{30}

then we take 14 bits from options field.

Checksum:

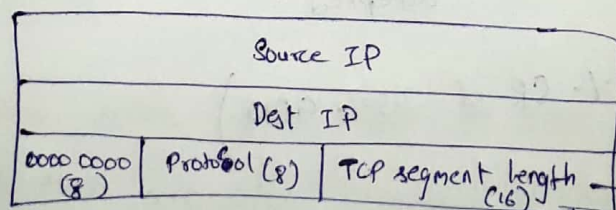
→ The checksum in IP header is computed only on IP header.

→ The checksum in TCP header is computed on IP header, TCP header, data. ~~(segment)~~

But, we calculate ~~this~~ the checksum only on some fields of IP ~~header~~ as many fields ~~are~~ change while the pkt is being transmitted.

→ So in checksum computation we include only those fields of IP header that doesn't change.

~~Checksum~~ Checksum is calculated on below on below fields of IP header (i.e., pseudo IP header)



Total length
- header length

→ The reason behind including IP header in TCP checksum is that we just need to double check that pkt has been delivd to correct host.

Options :

(i) Timestamp : used to increase sequence number bits

It is used when wrap around time $\leq$ life time

The MSB bits of seq num are stored in the timestamp

(ii) window size extension : used when size of window is higher than $2^{16}-1$

(iii) Parameter Negotiation : At the time of connection establishment,

there may be a need to exchange some information. In that case we use this option.

Eg: MSS

(iv) Padding : Used to make header size a multiple of 4.

Retransmissions in TCP

→ TCP uses some characteristics of SR and some of GBN

→ $WS = WP$

→ Out of order pkts are accepted

Cumulative ack are used

$\therefore (75\% \text{ SR \& } 25\% \text{ GBN})$

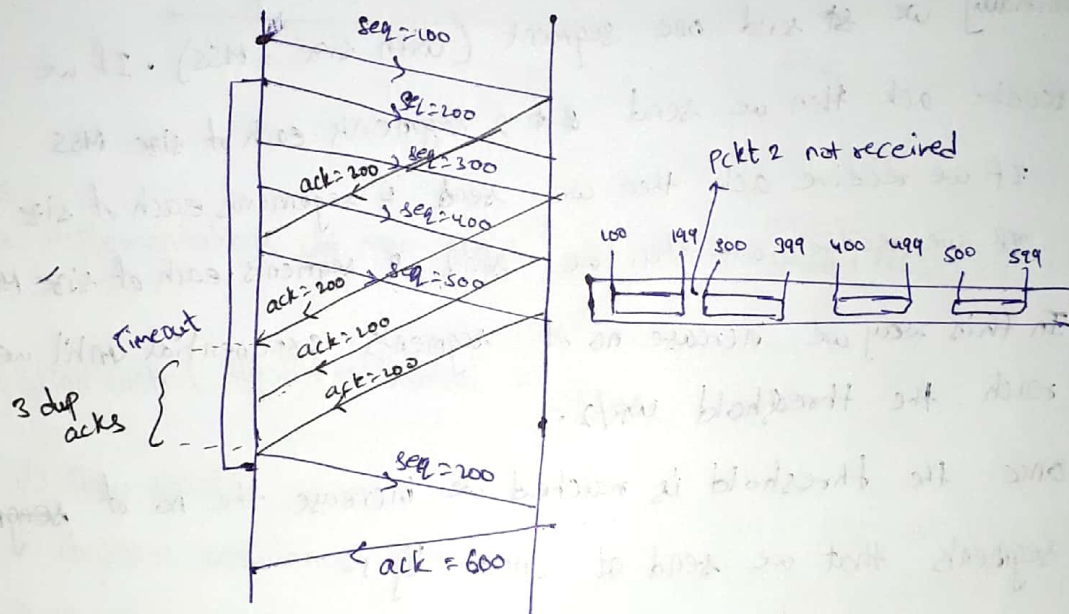
→ In TCP, if ack number received is 'x' then sender assumes that all the data before seq num 'x' is received correctly.

→ TCP uses retransmission after 3 duplicate acknowledgments.

This is also known as Early retransmission.

It means that retransmission done after receiving either 3 duplicate acknowledgments ^{within the timeout} or ~~after timeout~~ retransmission is done after timeout.

For example consider transmitting 5 pkts and ^{say} 2nd packet is lost. Assume size of each segment is 100.



→ Retransmission after timeout indicates that, the duplicate acks are also lost and hence congestion is higher.

Congestion is also indicated by source quench ICMP message.

Congestion Control:

→ If a sender sends pkts ~~more~~ more than the capacity of network then congestion occurs.

→ If capacity of nlw is W_c and receiver window size is W_R then sender window size, $W_s \leq \min(W_c, W_R)$

However there is no chance that we can know the value of w_c .

→ So to meet this problem we use congestion control protocols working:

→ let receiver window side be w_r

we define ~~as per~~ threshold = $\frac{w_r}{2}$

→ Initially we ~~at~~ send one segment (with size = MSS). If we receive ack then we send 2 segments each of size MSS.

If we receive ack then we send 4 segments each of size MSS.

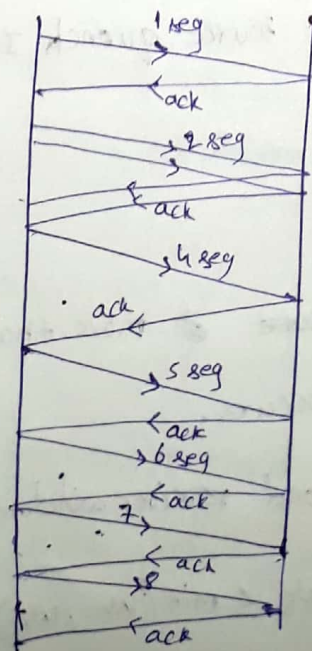
If we receive ack then we send 8 segments each of size MSS.

In this way we increase no. of segments exponential until we reach the threshold $w_r/2$.

→ Once the threshold is reached we increase the no. of ~~send~~ segments that we send at once by 1.

Eg: Assume $w_r = 8$ segments and $w_s = 8$ segments

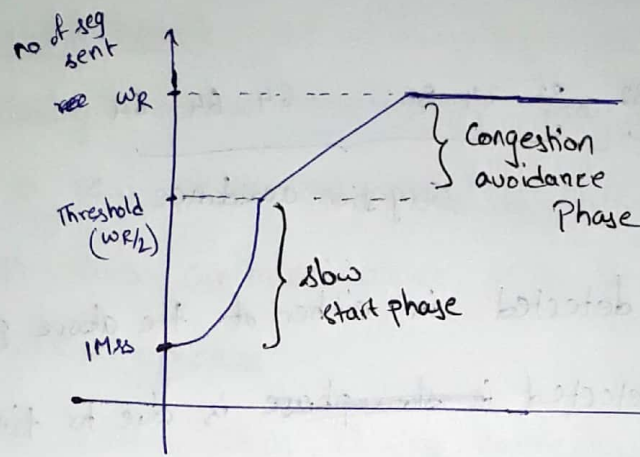
So initially we assume $w_c = 1$ and then increase it



Threshold = $\frac{8}{2} = 4$

145
Q: After how many round trip times did we reach maximum capacity of ~~send~~ received

Ans: 6



Note:

Some implementations ~~we~~ may start with initial $wc = 2$ ~~ms~~ MSS

→ Congestion Control Algorithm involves 3 steps:

- i) Slow start
- ii) Congestion avoidance phase
- iii) Congestion ~~Detection~~ Detection:

Congestion may be detected in slow start phase or congestion avoidance phase.

It is detected in 3 ways

- a) Timeout (congestion is severe)
- b) 3 duplicate acks (mild congestion)
- c) ICMP source quench

But this source quench talks only about one host but not about entire network. So this may not be considered a congestion.

Ex: $w_R = 64 \text{ KB}$

$MSS = 1 \text{ KB}$

$w_R = 64 \text{ MSS}$

Threshold = 32 MSS

$w_c: 1 \ 2 \ 8 \ 16 \ 32 \ 33 \ 34 \ 35 \dots 64 \ 64 \ 64$
Slow phase Congestion avoidance

Congestion may be detected in either of the above phases.

If congestion is detected in ~~slow phase~~ is due to timeout
then ~~threshold =~~

then threshold = $w_c/2$ and enter slow start phase.

If congestion is detected is due to 3 dup ack then

threshold = $w_c/2$ and enter congestion avoidance phase

Ex:

1 2 4 8 16 32 33 34

↑
congestion detected by timeout

$\therefore$ new threshold = $34/2 = 17$ & enter slow start phase

1 2 4 8 16 17 18 19 20

↑
congestion detected by 3 dup pckts

$\therefore$ new threshold = $20/2 = 10$ & enter congestion avoidance phase

10 11 12

↑
congestion detected by timeout

$\therefore$ Threshold = $12/2 = 6$ & enter slow start phase

1 2 (4 6) 7 8 9 10 11 64 64 64

64 64 ↑ 1 2 4 8 16 32 ↑ 16 17 ↑ 1 2 4 8 9 10 11

To Th=32 3dup Th=16 To Th=17/2=8

TCP timer management:

There are 5 types of timers

(i) Time-wait timer:

Closing connection immediately may assign the port number to a new process. Due to this the delayed pkts of previous communication may be ~~given~~ delivered to this new process.

So rather than closing connection immediately, we wait for time-wait timer.

$$\text{Time wait timer} = 2 \times \text{life-time.}$$

→ So time wait timer handles delayed pkts.

(ii) keep alive timer:

This used to close idle connections

↳ These are connections that are opened ~~but~~ but no communication is done.

Everytime a pkt is received, the system restarts keep alive timer. If no pkt is received until keep alive timer ~~ends~~ ends, then the station sends 10 probe messages. If no reply is received then we close the connection.

(iii) Persistent timer:

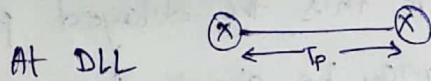
~~when~~ This is used ~~when~~ when a station receives window size of 0 from other host. After this timer we sender 1 byte to test if the window is free.

(iv) Acknowledgment timer:

This used to send cumulative acknowledgments.

Also using this we can wait until data is ready and thus implement piggybacking.

(v) Timeout timer



$$\text{Round trip time} = 2 \times T_p$$

$$\text{Timeout} = 2 \times \text{RTT}$$

But at transport layer deriving and finding $2 \times \text{RTT}$ in this way won't be easy. The path, traffic may change dynamically.

Hence the timeout timer at TCP also has to be dynamic.

→ Having a static TO timer may lead to congestion.

Consider a case where traffic is high but there is congestion.

If TO is small and fixed (static) then we will keep on retransmitting again and again causing congestion.

→ when TO is too high, we wait a lot of time for retransmission and it is a time waste.

There are 2 algorithms for TO timer

(i) Basic algorithm

(ii) Jacobson's algorithm

Basic Algorithm:

Initially we predict RTT (say IRTT) and set $\text{TO} = 2 \times \text{IRTT}$.

Assume we received ack after some time and we say

~~this~~ this is actual RTT (say ARTT). Using IRTT

and ARTT we predict NRTT (next RTT)

$$NRTT = \alpha (IRTT) + (1-\alpha) ARTT$$

- $\alpha = 1 \Rightarrow$ algorithm is static
- $\alpha > 0 \Rightarrow$ algorithm is fully dynamic

α is called smoothing factor.

Eg: let $IRTT = 10 \text{ ms}$ & $\alpha = 0.5$

$$\Rightarrow TO = 2 \times IRTT$$

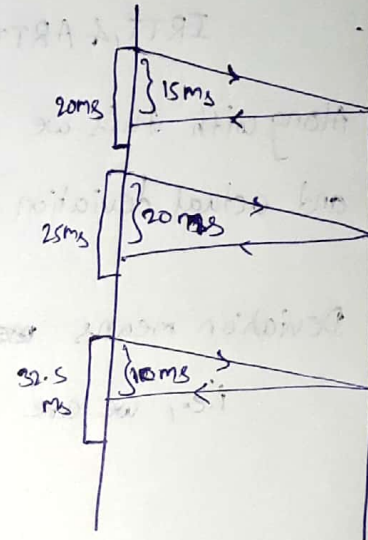
$$= 20 \text{ ms}$$

let $ARTT = 15 \text{ ms}$

$$\Rightarrow NRTT = 0.5(10) + 0.5(15)$$

$$= 25/2$$

$$\Rightarrow \text{new TO time} = 25 \text{ ms}$$



Now for 2nd transmission

$$IRTT = 25/2 \text{ ms}$$

$$ARTT = 20 \text{ ms}$$

$$2) NRTT = 0.5(25/2) + 0.5(20)$$

$$= 6.25 + 10 = 16.25$$

$$\Rightarrow TO = 32.5 \text{ ms}$$

Now for 3rd transmission

$$IRTT = 16.25 \text{ ms}; ARTT = 10 \text{ ms};$$

$$NRTT = 13.125 \text{ ms}$$

$$\Rightarrow TO = 26.25 \text{ ms}$$

Note:

$\rightarrow$ Here $NRTT$ depends on entire history of $RTTs$ but previous $RTTs$ have lesser weights.

Disadv: The disadv with this algorithm is that $TO = 2 \times RTT$ i.e., we always multiply RTT with a fixed number (2)

Jacobson's Algorithm:

→ This algorithm overcomes the disadvantage of basic algorithm

$$\text{i.e., } T_O = 2 \times R_{TT}$$



Using this has no logic & reason.

→ Here also we have

∴ IR_{TT} & AR_{TT}

Along with this we define 2 new parameters initial deviation (ID) and actual deviation (AD) and next deviation (ND).

Deviation means ~~the~~ error in our guess of R_{TT} .

i.e., we are expecting AR_{TT} to be in range

$$[IR_{TT} - ID, IR_{TT} + ID]$$

~~AD~~ AD is actual observed deviation

ND is predicted deviation for next transfer

$$ND = \alpha(ID) + (1-\alpha)ND \quad \& \quad AD = |IR_{TT} - AR_{TT}|$$

→ Here timeout is given by

$$T_O = \underbrace{(4 \times D)}_{\text{deviation}} + R_{TT}$$

This is experimentally found to give better results.

Eg: Let $IR_{TT} = 10 \text{ ms}$ $ID = 5 \text{ ms}$, $\alpha = 0.5$

for 1st transmission:

$$T_O = 4 \times D + R_{TT} = 30 \text{ ms}$$

$$\text{let } AR_{TT} = 20 \text{ ms}$$

$$AD = |IR_{TT} - AR_{TT}| = 10 \text{ ms}$$

$$\Rightarrow NRTT = 0.5(10) + 0.5(20) \\ = 15 \text{ ms}$$

$$ND = 0.5(5) + 0.5(10) \\ = 7.5$$

for 2nd transmission:

$$IRTT = 15 \text{ ms} ; ID = 7.5 \text{ ms}$$

$$\therefore T_0 = 4(7.5) + 15 \\ = 45 \text{ ms}$$

$$\Rightarrow \text{let } AD = 30 \text{ ms}$$

$$\Rightarrow AD = |15 - 30| = 15 \text{ ms}$$

$$\Rightarrow NRTT = 0.5(15) + 0.5(30) \\ = 22.5$$

$$ND = 0.5(7.5) + 0.5(15) \\ = 11.25$$

Note (Karn's Modification):

→ Neither of ~~basic~~ the two algorithms talk about the case where ack is not sent within the timer.

i.e., These algorithms don't tell what should be the initial prediction of timeout for retransmission.

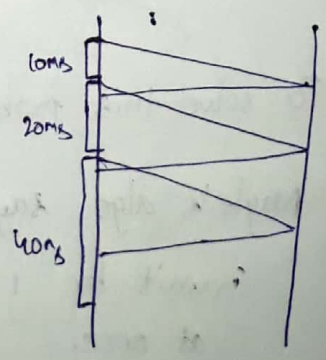
→ Karn's modification to Jackson's algorithms

says, whenever retransmission is required

set T_0 to double of the previous T_0 .

whenever you receive ack in time, you can

continue with ~~the~~ normal jackson's algorithm

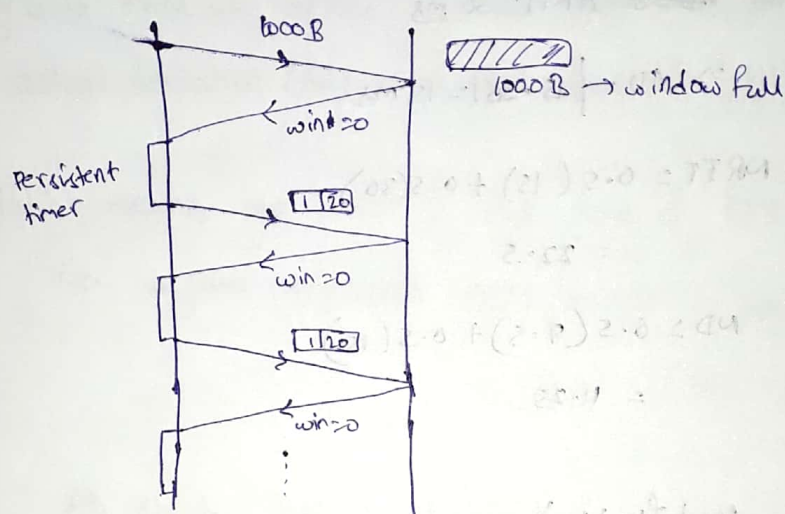


Silly Window Syndrome:

→ we say silly window syndrome problem occurred in 3 cases

- i) Receiver ~~always~~ advertises that its window size is 0 for certain amount of time.

But this problem is temporary and will be solved once window is available.



In this case, we use RST flag and restart the connection.

- ii) Second case where this problem occurs is when sender is slow and transmitting less amount of data (say 1 byte) at once. This means for 1 byte, $(1 + \underbrace{20 + 20 + 20 + 20}_{80})$ 81 bytes have to be transmitted.

TCP, IP headers
on sender side
header on
receiver side
for ack.

To solve this problem we use Nagle's algorithm

Nagle's algo says

- wait for 1 RTT and send the data produced in 1 RTT at once.

- ii) If data sufficient for 1 MSS is produced in less than 1 RTT then transmit it. $\downarrow$

(iii) Another case in which this problem occurs is that when receiver accepts only one byte of data repeatedly (i.e., receiver advertises its window size as 1)

Clark's solution for this problem:

Receiver should not advertise until it gets freed ~~half~~ half of the window or until it gets freed 1 MSS size of buffer

Traffic Shaping:

- Another method of congestion control is to shape the traffic before it enters network.
- Traffic shaping control the rate at which the pkts are sent.
- During connection establishment, the sender and carrier negotiate a traffic pattern (shape)

Traffic shaping is done using 2 algorithms:

- i) Leaky bucket
- ii) Token bucket

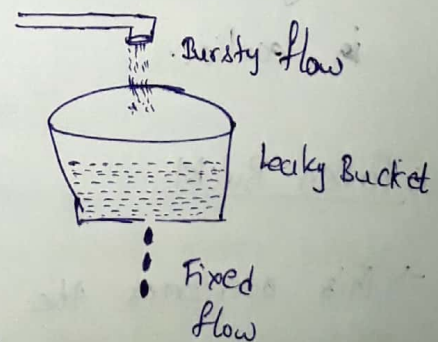
i) Leaky Bucket:

Here bucket corresponds to queue.

~~This is~~

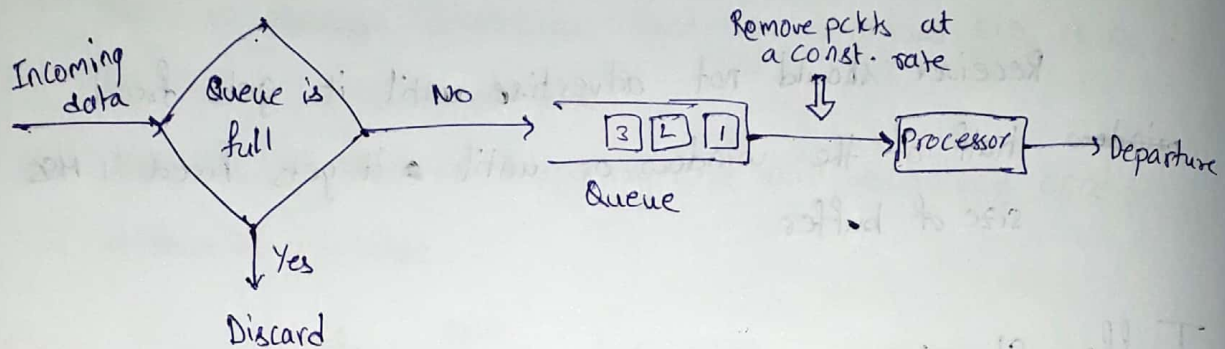
Data may come into queue at any rate
But it is taken out and put on the network at a constant rate.

~~However the bucket~~



However the bucket (queue) has some capacity.

If ~~data~~ bucket is full and new data comes in, the new data is discarded



→ Here required outflow is $\mu \times$ bytes per second and if pkt size is of variable length, then we use a counter to count no of bytes in queue and transmit req no of bytes.

Disadv :

→ If a station doesn't transmit data for long time and if it needs to transmit after sometime, still the station will have same outflow rate and no extra rate will be given for the reason that the station didn't transmit earlier.

ii) Token Bucket

→ This overcomes the disadv of ~~token~~ leaky bucket.

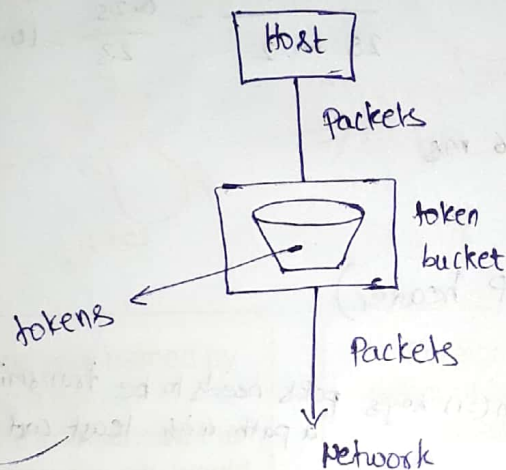
→ Each pkt needs a token to get on the network.

→ Here we maintain a token bucket to which tokens are

added at a fixed rate.

→ In this way even if a system doesn't transmit for long time and need to transmit later, it ~~can~~ can use the tokens and transmit packets (one per each token)

→ However, token bucket also has a capacity. ~~while~~ once token bucket is full, no more tokens will be added.



→ If ~~maximum~~ capacity of token bucket is c tokens and tokens enter bucket at rate of g token/sec, then find max no of pkts that can enter network during time interval t is _____

$$\text{Max no of packets} = c + gt$$

$$\Rightarrow \text{Max avg rate} = \frac{c + gt}{t} \text{ pkts/sec}$$

For large value of t , max avg rate $= g$

Q) Token bucket capacity = 250 KB; tokens arriving rate = 2 MB/s
If maximum output rate is 25 MB/sec, then find burst time.

Sol,

Since given token capacity = 250 KB

→ each byte is a token

Burst time is duration in which we send 25 MB

$$\therefore \frac{C + rt}{t} = M$$

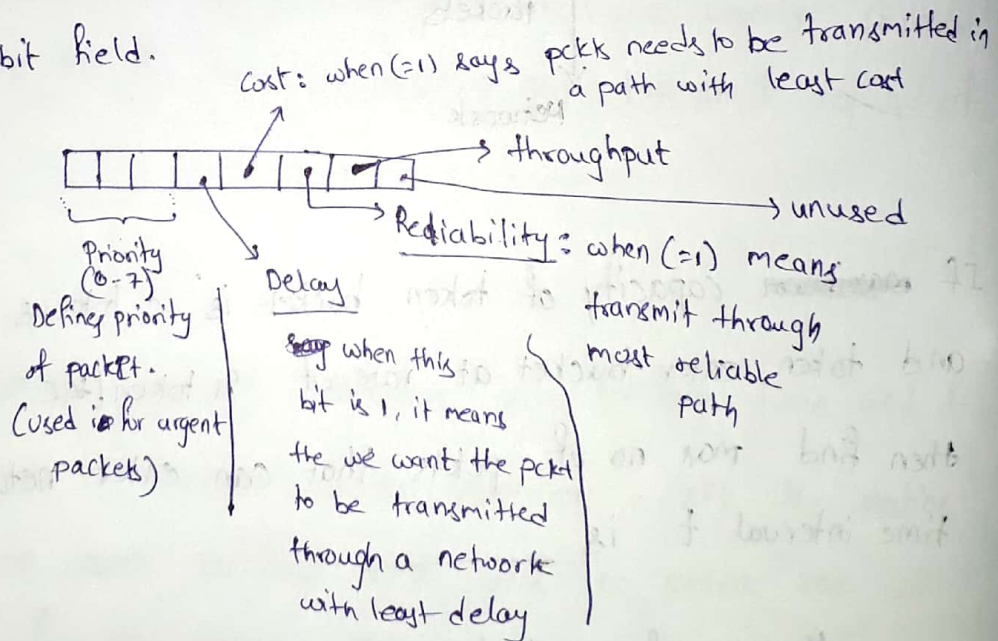
$$\Rightarrow C + rt = Mt \Rightarrow t = \frac{C}{M - r}$$

$$t = \frac{250 \times 0.25}{25 - 2} = \frac{0.25}{23} = 10.86 \text{ ms}$$

$\therefore$ Burst time = 10.86 ms

Type of Service (field in IP header)

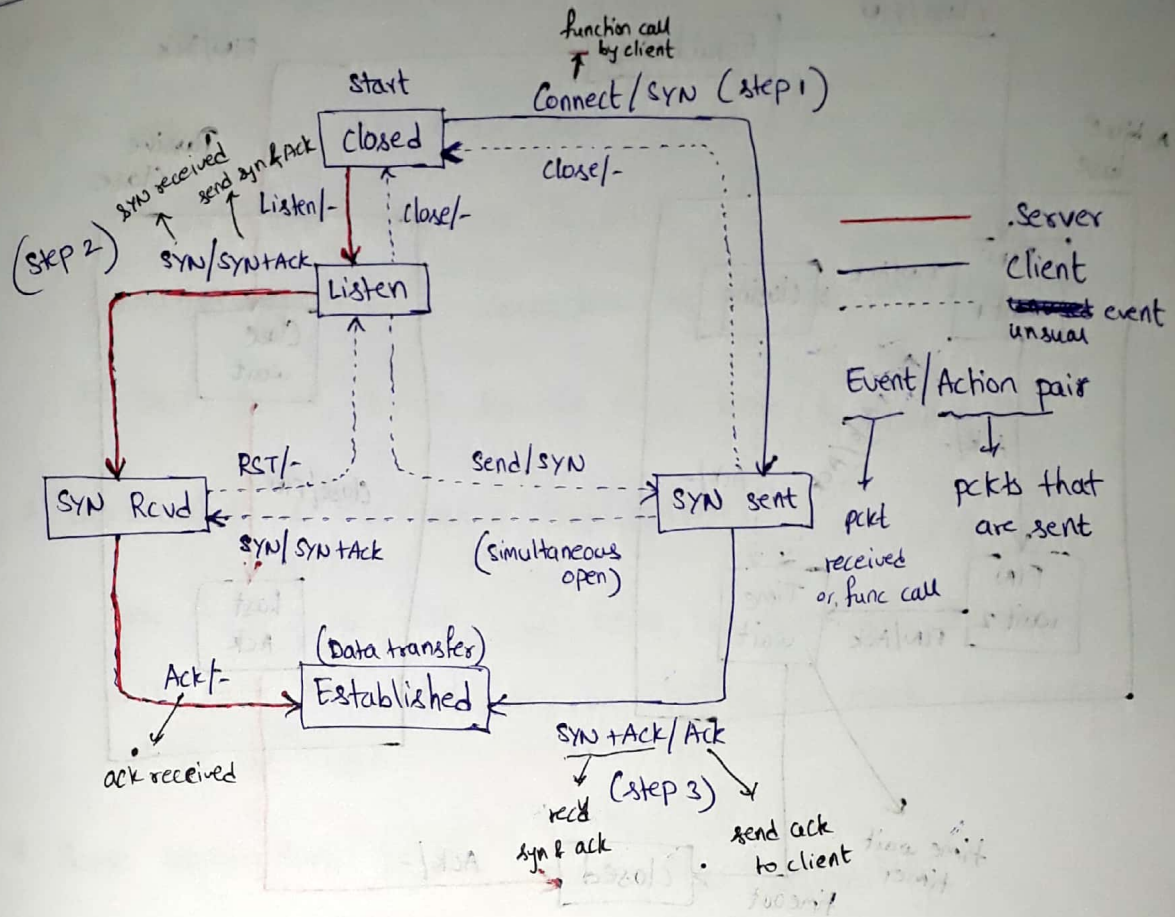
→ It is 8-bit field.



→ when throughput = 1, it means that packet has to be transmitted through a network where throughput is high

16/12/20

TCP State transition diagram: Connection Establishment



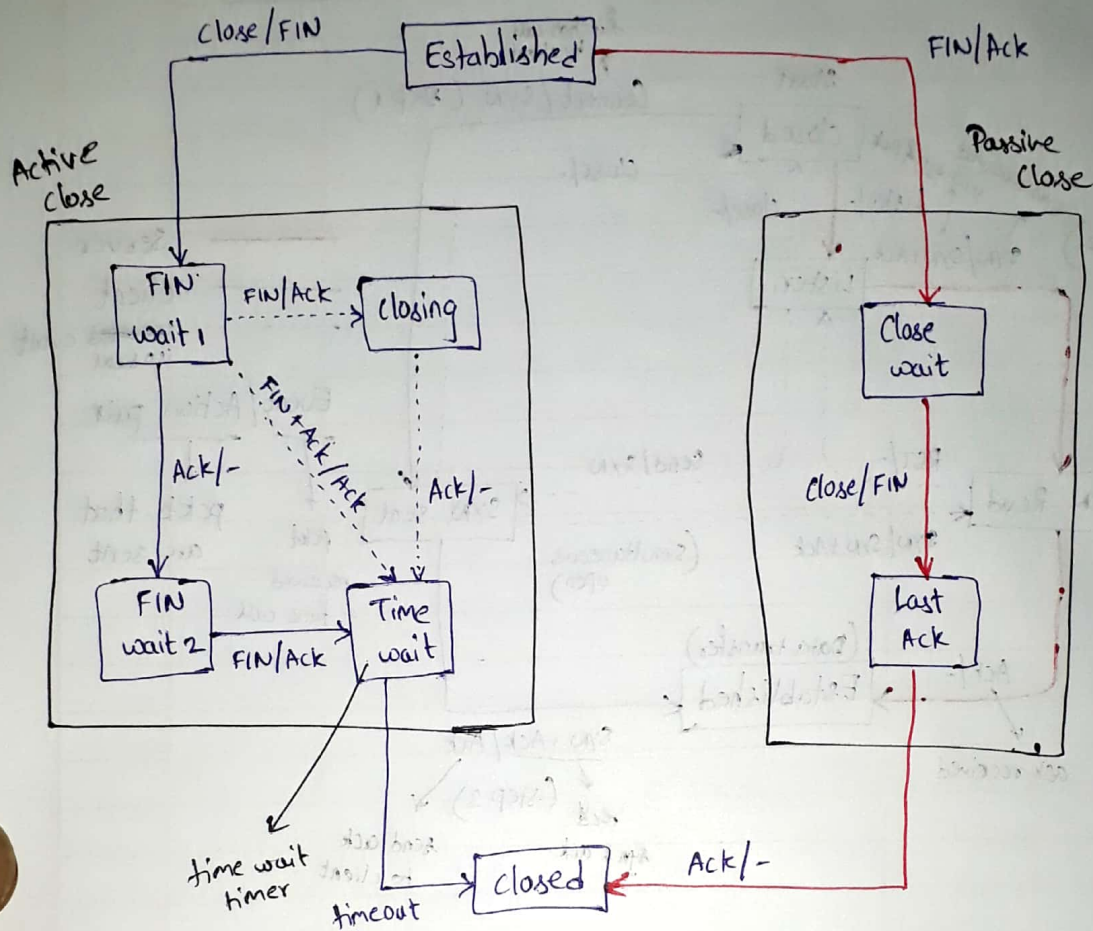
→ At "syn sent" state, if client doesn't receive (syn + ACK) for long enough time, then client executes close system call and moves to "closed" state.

→ At "Listen" state, if server doesn't receive any connection requests then server executes close and moves to "closed" state.

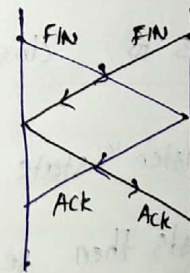
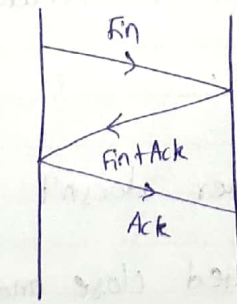
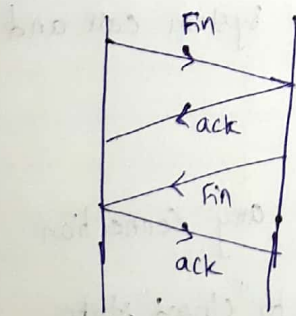
→ At "syn Rcvd", if server finds any problem, it ~~calls~~ calls reset and terminates the connection.

→ Sometime server may initiate connection. In this case server at "Listen" state sends syn. Then client at "syn sent" sends (syn + ACK) on receiving syn from server. This is called Simultaneous open as both server & client want to open connection at a time.

TCP state transition diagram: Connection Termination



Termination of connection may happen in any of below way



First FIN & Ack are sent at a time by server

Both ~~the~~ client & server sends FIN at a time

All the above cases are shown in the transition diagram.

UDP (Null Protocol)

→ Need for UDP:

* In applications that need one request & one reply.

when we need only one request & one reply, the connection establishment, connection termination are overheads

Eg: DNS, BOOTP, DHCP, Routing algorithms (for sharing DV)

* Broadcasting & Multicasting applications.

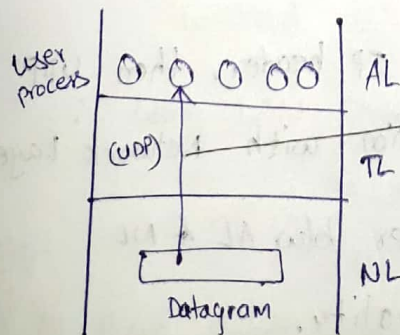
Here if we use TCP, we need to establish connection with each host and reserve buffers for each connection.

∴ we use UDP.

* Some applications require speed than reliability.

~~Using~~ TCP applies end to end congestion control due to which speed fluctuates.

Eg: Multimedia applications (watching videos)
Online Gaming etc..

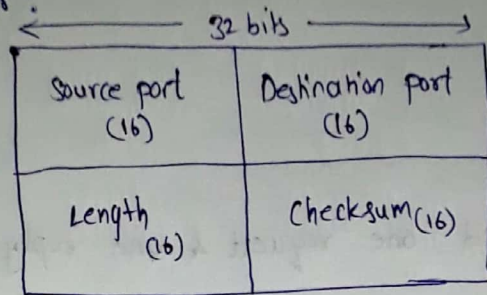


The received data gram is directly given to processes in AL bypassing the services of transport layer.

→ UDP header doesn't need seq num, ack, window size, flags, urgent, pointer, options.

∴ no flow ~~flow~~ control

UDP header :



Header size = 8 bytes

UDP has fixed header size

length: length of datagram including header

Checksum: Checksum is computed on UDP header, UDP data, & pseudoheader of IP.

→ Since UDP is ~~un~~ unreliable, checksum may not be used.
When checksum is not used it is set to (000...0)

→ However, if the computed checksum itself is 000...0
then we store 111...1 in checksum.

• Checksum is stored in 1's complement form

∴ If 0 is represented as 000...0 ⇒ checksum not used

0 is represented as 111...1 ⇒ checksum is used

Other functionalities of UDP:

→ If AL wants to set options in IP header, then UDP has to communicate this information with Network Layer.

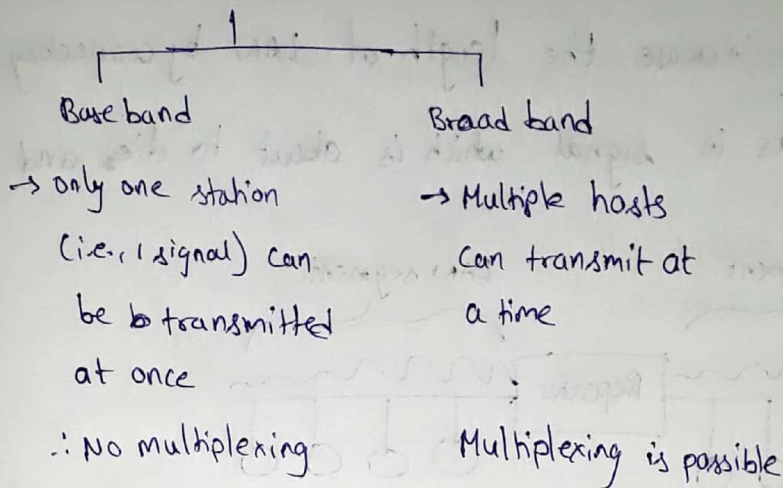
i.e., UDP has to act as messenger b/w AL & NL

TCP also has this functionality.

→ ICMP pkts received at IP has to be informed to AL through UDP

Hardware and other devices used in Networking

→ 2 types of channels



→ The wires come in different types. Few are shown below.

* 10 Base T (10 Mbps, No multiplexing, 100m)

* 10 Base 2 (10 Mbps, " 200m)

* 10 Base 5 (" " 500m)

* 100 Base T (100 Mbps, " 100m)

→ The third field is distance for which the wire can run.

The i.e., It is max distance for which signal can be transmitted without attenuation.

∴ LAN Segment with 10 Base T can range only for 100m
↳ LAN connected to one wire

Note:

(i) All these wires operate at PL.

(ii) Attenuation is possible for all.

(iii) Collisions are possible.

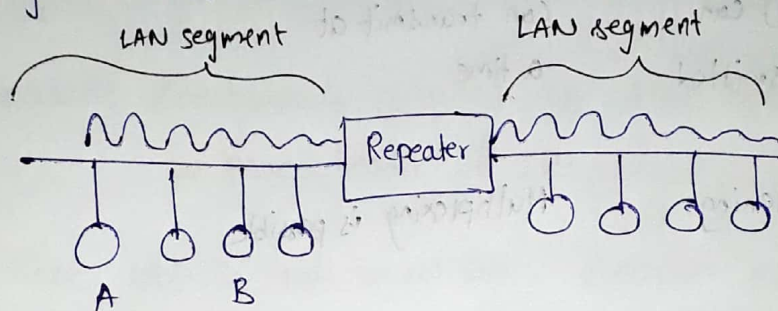
Collision Domain is n.

i.e., no of stations involving in collision

Here length of LAN depends on the type of wire.

Repeater:

- This is used to increase the length of LAN by connecting 2 LAN segments.
- Repeater takes in signal which is about to die and regenerates it



- Even if A want to send data to B, ~~and~~ repeater still sends data to other side.
- The LAN segments connected to repeater must be of same type. i.e., both should be ethernet or both should be token ring.
- Repeater is different from amplifier. Amplifier increases the amplitude whereas repeater just regenerates the original signal

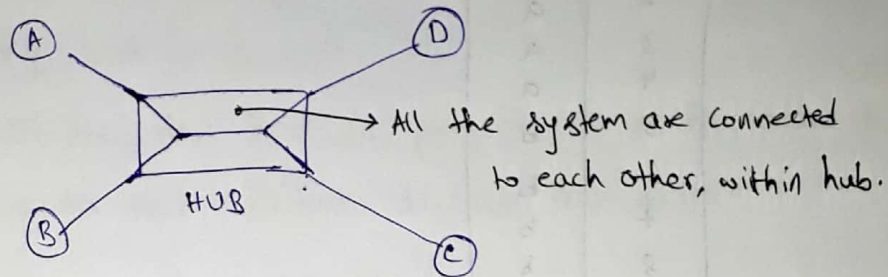


- Repeater runs at PL
i.e., repeater is purely hardware.
- Collisions are possible in repeater and hence all the stations in the network are in one collision domain.
∴ Repeater doesn't reduce collision domain. i.e., non

Hub:

→ Hub is a multi-port repeater.

→ For example, a 4-port hub can connect 4 stations



Here if B needs to transmit a packet to A, the packet will be transmitted to every station

∴ Traffic is very high

→ HUB has only PL.

→ Collision are possible inside hub.

Collision Domain = n

∴ Hub doesn't decrease Collision Domain.

Adv: Hub is cheaper.

Bridge:

→ Bridge is used to connect 2 LANs

(Repeater connects 2 LAN segments of same LAN)

→ If a bridge has n ports, then it can connect n LANs.

→ Also the 2 LANs connected by bridge may be different

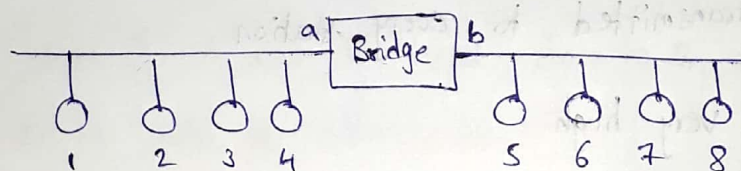
i.e., one may be ethernet and other may be token ring.

→ Bridge operates at PL & DLL

→ Since bridge works at DLL, it can look in MAC addresses.

→ Every bridge has a forwarding table.

MAC	Port
1	a
2	a
3	a
4	a
5	b
6	b
7	b
8	b



Bridges

- Static Bridges
- Dynamic / Learning / Transparent bridge.

Static Bridge :

→ Here the forwarding table is static and whenever we need to make a change in the network we need to change the table manually.

Dynamic Bridge :

- Here bridge will learn the MAC & port of a station.
- Whenever a station transmits data, the data reaches bridge and thus bridge will understand the MAC of the station and puts an entry in the forwarding table

→ But dynamic bridge never knows the MAC address of a host which has never transmitted any data.

→ Bridge is capable of filtering ($\because$ Bridge has DLT)

i.e., It sends a pkts to ~~the~~ ^{LAN} ~~that~~ in which the req host is present.

If the dest host is present ~~in~~ in the ~~same~~ N/w sender then bridge discards the pkt.

→ Bridge is capable of Forwarding.

i.e., sending data from one N/w to other N/w.

→ If a bridge doesn't know where the destination is present, then it floods the pkt.

$\therefore$ Bridge is capable of Flooding.

→ Bridge is capable of store & Forward.

Since it can store, collisions ~~can be~~ b/w hosts of diff N/w are not possible.

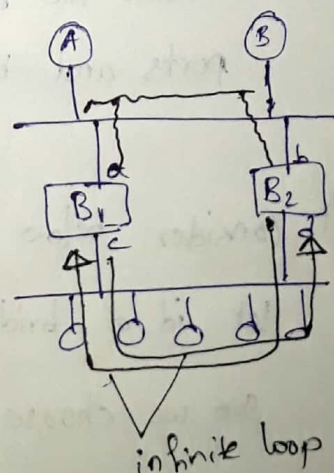
$\therefore$ Collision Domain is reduced.

Problems with bridges

→ If we connect two lans using 2 bridges, and assume initially forwarding table is ~~in~~ empty.

Now if A send data to B, this sent pkt is fall in infinite loop.

Another problem is that port of A with ~~sh~~ keeps on changing from a to c & c to a.



→ If MTU of LANs connected, is different, then bridges cannot do the job of fragmentation.

So the fact that bridges can connect different types of ~~to~~ N/w is ~~more~~ theoretical but not much practical.

17/12/20

Spanning Tree Algorithm:

→ This algorithm is used to avoid infinite loop that pkts fall into, when two ~~to~~ LANs are connected by more than one bridge.

Algo:

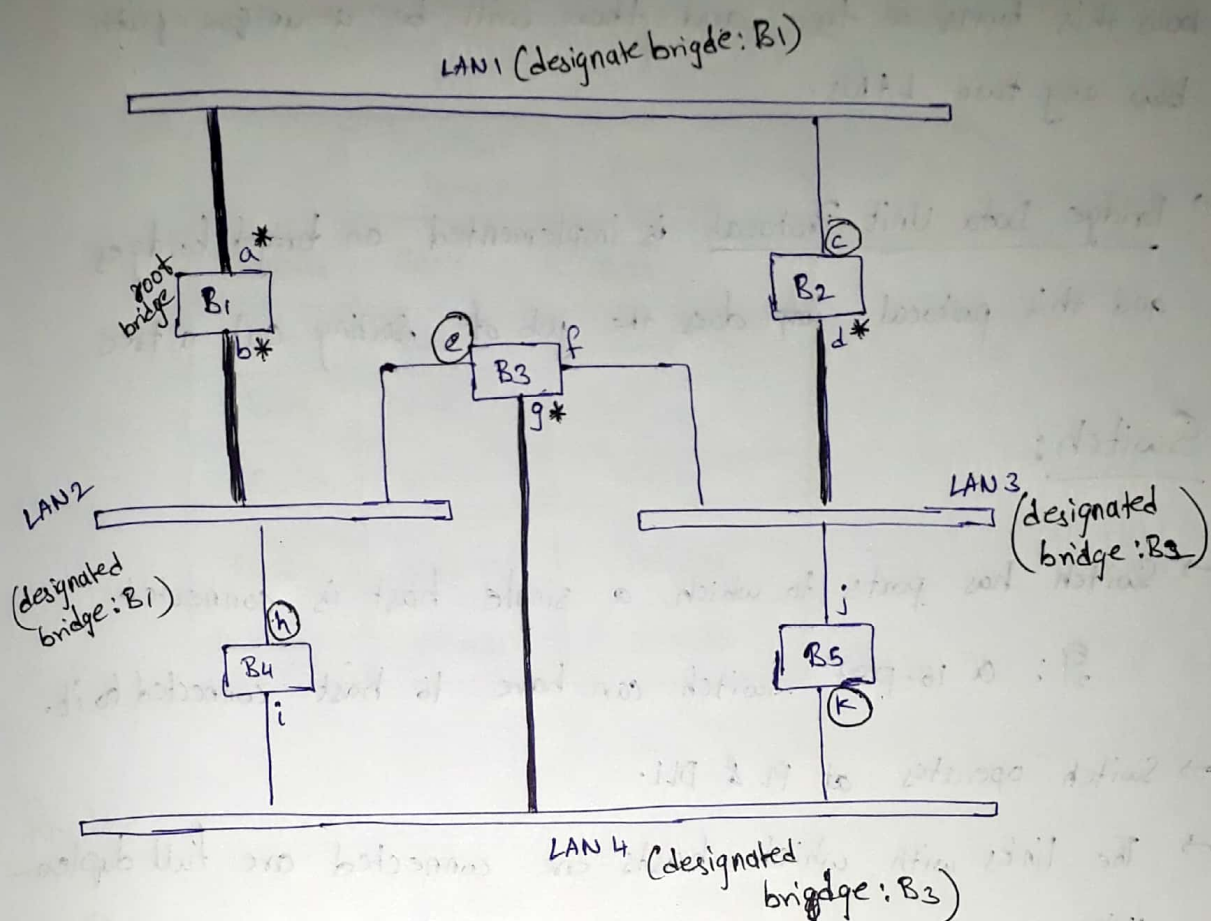
- (i) Every bridge has a built-in ID. The one with smallest ID is taken as root bridge.
- (ii) Mark one port of each bridge which is closest to root bridge as root port.
- (iii) Every LAN chooses a bridge closest to ^{root bridge} ~~to~~ as a designated bridge for that LAN. make the corresponding port as designated port.
- (iv) Mark the root port and designated port as forwarding ports and block remaining.

Eg: Consider below N/w with 4 LANs and 5 bridges.

let id of bridge B_i be i .

So we choose B_1 as root bridge.

→ Here closest is defined with some cost parameters.
Here we consider no of hops

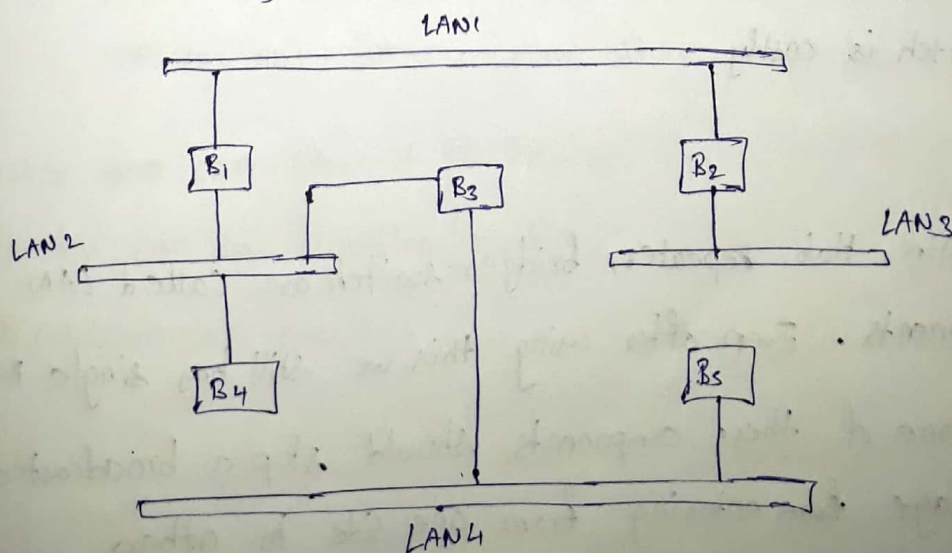


→ Root ports are encircle.

→ when ~~two~~ there is a conflict in choosing designated bridge, choose the bridge with least id.

—— (thick line) — line that ~~for~~ connects LAN & designated port (*)

→ Now we use root port & designated ports as forwarding port and block remaining



now this forms a tree and there will be a unique path b/w any two LANs.

→ Bridge Data Unit Protocol is implemented on ~~bridge~~ bridges and this protocol ~~is~~ does the job of sorting out a tree

Switch:

→ Switch has ports to which a single host is connected.

Eg: a 16-port switch can have 16 host connected to it.

→ Switch operates at PL & DLL.

→ The links with which hosts are connected are full duplex links.

→ Switch is designed in such a way that it can allow more than one communication occur at a time. Switch can forward pkt to crct host. (∵ it has DLL)

→ ∴ No collisions are possible using a switch.

Collision Domain = 0

→ Traffic is less with switch.

Disadvantage:

→ Switch is costly.

Note:

→ ~~wire~~ wire, Hub, repeater, bridge, switch are called LAN components. Even after using this we still have single N/w. So none of these components should stop a broadcasted message from entering from one side to other.

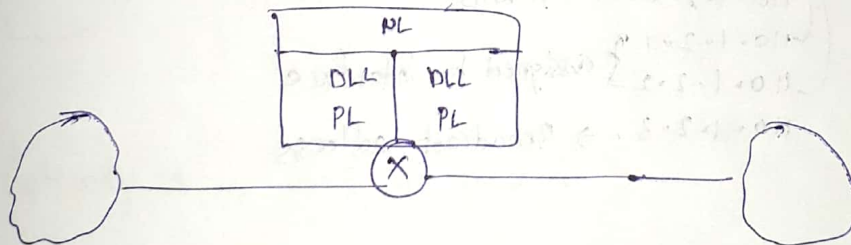
∴ These components doesn't change broadcast domain.

	Broadcast Domain	Collision Domain
Repeater	Same	Same
Hub	Same	Same
Bridge	Same	reduces
Switch	Same	reduces
Routers	reduces	reduces
Gateway	reduces	reduces

Router:

→ Router is a device used to connect 2 networks

→ Router has PL, DLL, NL



→ Router does the job of filtering

i.e., broadcast, BootP, DHCP, ARP etc. are discarded and are not let to cross other networks.

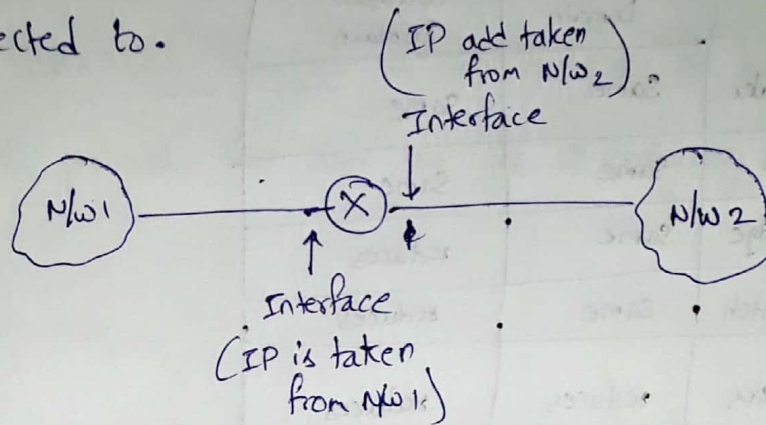
→ Router can store & forward.

→ Router can do flooding/routing.

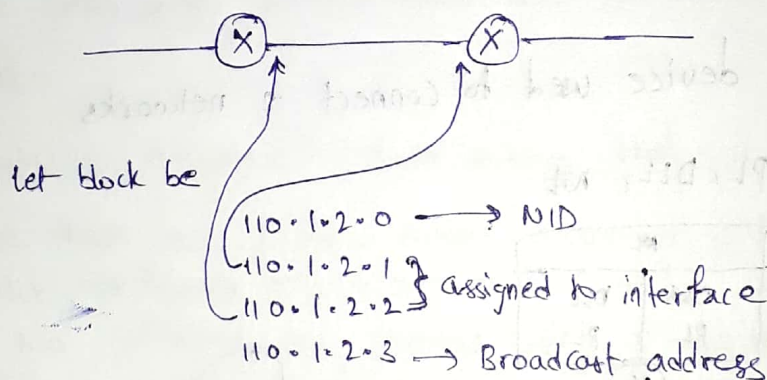
→ No collision are possible within a router

→ Every interface of router has an IP address.

The IP address is taken from ~~one~~ the N/w that router is connected to.



→ However if two routers are connected, then we need to ~~buy~~ buy a block of IP add of size 4.



Gateways

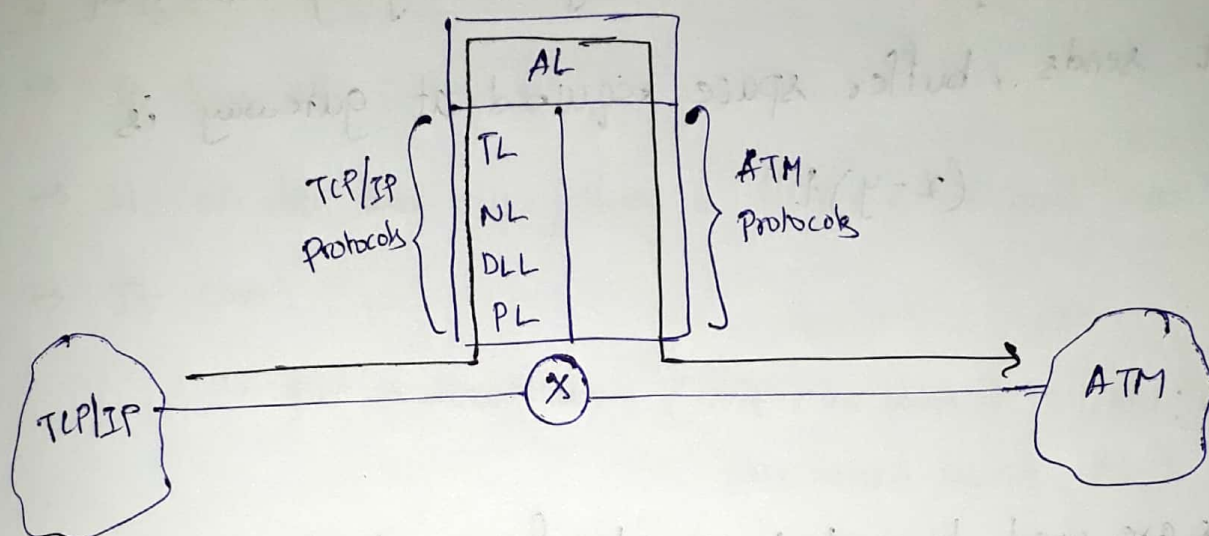
Router is capable of connecting similar type of N/ws;

i.e., two TCP/IP N/w or two ATM N/ws

but not a TCP/IP and an ATM N/w

→ ~~It is~~ For this need we use Gateways.

→ Gateway is used as protocol converter.



→ Gateway is used as proxy.

* A proxy can monitor every packet that is going out of the network.

* Proxy also does the job of buffering / caching

↓
i.e., recent accesses are stored.

→ Gateway is used as NAT server

↳ used to conserve IP addresses.

→ Gateway is also used as firewall.

Firewall monitors every incoming & outgoing packets and can impose some restrictions.

→ Another use of Gateway is Deep Packet Inspection (DPI)

DPI helps look into application layer data and thus know what data is being transmitted and can also impose some restrictions.

→ Gateway also does buffer management.

If data coming from other end is too fast, then gateway can buffer the data and sends us data at required rate.

* If x is incoming rate of data & y is outgoing rate then for t seconds, buffer space required at gateway is

$$(x-y)t$$

Firewalls:

→ Firewalls are used to protect a network from outside internet.

→ Any incoming/outgoing packets has to go through firewall.

Firewalls are of 3 types

(i) Layer 3 Firewall

(ii) Layer 4 Firewall

(iii) Layer 5 Firewall / Proxy

Layer 3 Firewall:

→ It has PL, DL, NL

This firewall can

(i) Block hosts (using SIP, DIP)

(ii) Block certain protocols (TCP, UDP, ICMP, IGMP)

Block ICMP can save from ICMP attacks.

iii, A protocol from particular host can be blocked.

Layer 4 Firewall:

→ It has PL, DLL, NL, TL

→ It can do everything a Layer 3 Firewall can do

→ It can:

i) Block a service (by looking into port number)

ii) Block a particular service from particular host.

Layer 5 Firewall / Proxy Firewall:

→ It has all 5 layers.

→ It can do ~~any~~ everything a layer 4 firewall can do.

→ It can:

i) give authentication (∵ it can look into username & password using AL)

→ Here a rule table is maintained.

A pkt is discarded if it matches ~~which~~ with atleast one rule.

Application Layer Protocols

→ DNS, HTTP, FTP, SMTP, POP

DNS (Domain Name Service)

→ port No: 53

→ Given a domain name, DNS gives its IP address.

Even if we remember IP add, there is no guarantee that the IP address of a website doesn't change

Types of domains:

i) Generic Domain:

• Com, • edu, • mil, • org, • net
↓ ↓
used by used by non-profit
Commercial organization organization

(ii) Country Domain:

- in, • us, • uk

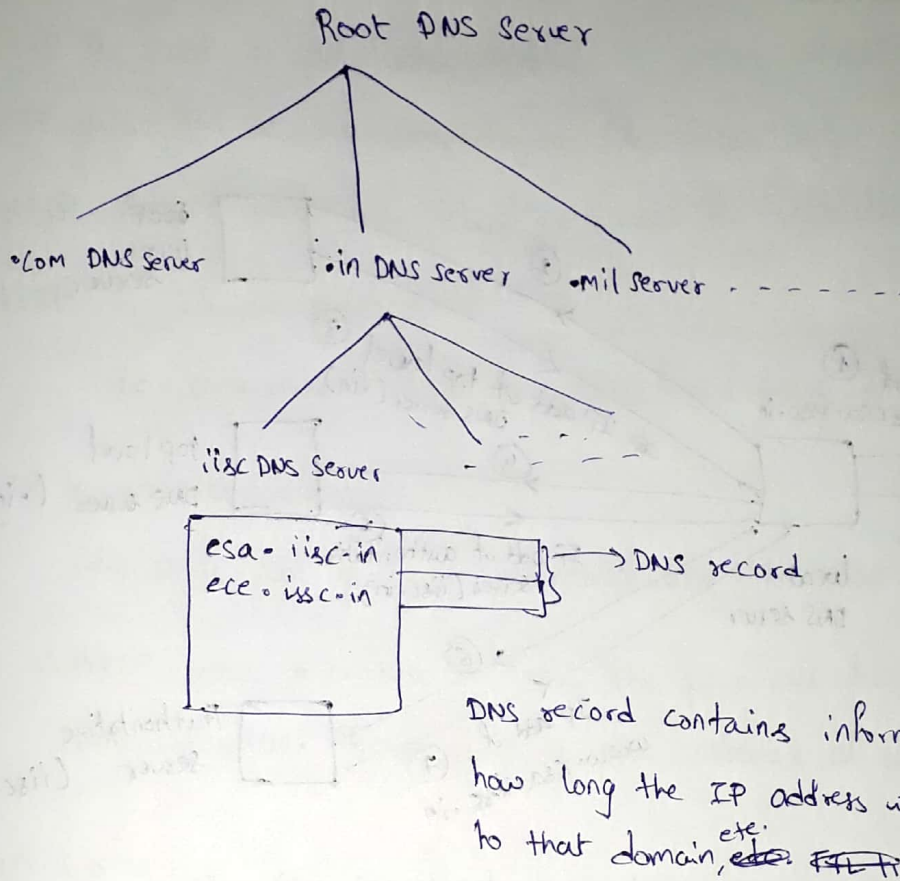
ciii) Inverse Domain:

Given an IP address, DNS can also give domain name.

→ DNS also does load balancing.

i.e., if a ~~do~~ website have more than one IP add (more than one server) then each time we access the website it will take us to a different server.

Data organization in DNS



→ Data of DNS is distributed.

→ There are 13 root DNS server

So that even if one server doesn't work there will be no problem

Note :

→ However, we don't need to go to Root DNS server everytime.

→ ISP provides local DNS which has most frequently used websites.

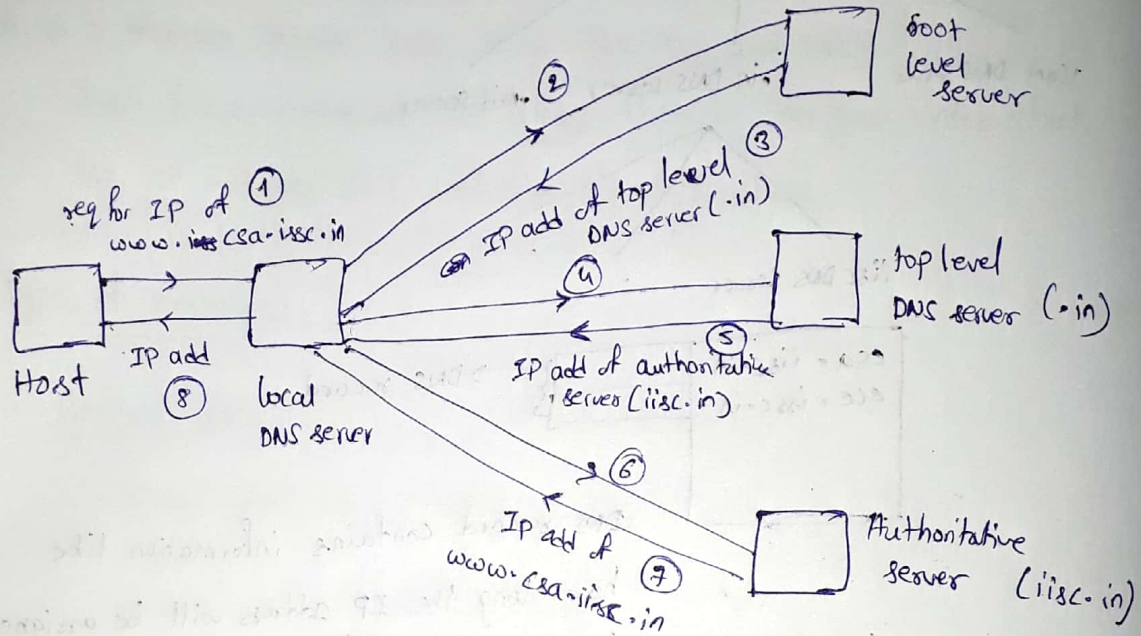
If local DNS can't help then we go to root DNS server.

→ The record of local DNS has a field ~~IP~~ Time to Live, after which entry is deleted.

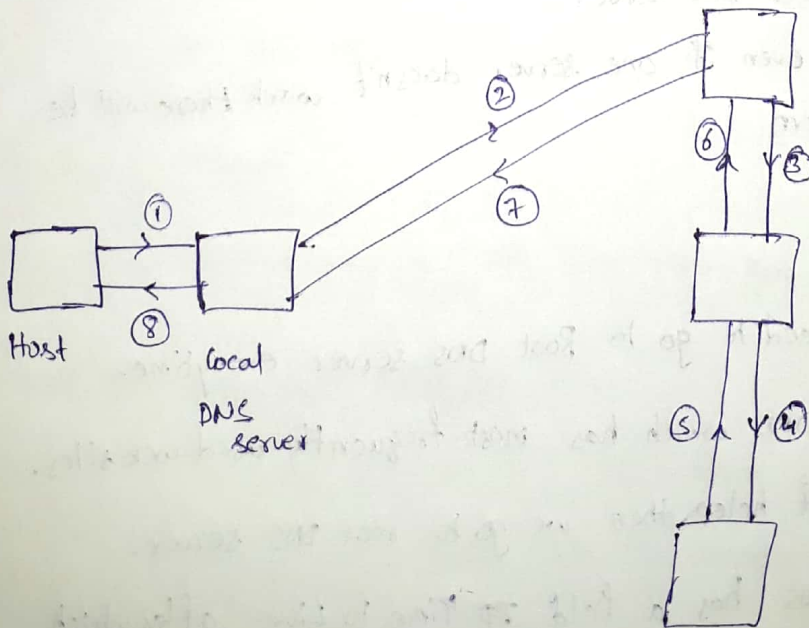
There are 2 ways through which local DNS contacts root DNS server.

- i) iterative
- ii) recursive.

Iterative:



Recursive:



→ ~~All~~ DNS uses UDP (since all the messages are single req & reply)

HTTP:

→ port number: 80

→ HTTP is used to get web pages.

→ HTTP uses TCP at transport layer (for reliability)

HTTP doesn't have any inbuilt mechanism for reliability.

→ HTTP is inband protocol.

i.e., commands & data are transferred using same connection.

→ HTTP is stateless protocol.

i.e., It is not going to maintain any information abt users

∴ HTTP uses cookies to know the previous history of communication. These cookies are stored at user's end.

→ HTTP 1.0 uses non-persistent connection

i.e., a separate connection is used to fetch each object.

For example if a web page has 10 image, we used 11 connections (one for each image & one for web page)

Here server doesn't need to hold connection for long time.

→ HTTP 1.1 uses persistent connection.

i.e., a single connection is used to fetch all the data.

Here server holds connection for long time. So here congestion window grows and thus we have high BW.

Methods used in HTTP:

i) Head: used to obtain header (meta data) of a webpage.

Usage: Gateway caches frequently used data.

So by getting head, gateway knows whether the data is modified or not. If not modified, data from gateway cache can be sent.

These are many other uses

ii) Get: Used to get the webpage

iii) Post: post is used to send data when we ~~use~~ fill forms

iv) Put: used to upload something

v) Delete: used to delete an object.

vi) Trace: Used to know the servers involved in sending data.

vii) Options: ~~opt~~ used to know whether the above functionalities are provided by a server or not.

viii) Connect: used for security (Authentication).

FTP (File Transfer Protocol)

→ ~~port~~ port number: 21

→ Example applications: Techia, Filezilla

→ FTP uses TCP

→ ~~To~~ FTP uses out of band connection

^{separate}
i.e., ~~a~~ connections are established for commands & data.

Control Connection (used for commands) (port: 21) (Persistent)

Data Connection (used for data) (port: 20) (non-persistent)

∴ separate connection is opened for each data transfer

FTP server: data of FTP server is used by FTP client.

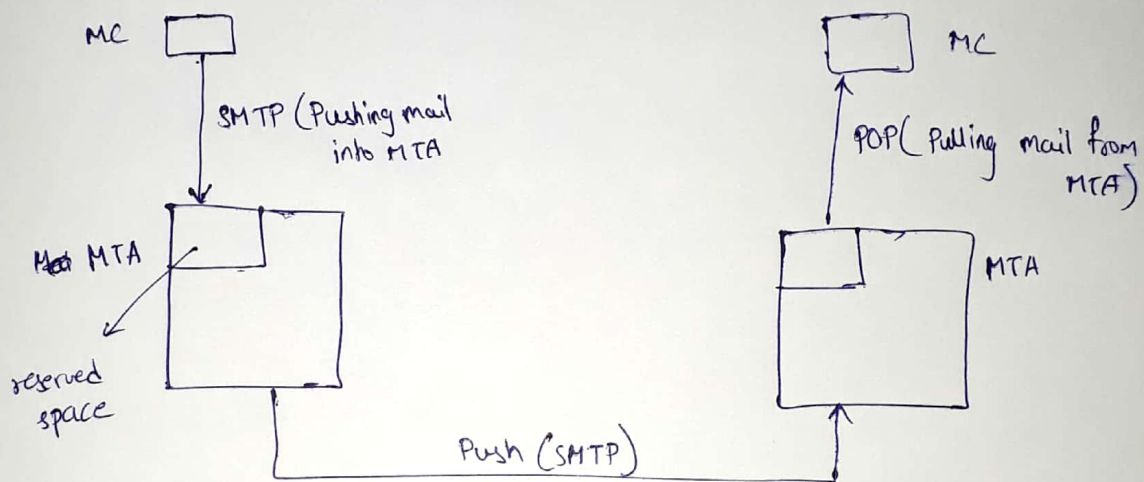
→ FTP is stateful protocol.

∴ FTP is going to log every activity.

SMTP (Simple Mail Transfer Protocol) and POP (Post Office Protocol)

→ FTP requires both the stations to be online while file transfer.

→ But SMTP doesn't need this. So we don't use FTP for emails.



MTA: Mail Transfer Agent

MC: Mail Client

→ SMTP & POP uses TCP for reliability.

→ To send data other than text, this ~~data~~ non-text data has to be converted into text format on sender side and ~~has~~ it has to be converted back into non-text format on receiver side.

The protocol used for this conversion is MIME

MIME: Multipurpose Internet Mail Extension.

→ SMTP & POP are inband protocols.